ASSP cmos

3 V Single Power Supply Audio Interface Unit (AIU)

MB86437

■ DESCRIPTION

The FUJITSU MB86437 is an AIU (audio interface unit) LSI for +3 V single-power source digital telephone devices, manufactured using CMOS process technology. The codec transmission filter characteristics meet G.712 standards, and can handle input and output in A-Law, μ -Law and linear conversion modes. The MB86437 also contains the necessary DTMF, microphone and receiver amps for telephone devices.

■ FEATURES

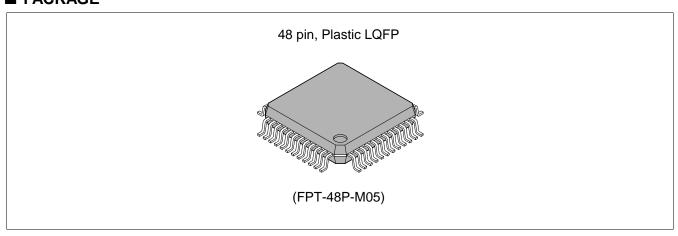
- +3 V single power supply
- Low power consumption: muting settings for each operating mode

Normal operation : 5.0 mA TYP Standby mode : $0.5 \mu A$ TYP

- On-chip codec filter meets G.712 standards
- Selection of codec companding law (A-law, μ-law, 14 bit linear)
- On-chip low-noise microphone amp (2-channel) (0 to 35 dB amplification)
- On-chip receiver speaker amps (32 Ω BTL type: 10 mW MIN)
- On-chip earphone speaker amps (32 Ω single type: 5 mW MIN)

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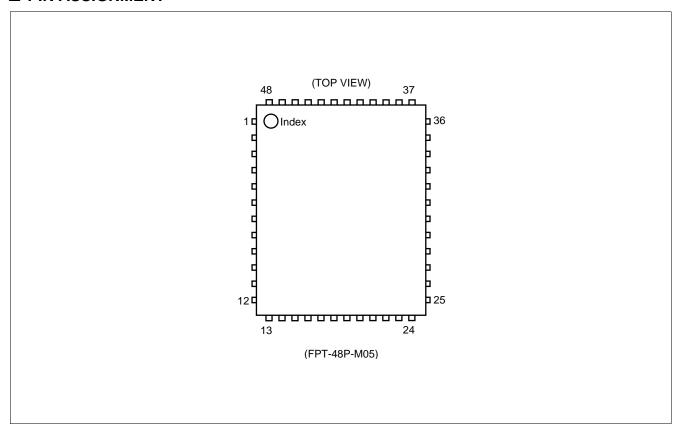
■ PACKAGE



(Continued)

- On-chip electronic volume gain adjustments (sending, receiving, tone)
- On-chip accessory input/output circuits
- DTMF generator function
- Service tone generation
- CMOS compatible input/output

■ PIN ASSIGNMENT

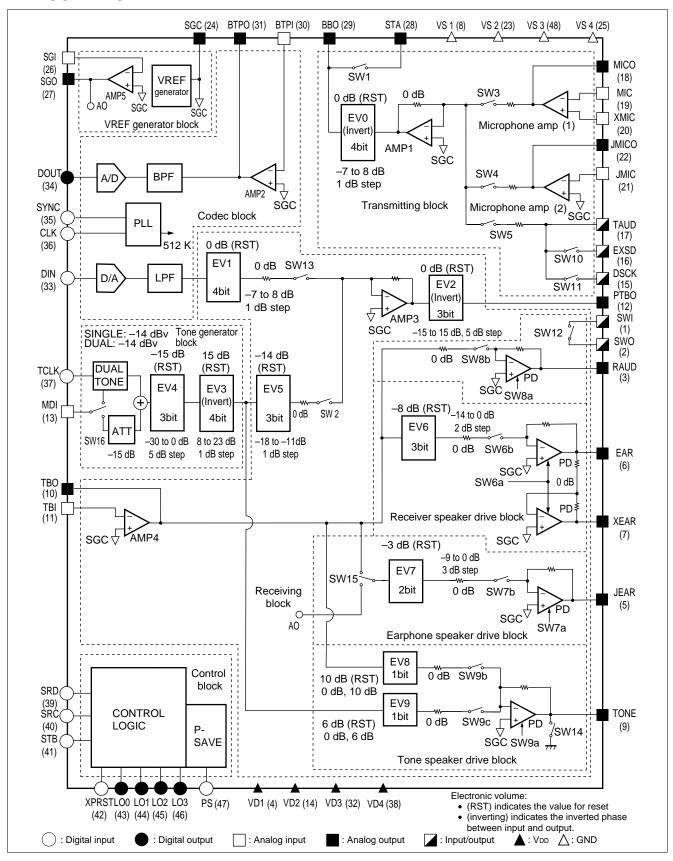


■ PIN DESCRIPTION

| Pin No. | Symbol | I/O | A/D | Description | |
|---------|--------|-----|-----|---|--|
| 1 | SWI | I/O | A/D | I/O pin for analog switch SW12 The standard on resistance for the analog switch is 500 Ω | |
| 2 | SWO | I/O | A/D | I/O pin for analog switch SW12 Connected to pin 1 via switch SW12. | |
| 3 | RAUD | 0 | Α | Output pin for the received audio signal to the external speaker or for testing. | |
| 4 | VD1 | Р | Α | Power supply pin for reception. Supply a voltage between 2.7 V and 3.6 V. | |
| 5 | JEAR | 0 | А | Amplifier output pin for the earphone speaker. Can output 5 mW for a 32 Ω load. | |
| 6 | EAR | 0 | А | Amplifier output pin for the receiver speaker. Internal BTL connection to XEAR. The maximum output for a 32 Ω load between EAR and XEAR is 10 mW. | |
| 7 | XEAR | 0 | Α | Amplifier output pin for the receiver speaker. BTL connection to XEAR. | |
| 8 | VS1 | G | Α | Ground pin for reception. Set to 0 V. | |
| 9 | TONE | 0 | А | Amplifier output pin for the tone speaker. The output can be set to normal mode, ground, or high impedance. | |
| 10 | ТВО | 0 | Α | AMP4 output pin. Pair high pass filter with TBI so that there is no DC offset at the speaker. | |
| 11 | TBI | I | Α | AMP4 inverted (–) input pin | |
| 12 | PTBO | 0 | Α | PCM reception, tone addition output | |
| 13 | MDI | ı | А | Pin used to add an analog input signal to the tone section or apply an envelope to the tone. Required functions can be selected by controlling SW16. Setting SW16 off sets the input impedance to approximately 140 k Ω and setting SW16 on sets the input impedance to approximately 210 k Ω . | |
| 14 | VD2 | Р | Α | Power supply pin for reception. Supply a voltage between 2.7 V and 3.6 V. | |
| 15 | DSCK | I/O | Α | Can be connected to EXSD and TAUD by path switching. | |
| 16 | EXSD | I/O | Α | Can be connected to DSCK and TAUD by path switching. | |
| 17 | TAUD | I/O | Α | Can be connected to EXSD and DSCK by path switching. | |
| 18 | MICO | 0 | Α | Output pin for mike amplifier [1] | |
| 19 | MIC | I | Α | Inverted input pin (–) for mike amplifier [1] | |
| 20 | XMIC | I | Α | Non-inverted input pin (+) for mike amplifier [1] | |
| 21 | JMIC | I | Α | Inverted input pin (–) for mike amplifier [2] | |
| 22 | JMICO | 0 | Α | Output pin for mike amplifier [2] | |
| 23 | VS2 | G | Α | Ground pin for transmission. Set to 0 V. | |
| 24 | SGC | 0 | Α | Pin for connecting the bypass capacitor for the signal ground potential generation circuit. Connect a capacitor between SGC and VS2. | |
| 25 | VS4 | G | Α | Ground pin for A/D and D/A. Set to 0 V. | |
| 26 | SGI | I | Α | A General-purpose amplifier. To use, connect to SGO. | |

| Pin No. | Symbol | I/O | A/D | Description | | |
|---------|--------|-----|-----|--|--|--|
| 27 | SGO | 0 | А | General-purpose amplifier output pin. The signal can also go to JEAR via SW15. | | |
| 28 | STA | 0 | Α | Transmission analog signal output via SW1. Connect to AMP4 when performing sidetone addition for reception. The standard on resistance for the analog switch is 500 Ω . | | |
| 29 | BBO | 0 | Α | Transmission analog signal output pin | | |
| 30 | BTPI | I | Α | Inverted input pin (–) for the PCM ENCODE section input op-amp | | |
| 31 | ВТРО | 0 | Α | Output pin for the PCM ENCODE section input op-amp | | |
| 32 | VD3 | Р | D | Power supply pin for transmission. Supply a voltage between 2.7 V and 3.6 V. | | |
| 33 | DIN | I | D | PCM signal input pin. The signal is clocked in on the falling edge of CLK. CMOS interface. | | |
| 34 | DOUT | 0 | D | PCM signal output pin. The signal is clocked out on the rising edge of CLK. After data output, becomes fixed at the "H" level if PLL synchronization is lost or a power-down occurs. CMOS interface. | | |
| 35 | SYNC | I | D | Transmission and reception sync signal input pin for the PCM CODEC section. The operating clock frequency is 8 kHz. CMOS interface. Fixing at "H" or "L" causes part of the CODEC section to power-down. | | |
| 36 | CLK | I | D | Input pin for setting the bit rate for the transmission and reception PCM signals. The data rate can be selected from 64 kHz to 3.152 MHz for μ -law or A-law operation, or from 128 kHz to 3.152 MHz for linear operation. Fixing at "H" or "L" causes part of the CODEC section to power-down. CMOS interface. | | |
| 37 | TCLK | I | D | Clock input pin for tone generation. The internal clock divided by one or to (set by D ₄ D ₃ of address 01110) can be used as the tone CLK. CMOS interface. | | |
| 38 | VD4 | Р | D | Digital power supply pin. Supply a voltage between 2.7 V and 3.6 V. | | |
| 39 | SRD | I | D | 10-bit serial data input pin. CMOS interface. This data sets the electronic volume, path, and tone settings. | | |
| 40 | SRC | I | D | Write clock input pin for the 10-bit serial data. CMOS interface. SRD is clocked in the rising edge. | | |
| 41 | STB | I | D | Strobe signal for the serial data latch. Latches on "L". CMOS interface. | | |
| 42 | XPRST | I | D | Reset signal input pin for the digital circuits. CMOS interface. L: Initialize internal latches. H: Normal | | |
| 43 | LO0 | 0 | D | Latch output pin for external control. Outputs D ₀ of address 01000. CMOS interface. | | |
| 44 | LO1 | 0 | D | Latch output pin for external control. Outputs D ₁ of address 01000. CMOS interface. | | |
| 45 | LO2 | 0 | D | Latch output pin for external control. Outputs D ₂ of address 01000. CMOS interface. | | |
| 46 | LO3 | 0 | D | Latch output pin for external control. Outputs D ₃ of address 01000. CMOS interface. | | |
| 47 | PS | I | D | Power-down control signal input pin. CMOS interface. Powers down all circuits regardless of register settings. | | |
| 48 | VS3 | G | D | Digital ground pin. Set to 0 V. | | |

■ BLOCK DIAGRAM



■ FUNCTIONAL DESCRIPTION

1. Register Settings

The MB86437 IC chip controls all electronic volume, switch, tone generator circuit and power-down control circuit by means of the SRD, STB and SRC input.

(1) Mode setting

The data format consists of 10 bits of serial data. The first 5 bits (A_4 to A_0) are the address and the next 5 bits (D_4 to D_0) are data. SRD is clocked in on the rising edge of SRC and latched when STB is "L". During power-down, the register is not reset and writing to the register is possible. A reset and data initialization occurs when XPRST is "L".

| Data | Address | Meaning | A | ata fter | Se a F | ttin Res | g et | | D | ata Meaning | 9 | |
|------|---------|--|----------------|-------------|-----------|----------------|----------------|---|-----------------------|----------------|-----------------------------|---|
| | | | D ₄ | Dз | D_2 | D ₁ | D ₀ | D ₄ | D ₃ | D ₂ | D ₁ | D ₀ |
| A00 | 00000 | Test mode | 0 | 0 | 0 | 0 | 0 | 00000: Norr | mal operatio | n (writing pro | hibited) | |
| A01 | 00001 | EV0 gain | 0 | 1 | 1 | 1 | X | EV0 [0000: - Reset: 0 dB | | 1: 8 dB, step | 1 dB, | X |
| A02 | 00010 | EV1 gain | 0 | 1 | 1 | 1 | X | EV1 [0000: - Reset: 0 dB | | 1: 8 dB, step | 1 dB, | X |
| A03 | 00011 | EV2 gain | X | X | 0 | 1 | 1 | Х | X | | -15 dB to 11 Reset: 0 dB | |
| A04 | 00100 | Transmit mute 1 (SW3, 4, 5) Receive mute 1 (SW6b, 7b, 8b, 9b, 9c) | 0 | X | X | X | 0 | Receive mute (SW6b, 7b, 8b, 9b, 9c) 1: Mute 1 0: No mute | X | X | X | Transmit mute (SW3, 4, 5) 1: Mute 1 0: No mute |
| A05 | 00101 | SW8, 3, 4, 5 mute 2 | 1 | X | 1 | 1 | 1 | 1: Mute 2 | | | | 1: Mute 2 0: No mute |
| A06 | 00110 | EV7 gain/SW7b, 9b, 9c, 6b mute 2 | 1 | 0 | 1 | 1 | 1 | [00: -9 dB to 11: 0 dB, step 3 dB, Reset: -3] 1: Mute 2 | | | | |
| | | | | | | | | Valid when D ₄ of A04 is "0" | | | | |
| A07 | 00111 | SW2, 11, 12, 10 control | X | 1 | 0 | 0 | 0 | 0 X SW2 SW11 SW12 SW10 1: ON 1: ON 1: ON 1: ON 0: OFF 0: OFF 0: OFF | | | | |
| A08 | 01000 | Digital parallel output | X | 0 | 0 | 0 | 0 | Х | L03 | L02 | L01 | L00 |
| A09 | 01001 | EV3 gain | 0 | 1 | 1 | 1 | X | EV3 [0000: 8 Reset: 15 d | | : 23 dB, step | 1 dB, | Х |

(Continued)

| Data | Address | Meaning | | | | ttin Res | | | D | ata Meanin | g | |
|------|---------|--|----------------|----------------|----------------|----------------|----------------|---|---|---|--|--|
| | | | D ₄ | D ₃ | D ₂ | D ₁ | D ₀ | D ₄ | D ₃ | D ₂ | D ₁ | D ₀ |
| A0A | 01010 | Tone [1] setting | 0 | 0 | 0 | 0 | 0 | Tone 1 waveform 1: Square wave | na = a ₇ × 2 ⁷ | ' + a ₆ × 2 ⁶ + | + a ₁ × 2 + | a ₀ |
| | | | | | | | | 0: Sine wave | ur | uo | us . | 4 |
| A0B | 01011 | | Χ | 0 | 0 | 1 | 0 | X | a 3 | a 2 | a 1 | a 0 |
| A0C | 01100 | Tone [2] setting | 0 | 0 | 0 | 0 | 0 | Tone 2 waveform 1: Square | $nb = b_7 \times 2^7$ | ' + b ₆ × 2 ⁶ + | + b ₁ × 2 + | b ₀ |
| | | | | | | | | wave 0: Sine wave | b ₇ | b 6 | b₅ | b ₄ |
| A0D | 01101 | | X | 0 | 0 | 1 | 0 | X | bз | b ₂ | b ₁ | b ₀ |
| A0E | 01110 | Tone waveform setting (for tones [1] and [2]) | 0 | 0 | X | 0 | 0 | Divide ratio ratio (TCLK/N) 00 TCLK/1 01 TCLK/1 2 10 TCLK/2 2 | (M) 12 divisions 24 divisions 24 divisions | X | Tone [1] control 1: Generate 0: Stop | Tone [2] control 1: Generate 0: Stop |
| A0F | 01111 | CODEC compression rule | X | X | X | 0 | 0 | X | X | X | CODEC com 00: μ-LAW 01: Linear 10: A-LAW 11: Use pro | npanding law |
| A10 | 10000 | PD control and SW14 control for CODEC, TONE, SGO, and transmission (TX) | 0 | 0 | 0 | 0 | 0 | CODEC PD 1: PD 0: Operate | TONE PD 1: PD 0: Operate | SGO PD 1: PD 0: Operate | Transmit- ter PD 1: PD 0: Operate | SW14 1: TONE output 0 V 0: Operate |
| A11 | 10001 | PD control for RAUD, JEAR, TONE, and EAR | 0 | X | 0 | 0 | 0 | RAUD PD (SW8a) 1: Indepen- dent 0: Linked | X | JEAR PD (SW7a) 1: Inde- pendent 0: Linked | TONE PD (SW9a) 1: Inde- pendent 0: Linked | EAR PD (SW6a) 1: Inde- pendent 0: Linked |
| | | | | | | | | Independent conjunction Linked: Powwith mute. | with mute. | | | |
| A12 | 10010 | DOUT/SW1, 13, 9b, 9c | 0 | 0 | 0 | 1 | 1 | DOUT 1: Fixed at "H" 0: Operate | SW1 mute 1: Mute 0: No mute | | SW9b mute 0: Mute 1: No mute | SW9c mute 0: Mute 1: No mute |

The tone frequencies are as follows. (f_a and f_b are the frequencies of tones [1] and [2] respectively.) (f_{in} = TCLK input frequency (512 kHz recommended when N = 1, M = 12, 1024 kHz recommended when N = 1, M = 24 \rightarrow $f_{in}/(N \times M)$ = 42.667 kHz), N: Divide ratio (1 or 2), M: Number of divisions (12 or 24)) $f_a = (f_{in}/(N \times M))/(n_a + 1)$, $f_b = (f_{in}/(N \times M))/(n_b + 1)$

(Continued)

| Data | Address | Meaning | | Data Setting After a Reset | | | | | D | ata Meanin | g | |
|------|---------|---------------------|----------------|-------------------------------|----------------|----------------|----------------|---------------------------------|----------------|----------------|------------------------------|--|
| | | | D ₄ | Dз | D ₂ | D ₁ | D ₀ | D ₄ | D ₃ | D ₂ | D ₁ | D ₀ |
| A13 | 10011 | EV8, EV6 gain | 1 | X | 0 | 1 | 1 | EV8 gain 1: 10 dB 0: 0 dB | X | | -14 dB to 11 Reset: –8 dB | |
| A14 | 10100 | EV4 gain | Х | Χ | 0 | 1 | 1 | X | Х | | -30 dB to 11 Reset: –15 d | |
| A15 | 10101 | EV9, EV5 gain | 1 | Х | 0 | 1 | 1 | EV9 gain 1: 6 dB 0: 0 dB | X | | -11 dB to 11 Reset: –14 d | |
| A16 | 10110 | SW15, 16 control | X | X | X | 0 | 0 | X | X | X | SW15 1: AMP5 0: AMP4 | SW16 * 1 1: Envelope 0: ATT |
| A17 | 10111 | All PD | Х | X | Х | X | 1 | X | X | Х | Х | All circuits PD 1: Normal 0: PD |

Notes: 1. When unused, connect the MDI input to OPEN or SGC. When using ATT, an SGC-centered signal or capacitive coupling is required (to prevent an offset).

- 2. Set X to 0.
- 3. Set to initial value by a reset (_____ section).

(2) Transmitting audio mute settings

Switches SW1, SW3, SW4, SW5, SW10, and SW11 have the following functions. Address 00100 signals have priority.

| | | Setting | | | | | | | | | |
|----------|----------------------------------|----------------------------------|----------------------------------|----------------------------------|------|------|---------|---------|-----|-----|------------------------------|
| Address | A ₄ to A ₀ | | Sw | /itchin | g setti | ing | | Remarks |
| Address | 00100 | 00101 | 00111 | 10010 | | | | | | | |
| | D ₄ to D ₀ | SW1 | SW3 | SW4 | SW5 | SW1 | SW1 | |
| | D4 10 D0 | D4 10 D0 | D4 10 D0 | D4 10 D0 | 3001 | 3003 | 3004 | 3003 | 0 | 1 | |
| | - * * * 1 | - * | * | | _ | × | × | × | _ | _ | Microphone amp |
| | - * * * 0 | - * 0 1 - | * | | _ | 0 | × | _ | _ | _ | Microphone amp [1], [2] mute |
| Data bit | - * * * 0 | - * 1 0 - | * | | _ | × | 0 | _ | _ | _ | Microphone amp [2] mute |
| | - * * * 0 | - * 0 | * - 0 - 0 | | _ | _ | _ | 0 | × | × | Microphone amp |
| | - * * * 0 | - * 1 | * - 0 - 1 | | _ | _ | _ | × | 0 | × | [1] mute |
| | - * * * 0 | - * 1 | * - 1 - 0 | | _ | _ | _ | × | × | 0 | |
| | - * * * - | - * | * | -1 | × | _ | _ | _ | _ | _ | |

 \bigcirc : ON, \times : OFF, — : not determined

(3) Receiving audio mute settings

Switches SW6b, SW7b, SW8b, SW9b, SW9c, and SW12 have the following functions. Address 00100 signals have priority.

| | | Set | ting | | | | | | | | | |
|----------|----------------------------------|----------------------------------|----------------------------------|----------------------------------|----------------------------------|-----|----------|----------|----------|-----|----------|---------|
| Address | A ₄ to A ₀ | | Sw | itchin | g sett | ing | | Remarks |
| Address | 00100 | 00101 | 00110 | 00111 | 10010 | | | | | | | |
| | D ₄ to D ₀ | SW6 | SW7 b | SW8 b | SW9 b | SW9 | SW1 2 | |
| | 1 * * * - | - * | | * | | × | × | × | × | × | _ | |
| | 0 * * * - | 1 * | | * | | _ | _ | × | _ | _ | | |
| İ | 0 * * * - | 0 * | 1 | * | | _ | × | 0 | _ | _ | _ | |
| Data bit | 0 * * * - | - * | 01- | * | | _ | 0 | _ | × | × | _ | |
| | 0 * * * - | - * | 0- | * | 01 | _ | _ | _ | × | 0 | _ | |
| | 0 * * * - | - * | 0- | * | 10 | _ | _ | _ | 0 | × | | |
| | 0 * * * - | - * | 1 | * | | × | _ | _ | _ | _ | | |
| | 0 * * * - | - * | 0 | * 0 | | 0 | _ | _ | _ | _ | × | |
| | 0 * * * - | - * | | * 1 | | _ | _ | _ | _ | _ | 0 | |

 \bigcirc : ON, \times : OFF, — : not determined

(4) Electronic volume controls

There are ten different electronic volume controls, EV0 through EV9, with the following specifications. Electronic volume control settings are made by the SRD, SRC and STB signals, and setting values are reset by the XPRST signal.

Table 1 Relation of Volume Control Data bit Values to Gain

| | Address | 00001 | 00010 | 00011 | 01001 | 10100 | 10101 | 10011 | 00110 | 10011 | 10101 | |
|----------------|---|-------------------------------------|-------------------------------------|-------------------------------------|-------------------------------------|-------------------------------------|-------------------------------------|-------------------------------------|-------------------------------------|----------------------|----------------------|------|
| | Data | EV0 | EV1 | EV2 | EV3 | EV4 | EV5 | EV6 | EV7 | EV8 | EV9 | |
| Code | D ₄ D ₃ D ₂ D ₁ D ₀ | Inverte d | Non- Inverte d | Inverte d | Inverte d | Non- Inverte d | Non- Inverte d | Non- Inverte d | Non- Inverte d | Non- Inverte d | Non- Inverte d | Unit |
| | 5 0 | D ₄ to D ₁ | D ₄ to D ₁ | D ₂ to D ₀ | D ₄ to D ₁ | D ₂ to D ₀ | D ₂ to D ₁ | D ₂ to D ₀ | D ₄ to D ₃ | D ₄ | D ₄ | |
| 0 | 00000 | -7 | -7 | -15 -10 | 8 | -30 -25 | –11 –12 | -14 -12 | -9 -9 | 0 | 0 | |
| 2 | 0 0 0 1 0 | -6 | -6 | <u>-10</u> -5 | 9 | -23 -20 | -12 -13 | -12 -10 | _9 | 0 | 0 | |
| 3 4 | 00011 | – 5 | - 5 | 0 5 | 10 | –15 –10 | −14 −15 | -8 -6 | _9 _9 | 0 0 | 0 0 | |
| 5 | 0 0 1 0 1 | | | 10 | 10 | - 5 | –16 | -4 | _9 | 0 | 0 | |
| 6 | 0 0 1 1 0 | -4 | -4 | 15 | 11 | 0 | -17 | -2 0 | -9 | 0 | 0 | |
| 7 8 | 00111 | -3 | -3 | 15 | 12 | 0 | –18 | U | -9 -6 | 0 | 0 | |
| 9 | 01001 | | | | | | | | -6 | | | |
| 10 11 | 01010 | -2 | -2 | | 13 | | | | -6 -6 | | | |
| 12 | 01100 | 1 | 1_ | | 14 | | | | -6 -6 | | | |
| 13 14 15 | 0 1 1 0 1 0 1 1 1 0 0 1 1 1 1 | 0 | 0 | | 15 | | | | -6 -6 -6 | | | |
| 16 | 10000 | 1 | 1 | | 16 | | -11 | -14 | -3 | 10 | 6 | dB |
| 17 18 19 | 1 0 0 0 1 1 0 0 1 0 1 0 0 1 1 | 2 | 2 | | 17 | | <u>-12</u> -13 -14 | <u>-12</u> -10 | -3 -3 | 10 10 10 | 6 6 6 | |
| 20 | 10100 | 3 | 3 | | 18 | | -15 | -8 -6 -4 | -3 -3 -3 -3 -3 | 10 | 6 | |
| 21 22 | 10101 | 4 | 4 | | 19 | | -16 -17 | -2 | -3 -3 | 10 10 | 6 | |
| 23 24 | 1 0 1 1 1 1 1 1 0 0 0 | 5 | 5 | | 20 | | –18 | 0 | -3 0 | 10 | 6 | |
| 25 26 | 1 1 0 0 1 1 1 0 1 0 | 6 | 6 | | 21 | | | | 0 | | | |
| 27 28 | 1 1 0 1 1 1 1 1 0 0 | 7 | 7 | | 22 | | | | 0 0 | | | |
| 29 30 | 11101 | 8 | 8 | | 23 | | | | 0 0 | | | |
| 31 | 11111 | | | | | | | | Ő | | | |

Notes: • Each setting value is determined in relation to the initial setting value.

- Returns to initial value at reset (parts)
 The "Inverted" and "Non-Inverted" columns indicate the I/O phase.
- Settings with no gain figure listed are undefined.

(5) Tone generation circuit

This section describes the frequency settings and output control.

• Tone frequency control register

The clock used to generate tones is the clock input from TCLK divided by 1 or 2. The divide ratio is set by the data at address 01110. Also, 12 division and 24 division modes are available to generate a smooth frequency even at low frequencies.

Table 2 Register Control for the TONE Clock Frequency

| Addres | s 01110 | Tone Generation Clock (fin) | Waveform Division | | |
|----------------|-----------------------|--------------------------------------|--------------------|--|--|
| D ₄ | D ₃ | Tone Generation Clock (III) | Wavelolli Division | | |
| 0 | 0 | Frequency input to TCLK | 12 divisions | | |
| 0 | 1 | Frequency input to TCLK | 24 divisions | | |
| 1 | 0 | Frequency input to TCLK divided by 2 | 24 divisions | | |
| 1 | 1 | Prohibited | | | |

The following formula specifies the frequencies that can be set by the tone frequency control register.

Set frequency $f = f_{IN}/(M \times (1 + n))$, M = division mode (12 or 24)

n = 4, 5, ..., 255 (fin: Tone generation clock)

 $f_{IN} = 4 MHz max.$

Therefore, the range of available frequencies in 12 division mode and $f_{IN} = 512$ kHz, and in 24 division mode and $f_{IN} = 1024$ kHz is:

 $f_{min} = 167 \text{ Hz}, f_{max} = 8533 \text{ Hz}$

Table 3 lists the frequency settings for all the standard DTMF frequencies.

Table 3 Tone Frequency Register Control

(Setting: 12 divisions and $f_{IN} = 512 \text{ kHz}$, or 24 divisions and $f_{IN} = 1024 \text{ kHz}$)

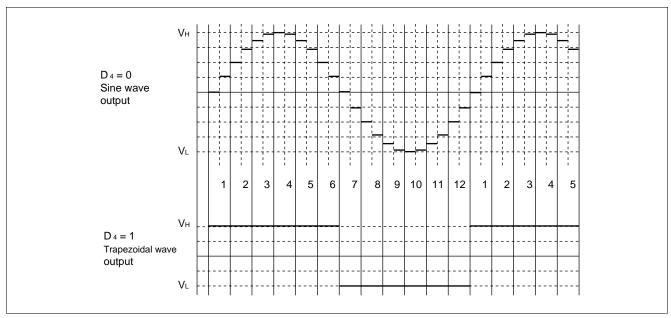
| | _ | Standard Frequency | Set | | | ddre 10/0 | |) | | | ddre 11/0 | | | | _ |
|--------|------------|----------------------------------|-----------|----------------|----------------|------------------------|----------------|----------------|----------------|----------------|------------------------|----------------|----------------|-----|--------|
| 1 | one Type | (Example of generated frequency) | Frequency | D ₄ | D ₃ | Data D ₂ | D ₁ | D ₀ | D ₄ | D ₃ | Data D ₂ | D ₁ | D ₀ | n | Error |
| Ser | vice tones | 400 Hz | 398.7 Hz | _ | 0 | 1 | 1 | 0 | * | 1 | 0 | 1 | 0 | 106 | -0.32% |
| (Sir | ngle tone) | 2000 Hz | 2031.7 Hz | _ | 0 | 0 | 0 | 1 | * | 0 | 1 | 0 | 0 | 20 | 1.56% |
| | | 697 Hz | 699.4 Hz | _ | 0 | 0 | 1 | 1 | * | 1 | 1 | 0 | 0 | 60 | 0.34% |
| | Low topos | 770 Hz | 775.7 Hz | _ | 0 | 0 | 1 | 1 | * | 0 | 1 | 1 | 0 | 54 | 0.74% |
| | Low tones | 852 Hz | 853.3 Hz | _ | 0 | 0 | 1 | 1 | * | 0 | 0 | 0 | 1 | 49 | 0.15% |
| D T | | 941 Hz | 948.1 Hz | _ | 0 | 0 | 1 | 0 | * | 1 | 1 | 0 | 0 | 44 | 0.75% |
| M | | 1209 Hz | 1219.0 Hz | _ | 0 | 0 | 1 | 0 | * | 0 | 0 | 1 | 0 | 34 | 0.82% |
| | High topos | 1336 Hz | 1333.3 Hz | _ | 0 | 0 | 0 | 1 | * | 1 | 1 | 1 | 1 | 31 | -0.20% |
| | High tones | 1477 Hz | 1471.3 Hz | _ | 0 | 0 | 0 | 1 | * | 1 | 1 | 0 | 0 | 28 | -0.38% |
| | | 1633 Hz | 1641.0 Hz | _ | 0 | 0 | 0 | 1 | * | 1 | 0 | 0 | 1 | 25 | 0.48% |

Notes: • Settings are shown in binary notation.

- Error is the error between the set frequency and standard frequency.
- Set n to 4 or higher and set a frequency of 5 kHz or less.

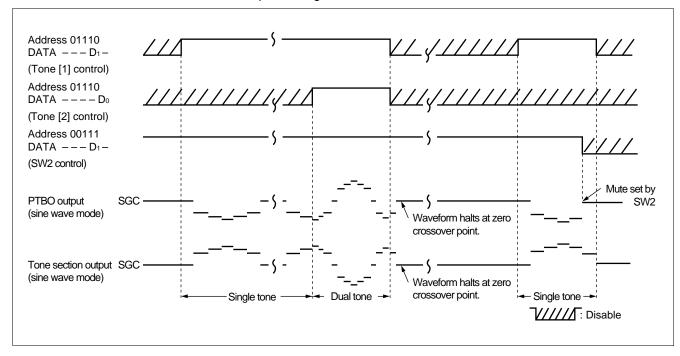
• Tone output waveform

The D₄ data bit at address 01010, 01100 may be used to select either sine-wave or trapezoidal waveforms for tone output.



• Tone output control

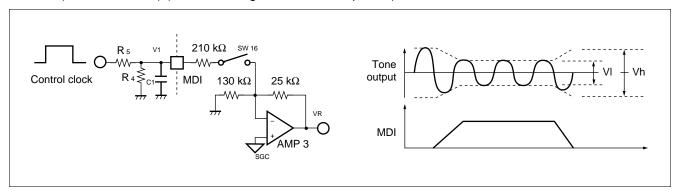
Tone output is controlled by addresses 01110 and 00111. Provided TCLK does not stop, sine wave output always halts close to zero. Also, SW2 controls output muting.



• Tone envelope

Even if the tone halts at close to zero, changes in the DC voltage can still occur can be audible. Using SW16 for tone control enables the voltage level for tone generation to be controlled. The waveform amplitude characteristics have the following general relationships.

$$Va = 2 \times (0.47 - 0.12 \times VI)$$
 (VI: MDI voltage, $Va = Tone$ amplitude)



For a cut off frequency of $8.3 \, \text{Hz}$, control clock of 0 to 3 V, and SGC = $1.5 \, \text{V}$, the envelope ratio and resistor and capacitor values are as follows.

| Envelope Ratio | Reco | mmended Va | alues | Vh, VI V | oltages | Envelope Ratio |
|----------------|--------|------------|--------|-----------|-----------|------------------|
| Aim Value | R4 | R5 | C1 | Max. (Vh) | Min. (VI) | Calculated Value |
| −3 dB | 33 kΩ | 22 kΩ | 1.5 μF | 0.828 V | 0.584 V | –3.13 dB |
| –4 dB | 47 kΩ | 18 kΩ | 1.5 μF | 0.824 V | 0.516 V | -4.05 dB |
| −5 dB | 82 kΩ | 15 kΩ | 1.5 μF | 0.810 V | 0.448 V | –5.15 dB |
| −6 dB | 270 kΩ | 15 kΩ | 1.5 μF | 0.790 V | 0.400 V | -5.91 dB |

(6) CODEC I/O

Code companding for μ -law and A-law is in accordance with CCITT Recommendation G.711. Linear coding uses 14-bit, two's complement code which is output MSB-first. Address 01111 is used to control μ -law, A-law, and linear code I/O.

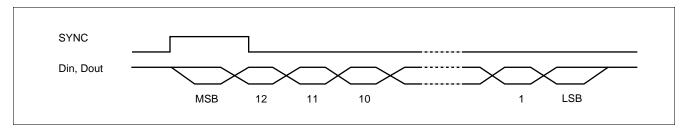
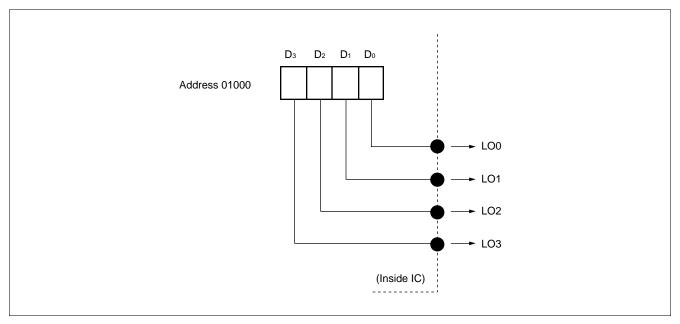


Table 4 Table of Linear Code vs. Voltage

| MSB Code | LSB | PTBO Standard Voltage (V) |
|---------------------|---------|---------------------------|
| 0 1 1 1 1 1 1 1 1 1 | 1 1 1 1 | 2.2647 |
| to | | to |
| 0 0 0 0 0 0 0 0 0 | 0 0 0 1 | 1.5009 |
| 0 0 0 0 0 0 0 0 0 0 | 0 0 0 0 | 1.5000 |
| 1 1 1 1 1 1 1 1 1 1 | 1 1 1 1 | 1.4991 |
| to | | to |
| 1 0 0 0 0 0 0 0 0 0 | 0 0 0 1 | 0.7354 |

(7) Parallel output

LO0 to 3 are general-purpose latch outputs for external control. LO0 to 3 output the data written to address 01000. The outputs are CMOS outputs. Data output continues during power-down.

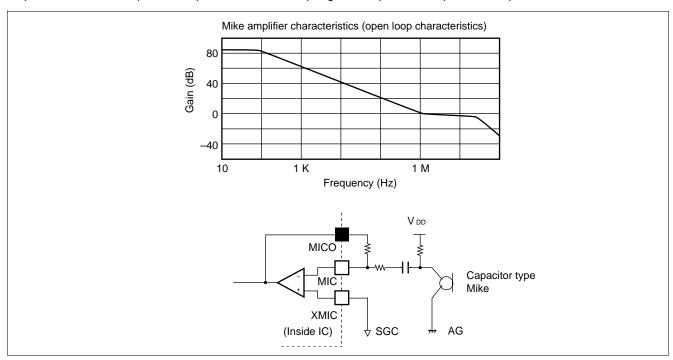


2. Analog Input

Analog inputs in the MB86437 include the two microphone inputs and the three accessory input.

(1) Microphone amps

The microphone amps take the incoming signal from the microphones and amplify it to any desired level of gain. The microphone amps are low-noise types for use with capacitor microphones, and are capable of a wide range of amplification. All microphone amps must be AC coupling with capacitors to prevent amplification of DC offset level.



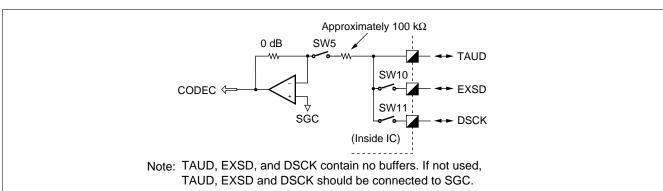
(2) Accessory input

Direct input from the TAUD to the codec unit is possible through SW5, without passing through the microphone amp. Care must be taken with the input signal in this case, however, because input resistance is not at high-impedance level.

Microphone amp output may be added to the signal by using switching controls.

In this case, the result will be at the additional output level.

In addition, SW10 and SW11 may be used to transmit digital data from the TAUD to EXSD and DSCK, allowing the sending of fax or PC data without modification.



3. Analog Output Relationships

The four analog outputs consist of three speaker drivers (for receiver, earphone, and tone) and an accessory output.

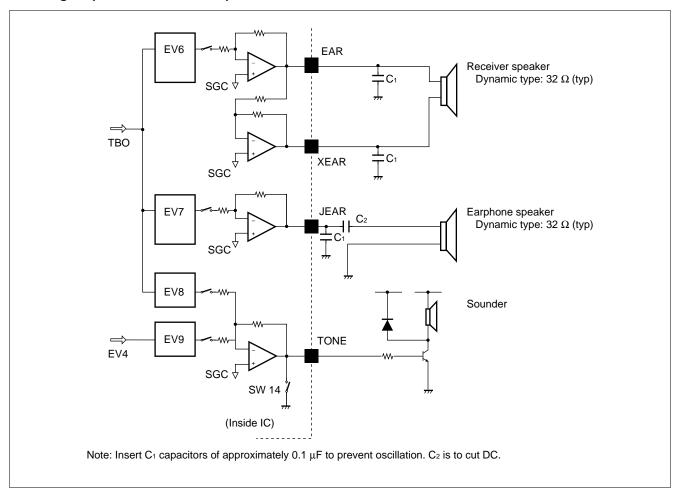
(1) Speaker driver amps

The speaker driver amps consist of one BTL output (the receiver output) and one single output (the earphone output). Also, the sounder driver consists of one single output and the sounder output can be obtained via a transistor. As the speaker amps have high power consumption, separate power-down control is available for each speaker amp.

| Parameter | Receiver Speaker Amp (EAR, XEAR) | Earphone Speaker Amp (JEAR) | Tone Amp (TONE) |
|----------------------|-------------------------------------|--------------------------------|--------------------|
| Output type | BTL | Single | Single |
| Load resistance *1 | 32 Ω (typ.) | 32 Ω (typ.) | 600 Ω (typ.) |
| Load capacitance *2 | 0.1 μF | 0.1 μF | |
| Maximum output power | 10 mW (min.) | 5 mW (min.) | |

^{*1:} Dynamic speaker

Analog output connection example



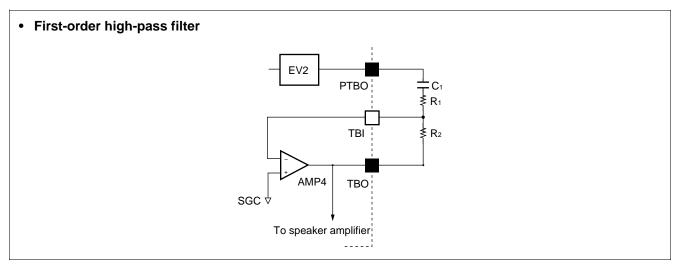
^{*2:} A capacitor is required to prevent oscillation.

4. Reception Connections

This section describes reception connections, sidetone addition, and melody IC connection.

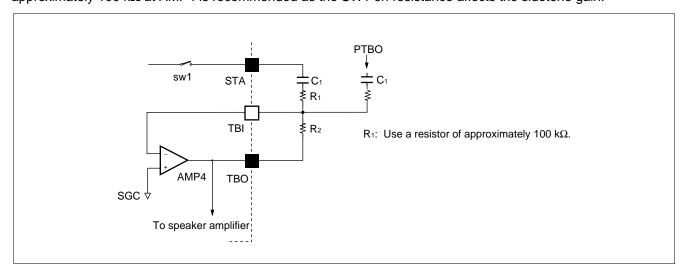
(1) Reception connections

This describes the connection to the speaker amp for the reception signal. Provide a high-pass filter at AMP4 to prevent a DC offset being applied to the speaker amp.



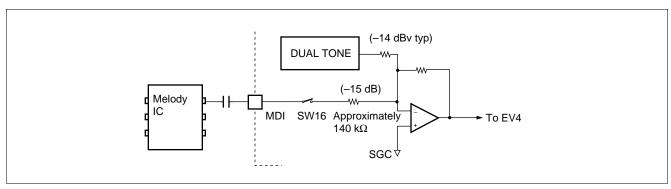
(2) Sidetone addition

Sidetone addition is implemented by connecting the STA output and AMP4. In this case, use of a resistor of approximately 100 $k\Omega$ at AMP4 is recommended as the SW1 on resistance affects the sidetone gain.



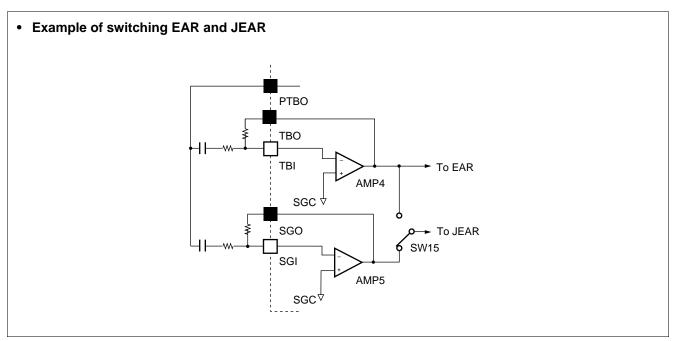
(3) Melody IC connection

A melody IC can be connected using AMP4. However, the level can be made to vary in the same way as the tone if the MDI pin is used. MDI has an input impedance of approximately 140 $k\Omega$ and is not high impedance.



(4) JEAR signal selection

JEAR can receive a signal from AMP4 or AMP5. This enables a range of applications to be implemented depending on the AMP4 and AMP5 circuit structures.



(5) Preventing a clicking sound when the electronic volume gain is changed or when muting

Changing the gain of the electronic volume or muting may result in a clicking sound due to fluctuation in the DC level. In such cases, the following setting is recommended.

Set the mode in which powering down the speaker amplifier is not linked with SW6b, 7b, 8b, and 9b (ADDRESS: 10001, DATA: 10111) and mute using SW6b, 7b, 8b, and 9b.

5. Power-Save Mode

This section describes the setting methods and states.

(1) Mode setting

Power-save mode can be controlled by an external control signal and register setting.

The various modes set each block to a power-save state, enabling the power consumption to be reduced.

• Power-save mode setting table

| | | | | | | | , | Addr | ess | | | | | | | SYNC | | | u | | | | Red | cept | ion | |
|------------------------|---------------------|----------------|-----|----------------|----------------|-----|----|----------------|-----|----------------|----|----------------|----------------|----------------|----------------|------|--------------|-------|------|--------|------|-----------|-----------|-----------|------|----------|
| Mode | PS or Address | 00 | 100 | 00101 | C | 011 | 0 | | 100 | 000 | | 10001 | | or CLK | VREF | AMP5 | Transmission | CODEC | TONE | AP3, 4 | sory | hone | 빚 | iver | | |
| | 10111 | D ₄ | Do | D ₄ | D ₂ | D₁ | Do | D ₄ | D₃ | D ₂ | D₁ | D ₄ | D ₂ | D ₁ | D ₀ | STOP | | | Tran | ပ | | EV2 AMP3, | Accessory | Ear Phone | TONE | Receiver |
| All PD | 0 | _ | - | - | - | - | - | _ | _ | - | _ | _ | _ | - | - | - | × | × | × | × | × | × | × | × | × | × |
| VREF operation | 1 | _ | _ | _ | _ | _ | _ | _ | _ | 0 | _ | _ | ı | _ | - | _ | 0 | 0 | _ | _ | _ | _ | _ | ı | - | _ |
| SGO PD | 1 | _ | _ | - | - | - | _ | - | _ | 1 | _ | _ | ı | _ | - | - | 0 | × | - | _ | - | - | - | 1 | - | _ |
| TONE operation | 1 | _ | _ | _ | _ | _ | _ | _ | 0 | _ | _ | _ | ı | _ | _ | _ | 0 | _ | _ | _ | 0 | 0 | _ | ı | - | _ |
| CODEC, TONE PD | 1 | _ | _ | _ | - | _ | _ | 1 | 1 | _ | _ | - | - | _ | - | _ | 0 | _ | - | × | × | × | × | × | × | × |
| CODEC operation | 1 | _ | _ | _ | _ | _ | _ | 0 | _ | _ | _ | _ | ı | _ | _ | 0 | 0 | _ | _ | 0 | _ | 0 | _ | ı | - | _ |
| CODEC SYNC PD | 1 | _ | _ | _ | _ | _ | _ | 0 | _ | _ | _ | _ | ı | _ | _ | × | 0 | _ | _ | × | _ | 0 | _ | ı | - | _ |
| Transmission operation | 1 | _ | _ | _ | _ | _ | _ | _ | _ | _ | 0 | _ | ı | _ | _ | _ | 0 | _ | 0 | _ | _ | _ | _ | ı | - | _ |
| Transmission PD | 1 | _ | _ | _ | _ | _ | _ | _ | _ | _ | 1 | _ | ı | _ | _ | _ | 0 | _ | × | _ | _ | _ | _ | ı | - | _ |
| | 1 | 1 | _ | 1 | 1 | 1 | 1 | 0 | 1 | _ | _ | 0 | 1 | 0 | 0 | _ | 0 | _ | - | 0 | _ | 0 | × | 0 | × | × |
| | 1 | 0 | - | 1 | 1 | 1 | 0 | 0 | 1 | - | _ | 0 | 1 | 0 | 0 | _ | 0 | _ | - | 0 | - | 0 | × | 0 | × | 0 |
| Reception operation | 1 | 0 | _ | 1 | 1 | 0 | 1 | 0 | 1 | _ | _ | 0 | 0 | 0 | 1 | _ | 0 | _ | - | 0 | _ | 0 | × | × | 0 | 0 |
| ' | 1 | 1 | _ | 0 | 0 | 0 | 0 | 0 | 1 | _ | _ | 1 | 1 | 0 | 0 | _ | 0 | _ | - | 0 | _ | 0 | 0 | 0 | × | × |
| | 1 | 0 | _ | 1 | 1 | 1 | 1 | 0 | 1 | _ | _ | 1 | 1 | 1 | 1 | _ | 0 | _ | - | 0 | _ | 0 | 0 | 0 | 0 | 0 |

○: Operation enabled, △: Changes depending on address 10001, ×: Power-down

Note: Powering down the CODEC or TONE generator powers down the entire reception block.

(2) Output pin states in each mode

| ` | | | | | | | | | | | | | | | | |
|------------------|---------------------|--|--------|--------|-----------|--------|----------------------|-------------------------|---------------------------|--------|-----------------|---------------------|-------------------------|------------------------|--------------|-------------|
| | £ 01 (| רסנ | * | -1 | -1 | -1 | 1 | 1 | 1 | -1 | - 1 | 1 | - 1 | 1 | - 1 | 1 |
| | TUG | DO | I | I | I | I | エ | ı | I | I | I | エ | 0 | I | I | I |
| | 09 | S | × | I | I | × | I | I | ı | ı | I | I | I | I | I | I |
| | 29 | | X | 0 | 0 | 0 | 0 | 0 | ı | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| ţ | Od. | | X | ı | ı | ı | <u>~</u> | ı | ı | ı | | ı | 0 | ı | ī | ı |
| Sta | AT | | X | i | i | ı | | ਨ ← | ı | × | S | l | ı | l | i | i |
| Ë | 80 | | × | i | ı | ı | ı | Α, | i | S | S | ı | i | ı | ı İ | · |
| # | ОЗІМІСО | | | - | | | | | | | | | | | - | |
| Output Pin State | | | × | 10 | 1 | | 1 | × | I | 0 | 0 | l | I | I | - I | . I |
| ō | OBT9 | | × | S | I | ı | ~ | 1 | I . | I | - | l | 0 | 0 | | 1 |
| | BNE | | × | X | S | I | × | I | I | I | I | I | I | I | S | വ |
| | ЯA | | X | ഗ | × | I | × | I | I | I | ı | I | I | I | I | I |
| | ЯАЭХ | | × | × | S | I | × | I | I | I | ı | I | I | I | I | I |
| | np | ₹И | × | တ | × | I | × | 1 | I | I | | I | I | I | l | 1 |
| | SYNC or CLK | | | | | | | | | | | STO P | 0 | | | |
| | ั้ธั | | | | | | | | | | | ν - | | | | |
| | | ۵ | | | | | | | | | | | | | _ | |
| | 0 | D ₂ D ₇ | | | | | | | | | | | | | _ | |
| | 10010 | \mathbf{D}_2 | | _ | | | | | | | | | | | | |
| | 7 | ۵ | | | | | | | | 1 | 0 | | | | | |
| | | Δ | | | | | | | _ | | | | | | | |
| | | ۵ | | 0 | _ | | | | | | | | | | | |
| | 2 | Δ | | 0 | _ | | | | | | | | | | | |
| | 10001 | | | _ | 0 | | | | | | | | | | | |
| | _ | D ₀ D ₄ D ₂ | | _ | 0 | | | | | | | | | | | |
| | | ° | | · | _ | | | | | | | | | | | _ |
| | | | | | | | | - | 0 | 0 | 0 | | | | | ` |
| S | 000 | D ₂ | | | | | | ` | |) |) | | | | | |
| Address | 10000 | ۵ | | | | _ | | | | | | | | | | |
| В | | | | | | | _ | | | | | _ | _ | 0 | | |
| ٩ | | D ₄ | | | | | _ | | | | | 0 | 0 | | | |
| | 00111 | ũ | | _ | | | | | | | | | | | | |
| | 0 | D° | | | ~ | | | | | | | | | | | |
| | 00110 | Δ | | | ~ | | | | | | | | | | | |
| | 0 | D ₀ D ₂ D ₁ | | | _ | | | | | | - | | | | | |
| 1 | | ۵ | | | | | | | | | 1 | | | | | |
| | 70 | Δ | | | | | | | | | 1 | | | | | |
| | 00101 | ² | | | | | | | | | 1 | | | | | |
| | | 4 | | | _ | | | | | | | | | | | |
| | 00 | | | | | | | | | 1 | 0 | | | | | |
| | 00100 | D ₄ D ₀ D ₄ D ₂ D ₁ | | _ | 0 | | | | | | - | | | | | |
| <u> </u> | Sis . | | | | _ | | | | | | | | | | | |
| | PS or Address | 5 | 0 | ~ | _ | _ | ~ | 1 | I | 1 | 1 | ~ | ~ | ~ | _ | _ |
| | Mode | | All PD | Recep- | tion mute | SGO PD | CODEC, TONE PD | Trans- mission PD | Trans- mission halt | Trans- | mission mute | CODEC SYNC PD | CODEC opera- tion | TONE opera- tion | TONE mute | TONE GND |

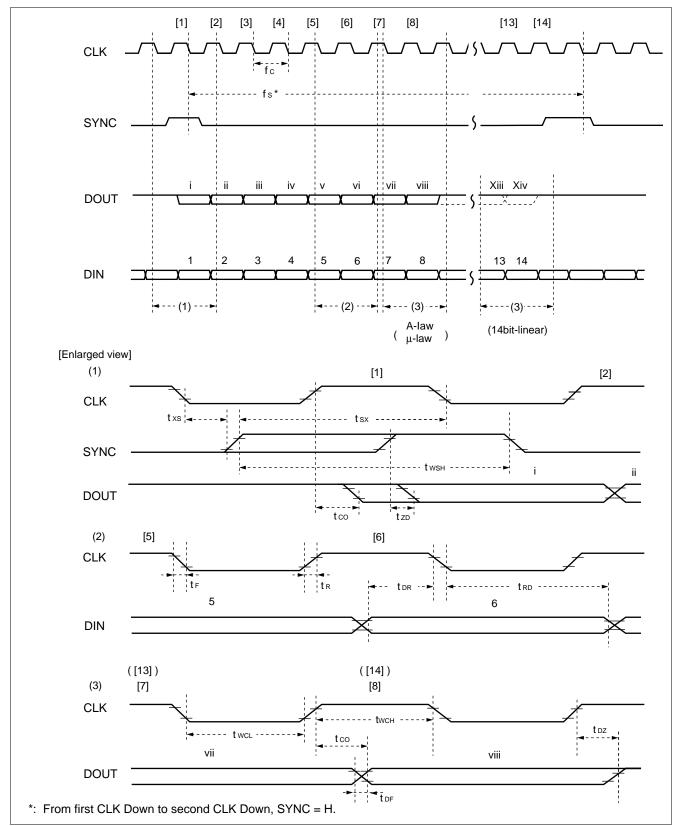
^{×:} High impedance, S: Signal ground, R: Connected to signal ground via high resistance, \bigcirc : Normal operation

^{* :} Depends on value of address 01000, G: Ground output, R1: Connected to signal ground via high resistance when SW1 is on.

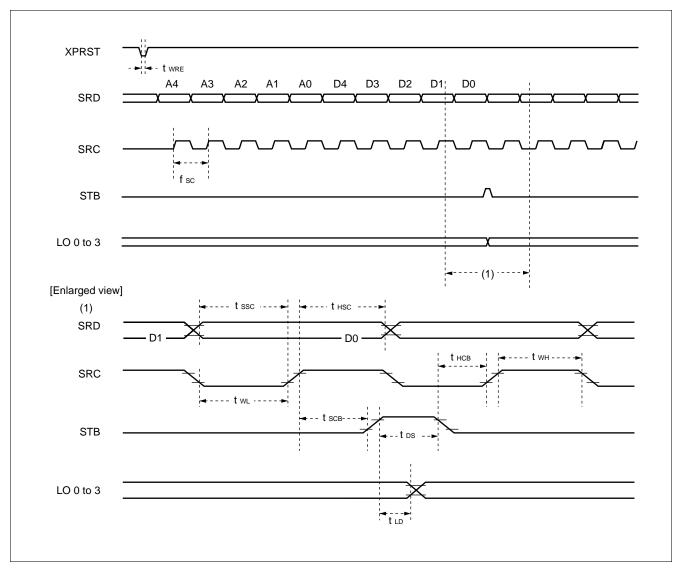
H: High level output

■ TIMING CHART

(1) Codec-Related Signals



(2) Microcomputer Data-Related Signals



■ ABSOLUTE MAXIMUM RATINGS (See WARNING)

| Parameter | Symbol | Rat | Unit | |
|-----------------------|-----------------|------|-----------------------|-------|
| Farameter | Symbol | Min. | Max. | Offic |
| Power supply voltage | V _{DD} | -0.3 | +6.0 | V |
| Analog input voltage | Vain | -0.3 | V _{DD} + 0.3 | V |
| Digital input voltage | Vdin | -0.3 | V _{DD} + 0.3 | V |
| Storage temperature | Tstg | -55 | +125 | °C |

WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

■ RECOMMENDED OPERATING CONDITIONS

| Doromotor | Symbol | Din nama | | Value | | l lmi4 |
|---------------------------------|-----------------|------------------------------|----------------------------|-------|-----------------------|--------|
| Parameter | Symbol | Pin name | Min. | Тур. | Max. | Unit |
| Operating temperature | Та | _ | -20 | 25 | 80 | °C |
| Power supply voltage | V _{DD} | VD1, VD2, VD3 | 2.7 | 3.0 | 3.6 | V |
| "H" level digital input voltage | Vн | All digital input ping | $V_{\text{DD}} \times 0.7$ | _ | V _{DD} | V |
| "L" level digital input voltage | VL | All digital input pins | 0.0 | _ | $V_{DD} \times 0.3$ | V |
| Analog output load resistance | RLB | *2 | 50 | _ | _ | kΩ |
| Analog output load capacity | Сьв | BTPO, BBO, PTBO, TBO, SGO | _ | _ | 20 | pF |
| | CLS | Between SGC-VS4 | _ | 10 | _ | μF |
| Analog output load resistance*1 | RLE | Between EAR-XEAR | 28 | 32 | _ | Ω |
| Analog output load capacity*1 | CLE | EAR, Between XEAR-GND | 0.1 | _ | _ | μF |
| Analog output load resistance*1 | RLJ | JEAR | 28 | 32 | _ | Ω |
| Analog output load capacity*1 | CLJ | Between JEAR-GND | 0.1 | _ | _ | μF |
| Analog output load resistance | Rlt | TONE | 600 | _ | _ | Ω |
| Analog output load capacity | Сьт | TONE | _ | _ | 100 | pF |
| Analog output load resistance | RLM | MICO IMICO | 10 | _ | _ | kΩ |
| Analog output load capacity | Сьм | MICO, JMICO | _ | _ | 20 | pF |
| Analog output load resistance | RLM | RAUD | 5 | _ | _ | kΩ |
| Analog output load capacity | Сьм | KAUD | _ | _ | 20 | pF |
| Analog output voltage | VAOUT | All Amp. output pins | 0.45 | _ | V _{DD} -0.45 | V |
| Analog input voltage | Vain | All Amp. input pins | 1.2 | 1.5 | 1.8 | V |
| TCLK frequency | FTCLK | TCLK | _ | _ | 4.0 | MHz |

^{*1:} Dynamic typ speakers

^{*2:} BTPO, BBO, PTBO, TBO, SGC, SGO

■ ELECTRICAL CHARACTERISTICS

1. DC Characteristics

| Donomotor | Cumbal | Dim | Conditions | | Value | | Unit |
|---|------------------|--------------------------|---|---------------------|-------|---------------------|------|
| Parameter | Symbol | Pin | Conditions | Min. | Тур. | Max. | Unit |
| Power supply current at full power-down mode | I _{PD} | | PS = 0 Digital input = GND | _ | 0.5 | 50 | μА |
| Power supply current for normal operation (all operation) | I _{VD2} | All V _{DP} pins | All blocks operating, CLK = 2048, SYNC = 8 kHz, no signal | _ | 5.0 | 10 | mA |
| Digital input current | Іін | All digital input | _ | | _ | 10 | μΑ |
| Digital input current | Iı∟ | pins | _ | _ | _ | 10 | μΑ |
| Digital output voltage | Vон | All digital | Iон = $-1.5 mA$ | $V_{DD} \times 0.8$ | _ | V_{DD} | V |
| Digital output voltage | Vol | output pins | IoL = 1.5 mA | 0.0 | _ | $V_{DD} \times 0.2$ | V |
| Input offset voltage | VFM | Between MIC-XMIC | MICO-MIC short | -10 | _ | 10 | mV |
| Output offset voltage | VFE | Between EAR-XEAR | TBO-TBI short EV6 = 0 dB | -20 | _ | 20 | mV |
| SGC output voltage | Vsgc | SGC | _ | 1.40 | 1.50 | 1.60 | V |
| | Rsw | Between SWI-SWO | SW12 = on | _ | _ | 2 | kΩ |
| | RTE | Between TAUD-EXSD | SW10 = on, SW11 = off, SW5 = off | _ | _ | 2 | kΩ |
| Inter-pin resistance | R _{TD} | Between TAUD-DSCK | SW10 = off, SW11 = on, SW5 = off | _ | _ | 2 | kΩ |
| | Rтg | Between TONE-VS | SW14 = on | _ | _ | 2 | kΩ |
| | R _{BS} | Between BBO-STA | SW1 = on | _ | _ | 2 | kΩ |
| | RITA | TAUD | Operating | 70 | 100 | 140 | kΩ |
| Input resistance | RIMDA | MDI | Operating, SW16 = ATT | 100 | 140 | 200 | kΩ |
| imput resistance | RIMD | MDI | Operating, SW16 = envelope | 150 | 210 | 300 | kΩ |
| Analog output off leak | Іоғн | RAUD, TONE | SW8a, SW9a, b, c, 14 = off, Vin = 0 to V _{DD} | -10 | _ | 10 | μΑ |

Note: Measurement conditions: ■ Standard Test Circuit

2. AC Characteristics

(1) Codec-Related Signals

| Parameter | Symbol | Conditions | | Value | | Unit |
|-----------------------------|------------------------|---|----------|-------|----------|------|
| Parameter | Symbol | Conditions | Min. | Тур. | Max. | Unit |
| Digital input rise time | t R | $Vs \times 0.3 \rightarrow Vs \times 0.7$ | _ | _ | 50 | ns |
| Digital input fall time | tF | $VS \times 0.3 \rightarrow VS \times 0.7$ | _ | _ | 50 | ns |
| Shift alook fraguency | fc | μ-law, A-law | 64 | _ | 3152 | kHz |
| Shift clock frequency | IC | Linear | 128 | _ | 3152 | kHz |
| Shift clock pulse width (H) | twcн | $V_{IH} = V_S \times 0.7$ | 1/fc×0.3 | _ | 1/fc×0.7 | ns |
| Shift clock pulse width (L) | twcL | V _{IL} = V _S × 0.3 | 1/fc×0.3 | _ | 1/fc×0.7 | ns |
| Sync frequency | f s | _ | _ | 8 | _ | kHz |
| Sync pulse width | twsн | _ | 1/fc | _ | 62 | μs |
| SYNC to CLK setup time | tsx | _ | 100 | _ | _ | ns |
| CLK to SYNC hold time | txs | _ | 50 | _ | _ | ns |
| CLK to DIN hold time | t _{RD} | _ | 50 | _ | _ | ns |
| DIN to CLK setup time | t DR | _ | 50 | _ | _ | ns |
| SYNC to DOUT delay time | t zD | BIT 1 | _ | _ | 200 | ns |
| CLK to DOUT delay time | tco | BIT 2 to 8 | _ | _ | 200 | ns |
| CLK to DOUT disable time | t DZ | "H" | _ | _ | 200 | ns |

(2) Microcomputer Data-Related Signals

| Parameter | Symbol | Pin | | Value | | Unit |
|----------------------------|--------------|----------|------|-------|------|-------|
| raiailletei | Syllibol | FIII | Min. | Тур. | Max. | Oilit |
| SRC to SRD data setup time | tssc | SRD, SRC | 50 | _ | _ | ns |
| SRC to SRD data hold time | t HSC | SKD, SKC | 50 | _ | _ | ns |
| SRC to STB setup time | tscв | SRC, STB | 50 | _ | _ | ns |
| SRC pulse width (H) | twн | SRC | 200 | _ | _ | ns |
| SRC pulse width (L) | tw∟ | SKC | 200 | _ | _ | ns |
| STB pulse width | t os | STB | 50 | _ | _ | ns |
| STB to SRC hold time | t нсв | STB, SRC | 50 | _ | _ | ns |
| LO0 to 3 delay time | t LD | LO0 to 3 | _ | _ | 200 | ns |
| Shift clock frequency | fsclk | SRC | _ | _ | 2048 | kHz |
| Reset pulse width | twre | XPRST | 1 | _ | _ | μs |

3. Transmission Characteristics

(1) Microphone Amp System

| Doromotor | Symbol | Conditions | | Value | | Unit |
|--|-----------------|---|------|-------|------|------|
| Parameter | Symbol | Conditions | Min. | Тур. | Max. | Unit |
| Gain (between MICO and BBO) | G _{мв} | MICO = -20 dBV, 1020 Hz SW3 = on, SW1 = SW4 = SW5 = off EV0 = 0 dB | -1.5 | _ | 1.5 | dB |
| Gain (between JMICO and BBO) | G JB | JMICO = -20 dBV, 1020 Hz SW4 = on, SW1 = SW3 = SW5 = off EV0 = 0 dB | -1.5 | _ | 1.5 | dB |
| Gain (between TAUD and BBO) | Gтв | TAUD = -20 dBV, 1020 Hz SW5 = on, SW1 = SW3 = SW4 = off EV0 = 0 dB | -1.5 | _ | 1.5 | dB |
| Signal to noise ratio (Microphone amp [1]) | Ѕмв | Ain1 = -40 dBV (+20 dBgain), 1020 Hz SW3 = on, SW1 = SW4 = SW5 = off C message, Measured at MICO | 40 | _ | _ | dB |
| Signal to noise ratio (Microphone amp [2]) | Ѕјв | Ain2 = -40 dBV (+20 dBgain), 1020 Hz SW4 = on, SW1 = SW3 = SW5 = off C message, Measured at JMICO | 40 | _ | _ | dB |
| Signal to noise ratio (BBO) | Sтв | TAUD = -40 dBV, 1020 Hz, SW5 = on, SW1 = SW3 = SW4 = SW10 = SW11 = off, EV0 = 0 dB, C message, Measured at BBO | 40 | _ | _ | dB |

Note: Measurement conditions: ■ Standard Test Circuit

(2) Reception

| Parameter | Symbol | Conditions | | Value | | Unit |
|-----------------------|----------------------|---|------|-------|------|-------|
| Parameter | Symbol | Conditions | Min. | Тур. | Max. | Ullit |
| | Gtr | Measured at RAUD | -1 | 0 | 1 | |
| Gain | GTE | EV6 = 0 dB, Measured between EAR and XEAR | 5 | 6 | 7 | dB |
| Conditions: | G тл | EV7 = 0 dB, Measured at JEAR | -1 | 0 | 1 | ub |
| TBO = -20 dB, 1020 Hz | Gтт | EV8 = 0 dB, SW9b = on, SW9c = off, Measured at TONE | -1 | 0 | 1 | |
| Output power | PE EV6 = 0 dB, THD = | R = 32 Ω , Between EAR and XEAR, EV6 = 0 dB, THD = 10%, 1020 Hz | 10.0 | _ | _ | mW |
| Output power | Рл | R = 32 Ω , JEAR, EV7 = 0 dB, THD = 10%, 1020 Hz | 5.0 | _ | _ | mW |
| Signal to noise ratio | Str | TBO = -40 dBV, 1020 Hz, SW6b = SW7b = SW8b = SW9b = on, SW15 = AMP4, EV6, 7, 8 = 0 dB C message, RAUD, EAR-XEAR, Measured at JEAR | 40 | _ | _ | dB |
| | S тл | SGO = -40 dBV, 1020 Hz, SW7b = on, SW15 = AMP5, C message, Measured at JEAR | 40 | _ | _ | dB |

Note: Measurement conditions: ■ Standard Test Circuit

(3) TONE

| Doromotor | Symbol | Conditions | | Value | | Unit |
|-------------------|--------|---|-------|-------|-------|------|
| Parameter | Symbol | Conditions | Min. | Тур. | Max. | Unit |
| TONE output level | GT1 | Generating 1 tone, f_1 = 948.1 kHz, sine wave SW2 = off, SW9b = off, SW9c = on, MDI = OPEN EV3 = 15 dB, EV4 = -15 dB, EV9 = 0 dB, Measured at TONE | -12.0 | -14.0 | -16.0 | dBV |
| | GT2 | Generating 2 tones, f_1 = 948.1 kHz, f_2 = 1219.1 kHz, simultaneous sine wave generation SW2 = off, SW9b = off, SW9c = on, MDI = OPEN EV3 = 15 dB, EV4 = -15 dB, EV9 = 0 dB, Measured at TONE | -12.0 | -14.0 | -16.0 | dBV |
| | GT3 | MDI = 1020 Hz, -10 dBV input SW2 = on, SW13 = off, DUAL TONE = off EV2 = 0 dB, EV3 = 15 dB, EV4 = -15 dB, EV5 = -14 dB, Measured at PTBO | -27.0 | -29.0 | -31.0 | dB |
| Harmonic level | Нтт | EV3 = 15 dB, EV4 = -15 dB, EV9 = 0 dB, SW9c = on SW2 = SW9b = off, MDI = OPEN, Generating a single tone, Measured at TONE, nth harmonic level (n = 2 to 5) | _ | _ | -38 | dB |
| | Нтр | EV3 = 15 dB, EV4 = -15 dB, EV5 = -15 dB, EV2 = 15 dB SW2 = on, SW9c = SW13 = off, MDI = OPEN, Generating a single tone, Measured at PTBO, nth harmonic level (n = 2 to 5) | _ | _ | -38 | dB |

(4) Reception and transmission (CODEC, Analog section)

| Parameter | Symbol | Conditions | | | Unit | |
|--|---------|--|------|------|------|------|
| Farameter | Зуппоот | Conditions | Min. | Тур. | Max. | Onne |
| | СТХ | Ain1 = 1020 Hz, -8.5 dBV (0 dBgain) D _{IN} = "H" Measurement: RAUD 1020 Hz | _ | _ | -50 | dB |
| Crosstalk (Reception → transmission) | CTR | D _{IN} = 1020 Hz, 0 dBm 0 A _{IN} = SGC Measurement: DOUT 1020 Hz | _ | _ | -50 | dB |
| Power supply noise rejection ratio | PSRR | 0 < f < 50 kHz, V _{DD} + 30 mV _{OP} C message A _{IN} = SGC, D _{IN} = ICN | _ | 22 | _ | dB |
| Electronic volume gain | GEV | EV0, EV1, EV3, EV5 Gain error relative to reset value Input = 1020 Hz, –20 dBV | -0.7 | _ | 0.7 | dB |
| error | | EV2, EV4, EV6, EV7, EV8, EV9 Gain error relative to reset value Input = 1020 Hz, –20 dBV | -1.0 | _ | 1.0 | dB |

(Continued)

| Darameter | Symbol | Can distance | Value | | | Unit |
|---|------------------|--|-------------|------|------|------|
| Parameter | | Conditions | | Тур. | Max. | Unit |
| Gms Mute level Gms Gms | Gmsw2 | SW2 = SW3 = off, EV4 = -15 dB EV2 = 0 dB, EV3 = 15 dB MDI = 1020 Hz, -30 dBV Measured at PTBO | _ | _ | -40 | dB |
| | Gmsw34 | SW1, 3, 4, 5 = off, EV0 = 0 dB AIN1 or AIN2 = 1020 Hz, -30 dBV Measured at BBO | _ | _ | -40 | dB |
| | Gmsw5 | SW1, 3, 4, 5 = off, EV0 = 0 dB TAUD = 1020 Hz, -30 dBV, Measured at BBO | _ | _ | -40 | dB |
| | Gmsw69 | SW6b = SW7b = SW8b = SW9b = SW9c = off EV6, 7, 8, 9 = 0 dB, TBO = 1020 Hz, -30 dBV MDI = 1020 Hz-30 dBV, EV4 = 0 dB RAUD, EAR, XEAR, JEAR, Measured at TONE | _ | _ | -40 | dB |
| | Gmsw13 | SW13 = SW2 = off, EV1, 2 = 0 dB, D_{IN} = 1020 Hz, 0 dBm0, Measured at PTBO | _ | _ | -40 | dB |
| | Gmsw15a | SW15 = AMP4, TBI-TBO = short SGO = 1020 Hz, -30 dBV, Measured at JEAR | _ | _ | -40 | dB |
| | Gmsw15b | SW15 = AMP5, SGI-SGO = short TBO = 1020 Hz, -30 dBV, Measured at JEAR | _ | _ | -40 | dB |
| Electronic volume | VEV0off (EV0) | SW3 = on, SW4 = SW5 = off MIC-MICO, SGC-XMIC = short Measured between SGC and BBO when EV0 variable | -10 | _ | 10 | mV |
| | VEV1off (EV1) | SW2 = off, SW13 = on, EV2 = 0 dB SYNC = 8 kHz, CLK = 2048 kHz, D _{IN} = ICN Measured between SGC and PTBO when EV1 variable | -25 | _ | 25 | mV |
| offset variation (amount of change for 1 step) | VEV2off (EV2) | SW2 = off, SW13 = on, EV1 = 0 dB SYNC = 8 kHz, CLK = 2048 kHz, D _{IN} = ICN Measured between SGC and PTBO when EV2 variable | -25 | _ | 25 | mV |
| VEV3off (EV3) | VEV3off (EV3) | Tone generation = off, SW9a, 9b = off, SW9c = on, EV4 = -15 dB, EV9 = 0 dB, MDI = open Measured between SGC and TONE when EV3 variable | –7 0 | _ | 70 | mV |
| Electronic volume offset variation (amount of change for 1 step) | VEV4off (EV4) | Tone generation = off, MDI = open, EV3 = 15 dB, EV9 = 0 dB, SW9a = 9b = off, SW9c = on Measured between SGC and TONE when EV4 variable | -300 | _ | 300 | mV |
| | VEV5off (EV5) | Tone generation = off, MDI = open, EV3 = 15 dB, EV2 = 0 dB EV4 = -15 dB, SW2 = on, SW13 = off Measured between SGC and PTBO when EV5 variable | - 5 | _ | 5 | mV |

| Doromotor | Symbol | Conditions | Value | | | Unit |
|--|--------------------|---|------------|------|------|------|
| Parameter | | Conditions | Min. | Тур. | Max. | Jill |
| Electronic volume offset variation (amount of change for 1 step) VE | VEV6off (EV6) | SW6b = on, SW6a = off TBI-TBO = short Measured between SGC and EAR when EV6 variable | – 5 | _ | 5 | mV |
| | VEV7off (EV7) | SW7b = on, SW7a = off, SW15 = AMP4 TBI-TBO = short Measured between SGC and JEAR when EV7 variable | – 5 | _ | 5 | mV |
| | VEV8off (EV8) | SW9b = on, SW9a, 9c = off TBI-TBO = short Measured between SGC and TONE when EV8 variable | -50 | _ | 50 | mV |
| | VEV9off (EV9) | Tone generation = off, MDI = open, EV3 = 15 dB EV4 = -15 dB, SW9c = on, SW9a, 9b = off Measured between SGC and TONE | -140 | _ | 140 | mV |
| Change in DC offset during mute | VSW2off (SW2) | SW13 = off, EV2 = 0 dB, EV3 = 15 dB, EV4 = -15 dB EV5 = -14 dB, Tone = off, MDI = open Measured at PTBO for SW2 on and off | -30 | _ | 30 | mV |
| | VSW3off (SW3) | SW1, 4, 5 = off, EV0 = 0 dB MIC-MICO = short Measured at BBO for SW3 on and off | | _ | 20 | mV |
| | VSW4off (SW4) | SW1, 3, 5 = off, EV0 = 0 dB JMIC-JMICO = short Measured at BBO for SW4 on and off | -20 | _ | 20 | mV |
| | VSW5off (SW5) | SW1, 3, 4, 10, 11 = off, EV0 = 0 dB TAUD = SGC Measured at BBO for SW5 on and off | -10 | _ | 10 | mV |
| | VSW6off (SW6b) | SW7a, 8a, 9a = off, EV6 = -8 dB TBI-TBO = short, EV7 = -3 dB Measured at EAR, XEAR for SW6b on and off | -10 | _ | 10 | mV |
| | VSW7off (SW7b) | SW6a, 8a, 9a = off, SW15 = AMP4 EV7 = -3 dB, TBI-TBO = short Measured at JEAR for SW7b on and off | -10 | _ | 10 | mV |
| | VSW8off (SW8b) | SW6a, 7a, 9a = off TBI-TBO = short Measured at RAUD for SW8b on and off | -20 | _ | 20 | mV |
| | VSW9boff (SW9b) | SW6a, 7a, 8a, 9c = off, EV8 = 10 dB MDI = open, TBI-TBO = short Measured at TONE for SW9b on and off | -65 | _ | 65 | mV |
| | VSW9off (SW9c) | SW6a, 7a, 8a, 9b = off, EV9 = 6 dB MDI = open, TBI-TBO = short Measured at TONE for SW9c on and off | -300 | _ | 300 | mV |
| | VSWDoff (SW13) | SW2 = off, EV1, 2 = 0 dB, D _{IN} = ICN SYNC = 8 kHz, CLK = 2048 kHz Measured at PTBO for SW13 on and off | -90 | _ | 90 | mV |

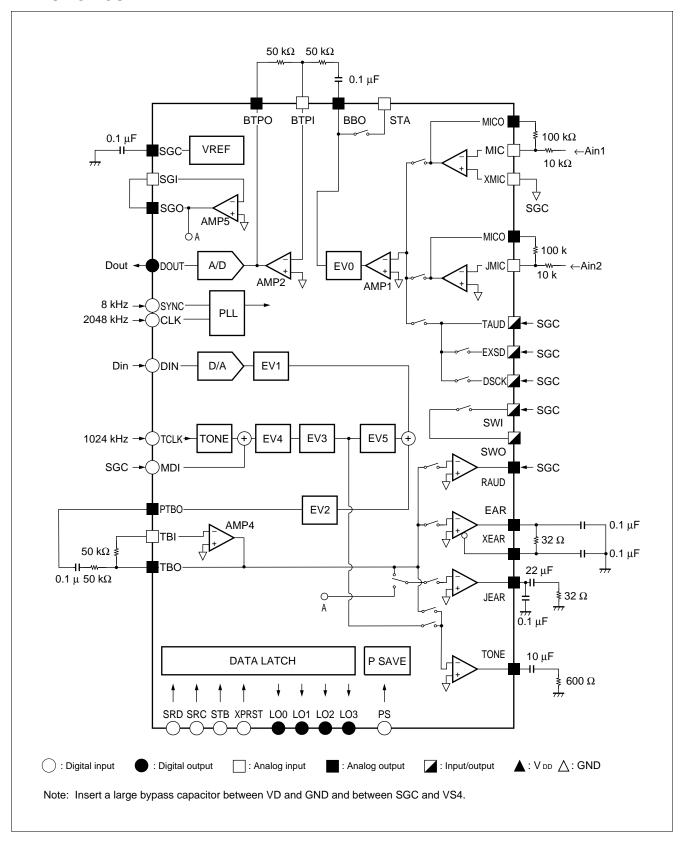
(5) Codec

| Dovernator | Symbol | Conditions | | Value | | | Unit |
|---|--------|---|-----------------------|-------|------|------|-------|
| Parameter | Symbol | | | Min. | Тур. | Max. | Oilit |
| | GTX | 1020 Hz, –10 dBm0 Reference value (μ-law) | +3 to -40 dBm0 | -0.3 | | 0.3 | dB |
| | | | -40 to -50 dBm0 | -0.5 | - | 0.5 | dB |
| BTPO → DOUT | | | -50 to -55 dBm0 | -1.0 | 1 | 1.0 | dB |
| Gain tracking | GTR | 1020 Hz, -10 dBm0 Reference value (μ-law) | +3 to -40 dBm0 | -0.3 | | 0.3 | dB |
| (D to A) | | | -40 to -50 dBm0 | -0.5 | _ | 0.5 | dB |
| DIN → PTBO | | EV1 = EV2 = 0 dB | -50 to -55 dBm0 | -1.0 | _ | 1.0 | dB |
| Gain tracking | | | AFST to AFST-43 dB | -0.3 | | 0.3 | dB |
| (A to D) (Linear) | GTXL | 1020 Hz, AFST–13 dB Reference value | AFST-43 to AFST-53 dB | -0.5 | | 0.5 | dB |
| BTPO → DOUT | | | AFST-53 to AFST-58 dB | -1.0 | _ | 1.0 | dB |
| Gain tracking | GTRL | 1020 Hz, AFSR-13 dB Reference value EV1 = EV2 = 0 dB | AFSR to AFSR-43 dB | -0.3 | | 0.3 | dB |
| (D to A) (Linear) | | | AFSR-43 to AFSR-53 dB | -0.5 | _ | 0.5 | dB |
| $DIN \to PTBO$ | | | AFSR-53 to AFSR-58 dB | -1.0 | _ | 1.0 | dB |
| Transmitting frequency characteristics | FRX | 0 dBm0 1020 Hz Reference value | 0 to 60 Hz | 24.0 | _ | _ | dB |
| | | | 60 to 300 Hz | -0.20 | _ | _ | dB |
| | | | 300 to 3000 Hz | -0.20 | _ | 0.20 | dB |
| (A to D) | | | 3000 to 3400 Hz | -0.20 | _ | 0.8 | dB |
| BTPO → DOUT | | | 3400 to 4600 Hz | * | _ | _ | dB |
| | | | 4600 to 12 kHz | 32.0 | | _ | dB |
| Receiving frequency characteristics (D to A) DIN → PTBO | FRR | 0 dBm0 1020 Hz Reference value EV1 = EV2 = 0 dB | 0 to 300 Hz | -0.30 | _ | _ | dB |
| | | | 300 to 3000 Hz | -0.30 | _ | 0.30 | dB |
| | | | 3000 to 3400 Hz | -0.30 | | 1.10 | dB |
| | | | 3400 to 4600 Hz | * | _ | _ | dB |
| | | | 4600 to 12 kHz | 32.0 | | _ | dB |
| Transmitting absolute gain (A to D) BTPO → DOUT | GAX | 1020 Hz, 0 dBm0 (Linear: AFST-3 dB) Vs = 3.0 V, Ta = +25°C | | -1.0 | 0 | 1.0 | dB |
| Receiving absolute gain (D to A) DIN → PTBO | GAR | 1020 Hz, 0 dBm0 (Linear: AFSR-3 dB) EV1 = EV2 = 0 dB, Vs = 3.0 V, Ta = +25°C | | -1.20 | 0 | 1.20 | dB |

*:
$$14.5 \times \{1 - Sin \frac{\pi (4000 - f)}{1200}\}$$

| Downwater | Comb al | Conditions | | Value | | | Unit |
|--|---------|--|----------------------|--------|--------|--------|-------|
| Parameter | Symbol | | | Min. | Тур. | Max. | Offic |
| Transmitting signal to | | 1020 Hz | 0 to -30 dBm0 | 34.0 | _ | _ | dB |
| noise ratio (A to D) | SDX | C message | -40 dBm0 | 28.0 | _ | _ | dB |
| BTPO → DOUT | | (μ-law) | -45 dBm0 | 23.0 | _ | _ | dB |
| Receiving signal to | | 1020 Hz C message EV1 = EV2 = 0 dB | 0 to -30 dBm0 | 34.0 | _ | _ | dB |
| noise ratio (D to A) | SDR | | –40 dBm0 | 28.0 | _ | _ | dB |
| DIN → PTBO | | (μ-law) | –45 dBm0 | 23.0 | _ | _ | dB |
| Transmitting signal to noise ratio | | 1020 Hz C message | AFST-3 to AFST-33 dB | 34.0 | _ | _ | dB |
| (A to D) BTPO → DOUT | SDXL | | AFST-43 dB | 28.0 | _ | _ | dB |
| (Linear) | | | AFST-48 dB | 23.0 | _ | _ | dB |
| Recieving signal to noise ratio | | 1020 Hz C message EV1 = EV2 = 0 dB | AFSR-3 to AFSR-33 dB | 34.0 | | _ | dB |
| (D to A) SDRL | SDRL | | AFSR-43 dB | 28.0 | _ | | dB |
| DIN → PTBO (Linear) | | | AFSR-48 dB | 23.0 | _ | _ | dB |
| Transmitting no-talk noise BTPO → DOUT | ICNX | C message | | _ | -72 | -69 | dBm0C |
| Receiving no-talk noise DIN → PTBO | ICNR | C message EV1 = EV2 = 0 dB | | _ | -75 | -70 | dBm0C |
| Analog input level BTPO | AILU | 1020 Hz, 0 dBm0, Ta = +25°C Vs = 3.0 V μ-law | | 0.3290 | 0.3739 | 0.4195 | Vrms |
| Analog output level PTBO | AOLU | 1020 Hz, 0 dBm0, Ta = +25°C $Vs = 3.0 \text{ V}$ μ -law $EV1 = EV2 = 0 \text{ dB}$ | | 0.3290 | 0.3739 | 0.4195 | Vrms |
| Analog input fullscale level BTPO | AFST | Vs = 3.0 V, Ta = +25°C Linear | | 0.6729 | 0.7647 | 0.8581 | Vop |
| Analog output fullscale level PTBO | AFSR | Vs = 3.0 V, Ta = +25°C Linear EV1 = EV2 = 0 dB | | 0.6729 | 0.7647 | 0.8581 | Vop |

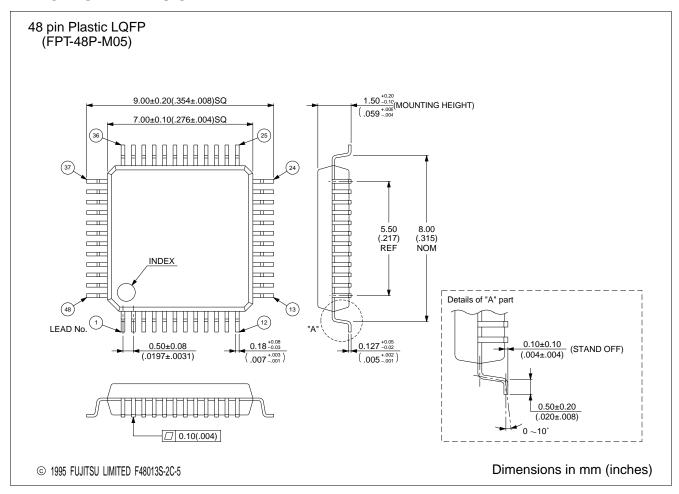
■ TEST CIRCUIT



■ ORDERING INFORMATION

| Part number | Package | Remarks | | |
|-------------|--|---------|--|--|
| MB86437PFV | 48 pins, Plastic LQFP (FPT-48P-M05) | | | |

■ PACKAGE DIMENSION



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