

Low Power, Chip Scale 10-Bit SD/HD Video Encoder

ADV7390/ADV7391/ADV7392/ADV7393

FEATURES

3 high quality, 10-bit video DACs

16× (216 MHz) DAC oversampling for SD

8× (216 MHz) DAC oversampling for ED

4× (297 MHz) DAC oversampling for HD

37 mA maximum DAC output current

Multiformat video input support

4:2:2 YCrCb (SD, ED, and HD)

4:4:4 RGB (SD)

Multiformat video output support

Composite (CVBS) and S-Video (Y/C)

Component YPrPb (SD, ED, and HD)

Component RGB (SD, ED, and HD)

Lead frame chip scale package (LFCSP) options

32-lead, 5 mm × 5 mm LFCSP

40-lead, 6 mm × 6 mm LFCSP

Advanced power management

Patented content-dependent low power DAC operation

Automatic cable detection and DAC power-down

Individual DAC on/off control

Sleep mode with minimal power consumption

74.25 MHz 8-/10-/16-bit high definition input support

Compliant with SMPTE 274M (1080i), 296M (720p), and 240M (1035i)

EIA/CEA-861B compliance support

NTSC M, PAL B/D/G/H/I/M/N, PAL 60 support

NTSC and PAL square pixel operation (24.54 MHz/29.5 MHz)

Macrovision® Rev 7.1.L1 (SD) and Rev 1.2 (ED) compliant

Programmable features

Luma and chroma filter responses

Vertical blanking interval (VBI)

Subcarrier frequency (F_{SC}) and phase

Luma delay

Copy generation management system (CGMS)

Closed captioning and wide screen signaling (WSS)

Integrated subcarrier locking to external video source

Complete on-chip video timing generator

On-chip test pattern generation

Serial MPU interface with dual I²C® and SPI® compatibility

2.7 V or 3.3 V analog operation

1.8 V digital operation

3.3 V I/O operation

Temperature range: -40°C to +85°C

APPLICATIONS

Mobile handsets

Digital still cameras

Portable media and DVD players

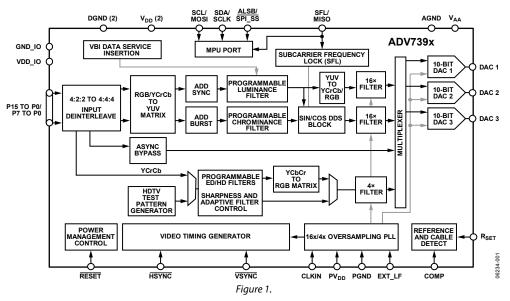
Portable game consoles

Digital camcorders

Set-top box (STB)

Automotive infotainment (ADV7393 only)

FUNCTIONAL BLOCK DIAGRAM



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REVISION HISTORY

10/06—Revision 0: Initial Version

DETAILED FEATURES

High definition (HD) programmable features

(720p/1080i/1035i)

4× oversampling (297 MHz)

Internal test pattern generator

Color and black bar, hatch, flat field/frame

Fully programmable YCrCb to RGB matrix

Gamma correction

Programmable adaptive filter control

Programmable sharpness filter control

CGMS (720p/1080i) and CGMS Type B (720p/1080i)

Dual data rate (DDR) input support

EIA/CEA-861B compliance support

Enhanced definition (ED) programmable features

(525p/625p)

8× oversampling (216 MHz output)

Internal test pattern generator

Color and black bar, hatch, flat field/frame

Individual Y and PrPb output delay

Gamma correction

Programmable adaptive filter control

Fully programmable YCrCb to RGB matrix

Undershoot limiter

Macrovision Rev 1.2 (525p/625p)

CGMS (525p/625p) and CGMS Type B (525p)

Dual data rate (DDR) input support

EIA/CEA-861B compliance support

Standard definition (SD) programmable features

16× oversampling (216 MHz)

Internal test pattern generator

Color and black bar

Controlled edge rates for start and end of active video

Individual Y and PrPb output delay

Undershoot limiter

Gamma correction

Digital noise reduction (DNR)

Multiple chroma and luma filters

 $\textbf{Luma-SSAF}^{\textbf{m}} \textbf{ filter with programmable gain/attenuation}$

PrPb SSAF™

Separate pedestal control on component and

composite/S-Video output

VCR FF/RW sync mode

Macrovision Rev 7.1.L1

Copy generation management system (CGMS)

Wide screen signaling (WSS)

Closed captioning

EIA/CEA-861B compliance support

GENERAL DESCRIPTION

The ADV7390/ADV7391/ADV7392/ADV7393 are a family of high speed, digital-to-analog video encoders on single monolithic chips. Three 2.7 V/3.3 V 10-bit video DACs provide support for composite (CVBS), S-Video (YC), or component

(YPrPb/RGB) analog outputs in either standard-definition (SD) or high-definition (HD) video formats.

Optimized for low power operation, occupying a minimal footprint and requiring few external components, these encoders are ideally suited to portable and power sensitive applications requiring TV-Out functionality. Cable detection and DAC auto power-down features ensure that power consumption is kept to a minimum.

The ADV7390/ADV7391 have an 8-bit video input port that supports SD video formats over a SDR interface and HD video formats over a DDR interface.

The ADV7392/ADV7393 have a 16-bit video input port that can be configured in a variety of ways. SD RGB input is supported.

All members of the family support embedded EAV/SAV timing codes, external video synchronization signals and the $\rm I^2C$ and SPI communication protocols.

Table 1 lists the video standards directly supported by the ADV739x family.

Table 1. Standards Directly Supported by the ADV739x1

		Frame	Clock Input	
Resolution	I/P ²	Rate (Hz)	(MHz)	Standard
720×240	Р	59.94	27	
720×288	Р	50	27	
720×480	1	29.97	27	ITU-R
				BT.601/656
720×576	I	25	27	ITU-R
				BT.601/656
720×480	I	29.97	24.54	NTSC Square Pixel
720 × 576	١.	25	29.5	
720×576	I	25	29.5	PAL Square Pixel
720×483	Р	59.94	27	SMPTE 293M
720×483	Р	59.94	27	BTA T-1004
720×483	Р	59.94	27	ITU-R BT.1358
720×576	Р	50	27	ITU-R BT.1358
720×483	Р	59.94	27	ITU-R BT.1362
720×576	Р	50	27	ITU-R BT.1362
1920×1035	1	30	74.25	SMPTE 240M
1920 × 1035	1	29.97	74.1758	SMPTE 240M
1280×720	Р	60, 50, 30,	74.25	SMPTE 296M
		25, 24		
1280×720	Р	23.97,	74.1758	SMPTE 296M
		59.94, 29.97		
1920×1080	I	30, 25	74.25	SMPTE 274M
1920×1080	I	29.97	74.1758	SMPTE 274M
1920×1080	Р	30, 25, 24	74.25	SMPTE 274M
1920×1080	Р	23.98, 29.97	74.1758	SMPTE 274M
1920×1080	Р	24	74.25	ITU-R BT.709-
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 $^{^{\}rm 1}$ Other standards are supported in the ED/HD nonstandard timing mode.

² I = interlaced, P = progressive.

SPECIFICATIONS

POWER SUPPLY SPECIFICATIONS

All specifications T_{MIN} to T_{MAX} (-40°C to +85°C), unless otherwise noted.

Table 2.

Parameter	Conditions	Min	Тур	Max	Unit
SUPPLY VOLTAGES					
V_{DD}		1.71	1.8	1.89	V
V_{DD_IO}		2.97	3.3	3.63	V
PV_{DD}		1.71	1.8	1.89	V
V_{AA}		2.6	3.3	3.465	V
POWER SUPPLY REJECTION RATIO			0.002		%/%

INPUT CLOCK SPECIFICATIONS

 V_{DD} = 1.71 V to 1.89 V, PV_{DD} = 1.71 V to 1.89 V, V_{AA} = 2.6 V to 3.465 V, V_{DD_IO} = 2.97 V to 3.63 V. All specifications T_{MIN} to T_{MAX} (-40°C to +85°C), unless otherwise noted.

Table 3.

Parameter	Conditions ¹	Min	Тур	Max	Unit
f _{CLKIN}	SD/ED		27		MHz
	ED (at 54 MHz)		54		MHz
	HD		74.25		MHz
CLKIN High Time, t ₉		40			% of one clock cycle
CLKIN Low Time, t ₁₀		40			% of one clock cycle
CLKIN Peak-to-Peak Jitter Tolerance			2		±ns

¹ SD = standard definition, ED = enhanced definition (525p/625p), HD = high definition.

ANALOG OUTPUT SPECIFICATIONS

 $V_{\rm DD}=1.71~V~to~1.89~V,~PV_{\rm DD}=1.71~V~to~1.89~V,~V_{\rm AA}=2.6~V~to~3.465~V,~V_{\rm DD_IO}=2.97~V~to~3.63~V.~All~specifications~T_{\rm MIN}~to~T_{\rm MAX}~(-40^{\circ}C~to~+85^{\circ}C),~unless~otherwise~noted.$

Table 4.

Parameter	Conditions	Min	Тур	Max	Unit
Full-Drive Output Current	$R_{SET} = 510 \Omega$, $R_L = 37.5 \Omega$	33	34.6	37	mA
Low Drive Output Current	$R_{SET} = 4.12 \text{ k}\Omega, R_L = 300 \Omega$		4.3		mA
DAC-to-DAC Matching	DAC 1, DAC 2, DAC 3		2.0		%
Output Compliance, Voc		0		1.4	V
Output Capacitance, C _{OUT}			10		рF
Analog Output Delay ¹			6		ns
DAC Analog Output Skew	DAC 1, DAC 2, DAC 3		1		ns

Output delay measured from the 50% point of the rising edge of the input clock to the 50% point of the DAC output full-scale transition.

DIGITAL INPUT/OUTPUT SPECIFICATIONS

 $V_{DD}=1.71~V~to~1.89~V, PV_{DD}=1.71~V~to~1.89~V, V_{AA}=2.6~V~to~3.465~V, V_{DD_IO}=2.97~V~to~3.63~V.$ All specifications T_{MIN} to T_{MAX} ($-40^{\circ}C$ to $+85^{\circ}C$), unless otherwise noted.

Table 5.

Parameter	Conditions	Min	Тур	Max	Unit
Input High Voltage, V _{IH}		2.0			V
Input Low Voltage, V _I L				0.8	V
Input Leakage Current, I _{IN}	$V_{IN} = V_{DD_IO}$			±10	μΑ
Input Capacitance, C _{IN}			4		pF
Output High Voltage, V _{OH}	$I_{SOURCE} = 400 \mu A$	2.4			V
Output Low Voltage, Vol	$I_{SINK} = 3.2 \text{ mA}$			0.4	V
Three-State Leakage Current	$V_{IN} = 0.4 \text{ V}, 2.4 \text{ V}$			±1	μΑ
Three-State Output Capacitance			4		pF

MPU PORT TIMING SPECIFICATIONS

 V_{DD} = 1.71 V to 1.89 V, PV_{DD} = 1.71 V to 1.89 V, V_{AA} = 2.6 V to 3.465 V, V_{DD_IO} = 2.97 V to 3.63 V. All specifications T_{MIN} to T_{MAX} (-40°C to +85°C), unless otherwise noted.

Table 6.

Parameter	Conditions	Min	Тур	Max	Unit
MPU PORT, I ² C MODE ¹	See Figure 15				
SCL Frequency		0		400	kHz
SCL High Pulse Width, t ₁		0.6			μs
SCL Low Pulse Width, t ₂		1.3			μs
Hold Time (Start Condition), t₃		0.6			μs
Setup Time (Start Condition), t ₄		0.6			μs
Data Setup Time, t₅		100			ns
SDA, SCL Rise Time, t ₆				300	ns
SDA, SCL Fall Time, t ₇				300	ns
Setup Time (Stop Condition), t ₈		0.6			μs
MPU PORT, SPI MODE ¹	See Figure 16				
SCLK Frequency		0		10	MHz
SPI_SS to SCLK Setup Time, t ₁		20			ns
SCLK High Pulse Width, t ₂		50			ns
SCLK Low Pulse Width, t₃		50			ns
Data Access Time after SCLK Falling Edge, t ₄				35	ns
Data Setup Time prior to SCLK Rising Edge, t ₅		20			ns
Data Hold Time after SCLK Rising Edge, t ₆		0			ns
SPI_SS to SCLK Hold Time, t ₇		0			ns
SPI_SS to MISO High Impedance, t ₈				40	ns

¹ Guaranteed by characterization.

DIGITAL TIMING SPECIFICATIONS

 $V_{\text{DD}} = 1.71 \text{ V to } 1.89 \text{ V}, PV_{\text{DD}} = 1.71 \text{ V to } 1.89 \text{ V}, V_{\text{AA}} = 2.6 \text{ V to } 3.465 \text{ V}, V_{\text{DD_IO}} = 2.97 \text{ V to } 3.63 \text{ V}.$ All specifications T_{MIN} to T_{MAX} (-40°C to +85°C), unless otherwise noted.

Table 7.

Parameter	Conditions ¹	Min	Тур	Max	Unit
VIDEO DATA AND VIDEO CONTROL PORT ^{2, 3}					
Data Input Setup Time, t ₁₁ ⁴	SD	2.1			ns
	ED/HD-SDR	2.3			ns
	ED/HD-DDR	2.3			ns
	ED (at 54 MHz)	1.7			ns
Data Input Hold Time, t ₁₂ ⁴	SD	1.0			ns
	ED/HD-SDR	1.1			ns
	ED/HD-DDR	1.1			ns
	ED (at 54 MHz)	1.0			ns
Control Input Setup Time, t ₁₁ ⁴	SD	2.1			ns
	ED/HD-SDR or ED/HD-DDR	2.3			ns
	ED (at 54 MHz)	1.7			ns
Control Input Hold Time, t ₁₂ ⁴	SD	1.0			ns
	ED/HD-SDR or ED/HD-DDR	1.1			ns
	ED (at 54 MHz)	1.0			ns
Control Output Access Time, t ₁₃ ⁴	SD			12	ns
	ED/HD-SDR, ED/HD-DDR, or ED (at 54 MHz)			10	ns
Control Output Hold Time, t ₁₄ ⁴	SD	4.0			ns
	ED/HD-SDR, ED/HD-DDR, or ED (at 54 MHz)	3.5			ns
PIPELINE DELAY ⁵					
SD ¹					
CVBS/YC Outputs (2×)	SD oversampling disabled		68		clock cycles
CVBS/YC Outputs (8×)	SD oversampling disabled		79		clock cycles
CVBS/YC Outputs (16×)	SD oversampling enabled		67		clock cycles
Component Outputs (2×)	SD oversampling disabled		78		clock cycles
Component Outputs (8×)	SD oversampling disabled		69		clock cycles
Component Outputs (16x)	SD oversampling enabled		84		clock cycles
ED ¹					
Component Outputs (1×)	ED oversampling disabled		41		clock cycles
Component Outputs (4×)	ED oversampling disabled	49		clock cycles	
Component Outputs (8×)	ED oversampling enabled		46		clock cycles
HD ¹					
Component Outputs (1×)	HD oversampling disabled		40		clock cycles
Component Outputs (2×)	HD oversampling disabled		42		clock cycles
Component Outputs (4×)	HD oversampling enabled		44		clock cycles
RESET CONTROL					
RESET Low Time		100			ns

¹ SD = standard definition, ED = enhanced definition (525p/625p), HD = high definition, SDR = single data rate, DDR = dual data rate.

 $^{^2}$ Video Data: P[15:0] for ADV7392/ADV7393 or P[7:0] for ADV7390/ADV7391. 3 Video Control: $\overline{\rm HSYNC}$ and $\overline{\rm VSYNC}$.

⁴ Guaranteed by characterization.

⁵ Guaranteed by design.

VIDEO PERFORMANCE SPECIFICATIONS

Table 8.

Parameter	Conditions	Min Typ	Max	Unit
STATIC PERFORMANCE				
Resolution		10		Bits
Integral Nonlinearity (INL) ¹	$R_{SET} = 510 \Omega$, $R_L = 37.5 \Omega$	0.5		LSBs
Differential Nonlinearity (DNL)1,2	$R_{SET} = 510 \Omega$, $R_L = 37.5 \Omega$	0.5		LSBs
STANDARD DEFINTION (SD) MODE				
Luminance Nonlinearity		0.5		±%
Differential Gain	NTSC	0.5		%
Differential Phase	NTSC	0.6		Degrees
Signal-to-Noise Ratio (SNR) ³	Luma ramp	58		dB
	Flat field full bandwidth	75		dB
ENHANCED DEFINITION (ED) MODE				
Luma Bandwidth		12.5		MHz
Chroma Bandwidth		5.8		MHz
HIGH DEFINITION (HD) MODE				
Luma Bandwidth		30.0		MHz
Chroma Bandwidth		13.75		MHz

 $^{^{1}}$ Measured on DAC 1, DAC 2, and DAC 3.

POWER SPECIFICATIONS

Table 9.

Parameter	Conditions	Min	Тур	Max	Unit
NORMAL POWER MODE ^{1, 2}					
I_{DD}^{3}	SD (16× oversampling enabled), CVBS		33		mA
	SD (16× oversampling enabled), YPrPb		68		mA
	ED (8× oversampling enabled) ⁴		59		mA
	HD (4× oversampling enabled) ⁴		81		mA
I _{DD_IO}			1		mA
I _{AA} ⁵	1 DAC enabled		50		mA
	All DACs enabled		122		mA
I _{PLL}			4		mA
SLEEP MODE					
I _{DD}			5		μΑ
I _{AA}			0.3		μΑ
I _{DD_IO}			0.2		μΑ
I _{PLL}			0.1		μΑ

² Differential nonlinearity (DNL) measures the deviation of the actual DAC output voltage step from the ideal. For +ve DNL, the actual step value lies above the ideal step value. For –ve DNL, the actual step value lies below the ideal step value.

³ Measured on the ADV7392/ADV7393 operating in 10-bit input mode.

 $^{^1}$ R_{SET} = 510 Ω (all DACs operating in full-drive mode). 2 75% color bar test pattern applied to pixel data pins.

 $^{^3\,\}mbox{I}_{\mbox{\scriptsize DD}}$ is the continuous current required to drive the digital core.

⁴ Applicable to both single data rate (SDR) and dual data rate (DDR) input modes.

⁵ I_{AA} is the total current required to supply all DACs.

TIMING DIAGRAMS

The following abbreviations are used in Figure 2 to Figure 9.

- $t_9 = Clock high time$
- $t_{10} = Clock low time$
- t₁₁ = Data setup time
- t_{12} = Data hold time
- t_{13} = Control output access time
- t_{14} = Control output hold time

In addition, refer to Table 30 for the ADV7390/ADV7391 input configuration and Table 31 for the ADV7392/ADV7393 input configuration.

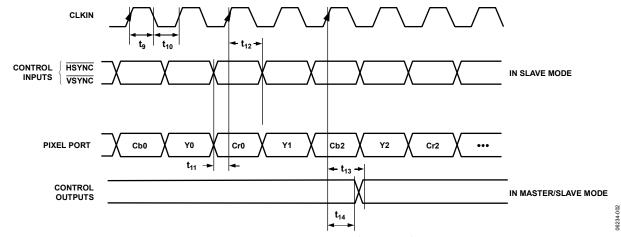


Figure 2. SD Input, 8-/10-Bit 4:2:2 YCrCb (Input Mode 000)

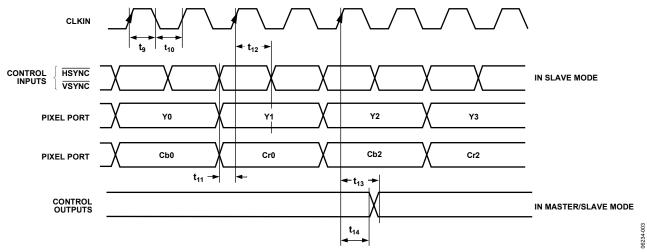


Figure 3. SD Input, 16-Bit 4:2:2 YCrCb (Input Mode 000)

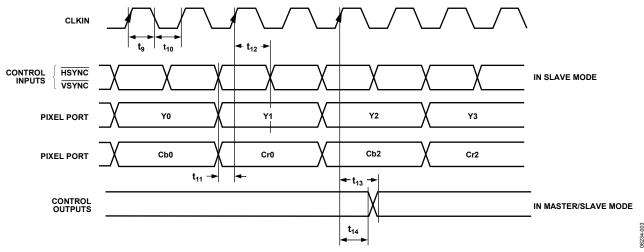


Figure 4. SD Input, 16-Bit 4:4:4 RGB (Input Mode 000)

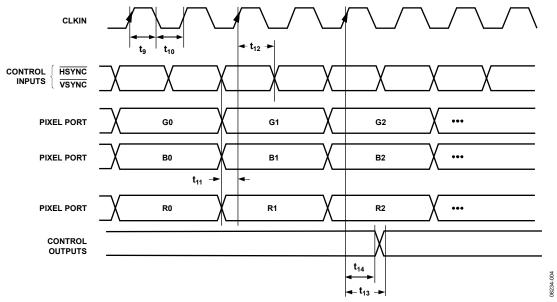
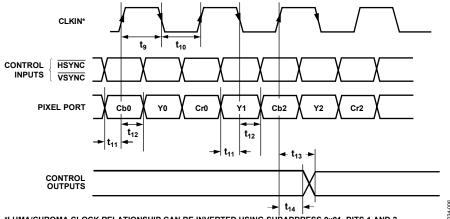


Figure 5. ED/HD-SDR Input, 16-Bit 4:2:2 YCrCb (Input Mode 001)



*LUMA/CHROMA CLOCK RELATIONSHIP CAN BE INVERTED USING SUBADDRESS 0x01, BITS 1 AND 2.

Figure 6. ED/HD-DDR Input, 8-/10-Bit 4:2:2 YCrCb (HSYNC/VSYNC), Input Mode 010

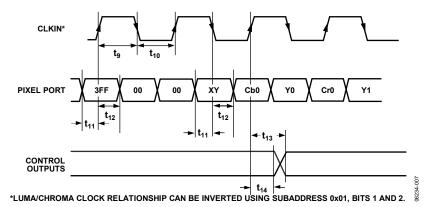


Figure 7. ED/HD-DDR Input, 8-/10-Bit 4:2:2 YCrCb (EAV/SAV), Input Mode 010

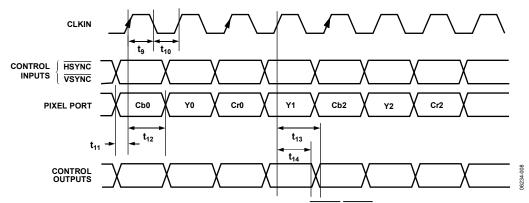


Figure 8. ED (at 54 MHz) Input, 8-/10-Bit 4:2:2 YCrCb (HSYNC/VSYNC), Input Mode 111

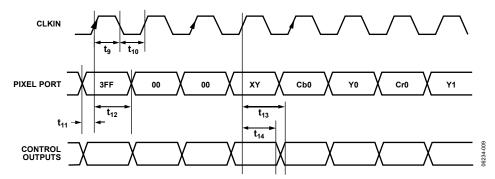
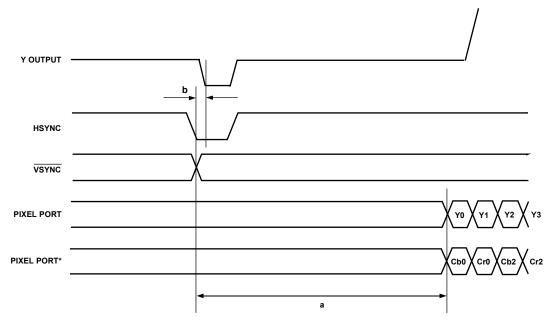


Figure 9. ED (at 54 MHz) Input, 8-/10-Bit 4:2:2 YCrCb (EAV/SAV), Input Mode 111

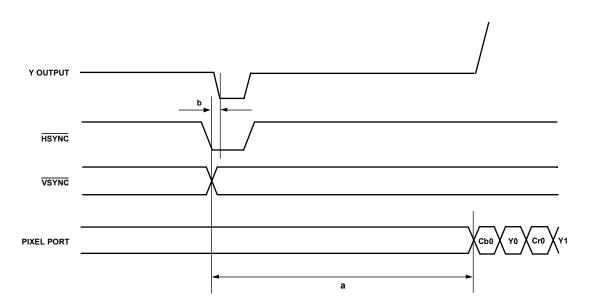


a = AS PER RELEVANT STANDARD.

b = PIPELINE DELAY. PLEASE REFER TO RELEVANT PIPELINE DELAY. THIS CAN BE FOUND IN THE DIGITAL TIMING SPECIFICATION SECTION OF THE DATA SHEET.

A FALLING EDGE OF $\overline{\text{HSYNC}}$ Into the encoder generates a sync falling edge on the output after a time equal to the pipeline delay.

Figure 10. ED-SDR, 16-Bit 4:2:2 YCrCb (HSYNC/VSYNC) Input Timing Diagram



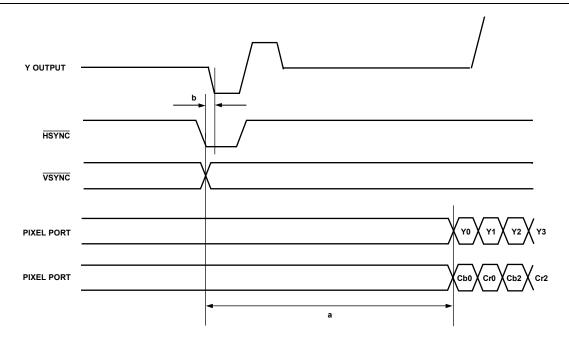
a(MIN) = 244 CLOCK CYCLES FOR 525p. a(MIN) = 264 CLOCK CYCLES FOR 625p.

b = PIPELINE DELAY. PLEASE REFER TO RELEVANT PIPELINE DELAY. THIS CAN BE FOUND IN THE DIGITAL TIMING SPECIFICATION SECTION OF THE DATA SHEET.

A FALLING EDGE OF $\overline{\mbox{HSYNC}}$ INTO THE ENCODER GENERATES A SYNC FALLING EDGE ON THE OUTPUT AFTER A TIME EQUAL TO THE PIPELINE DELAY.

Figure 11. ED-DDR, 8-/10-Bit 4:2:2 YCrCb (HSYNC/VSYNC) Input Timing Diagram

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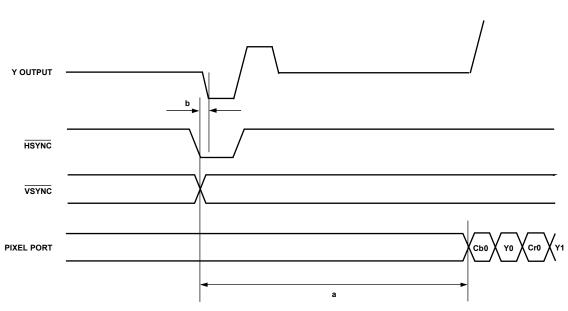


a = AS PER RELEVANT STANDARD.

b = PIPELINE DELAY. PLEASE REFER TO RELEVANT PIPELINE DELAY. THIS CAN BE FOUND IN THE DIGITAL TIMING SPECIFICATION SECTION OF THE DATA SHEET.

A FALLING EDGE OF $\overline{\text{HSYNC}}$ INTO THE ENCODER GENERATES A FALLING EDGE OF TRI-LEVEL SYNC ON THE OUTPUT AFTER A TIME EQUAL TO THE PIPELINE DELAY.

Figure 12. HD-SDR, 16-Bit 4:2:2 YCrCb (HSYNC/VSYNC) Input Timing Diagram



a = AS PER RELEVANT STANDARD.

b = PIPELINE DELAY. PLEASE REFER TO RELEVANT PIPELINE DELAY. THIS CAN BE FOUND IN THE DIGITAL TIMING SPECIFICATION SECTION OF THE DATA SHEET.

A FALLING EDGE OF $\overline{\text{HSYNC}}$ Into the encoder generates a falling edge of tri-level sync on the output after a time equal to the pipeline delay.

Figure 13. HD-DDR, 8-/10-Bit 4:2:2 YCrCb (HSYNC/VSYNC) Input Timing Diagram

3234-012

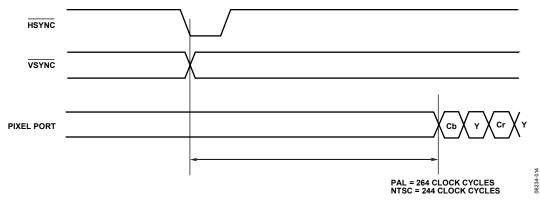


Figure 14. SD Input Timing Diagram (Timing Mode 1)

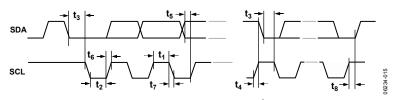


Figure 15. MPU Port Timing Diagram (I²C Mode)

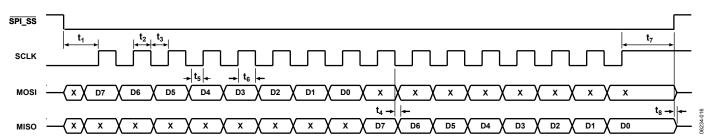


Figure 16. MPU Port Timing Diagram (SPI Mode)

ABSOLUTE MAXIMUM RATINGS

Table 10.

14516 101	
Parameter ¹	Rating
V _{AA} to AGND	-0.3 V to +3.9 V
V _{DD} to DGND	-0.3 V to +2.3 V
PV _{DD} to PGND	-0.3 V to +2.3 V
V_{DD_IO} to GND_IO	-0.3 V to +3.9 V
V_{AA} to V_{DD}	-0.3 V to +2.2 V
V_{DD} to PV_{DD}	-0.3 V to +0.3 V
V_{DD_IO} to V_{DD}	-0.3 V to +2.2 V
AGND to DGND	-0.3 V to +0.3 V
AGND to PGND	-0.3 V to +0.3 V
AGND to GND_IO	-0.3 V to +0.3 V
DGND to PGND	-0.3 V to +0.3 V
DGND to GND_IO	-0.3 V to +0.3 V
PGND to GND_IO	-0.3 V to +0.3 V
Digital Input Voltage to GND_IO	$-0.3 \text{ V to V}_{DD_IO} + 0.3 \text{ V}$
Analog Outputs to AGND	-0.3 V to V _{AA}
Storage Temperature Range (ts)	−60°C to +100°C
Junction Temperature (t _J)	150°C
Lead Temperature (Soldering, 10 sec)	260°C

¹ Analog output short circuit to any power supply or common can be of an indefinite duration.

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

THERMAL RESISTANCE

 θ_{JA} is specified for the worst-case conditions, that is, a device soldered in a circuit board for surface-mount packages.

Table 11. Thermal Resistance¹

Package Type	θ_{JA}^2	θις	Unit
32-Lead LFCP	27	32	°C/W
40-Lead LFCSP	26	32	°C/W

¹ Values are based on a JEDEC 4 layer test board.

The ADV739x is a Pb-free product. The lead finish is 100% pure Sn electroplate. The device is RoHS compliant, suitable for Pb-free applications up to 255°C (±5°C) IR reflow (JEDEC STD-20).

The ADV739x is backward-compatible with conventional SnPb soldering processes. The electroplated Sn coating can be soldered with SnPb solder pastes at conventional reflow temperatures of 220°C to 235°C.

ESD CAUTION



ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

² With the exposed metal paddle on the underside of the LFCSP soldered to the PCB ground.

PIN CONFIGURATIONS AND FUNCTION DESCRIPTIONS

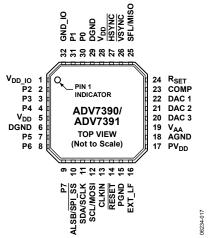


Figure 17. ADV7390/ADV7391 Pin Configuration

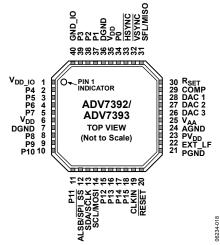


Figure 18. ADV7392/ADV7393 Pin Configuration

Table 12. Pin Function Descriptions

Pin	Number		Input/	
ADV7390/91	ADV7392/93	Mnemonic	Output	Description
9 to 7, 4 to 2, 31, 30		P7 to P0	I	8-Bit Pixel Port (P7 to P0). P0 is the LSB. Refer to Table 30 for input modes (ADV7390/ADV7391).
	18 to 15, 11 to 8, 5 to 2, 39 to 37, 34	P15 to P0	1	16-Bit Pixel Port (P15 to P0). P0 is the LSB. Refer to Table 31 for input modes (ADV7392/ADV7393).
13	19	CLKIN	I	Pixel Clock Input for HD (74.25 MHz), ED ¹ (27 MHz or 54 MHz), or SD (27 MHz).
27	33	HSYNC	I/O	Horizontal Synchronization Signal. This pin can also be configured to output an SD, ED, or HD horizontal synchronization signal. See the External Horizontal and Vertical Synchronization Control section.
26	32	VSYNC	I/O	Vertical Synchronization Signal. This pin can also be configured to output an SD, ED, or HD vertical synchronization signal. See the External Horizontal and Vertical Synchronization Control section.
25	31	SFL/MISO	I/O	Multifunctional Pin: Subcarrier Frequency Lock (SFL) Input/SPI Data Output (MISO). The SFL input is used to drive the color subcarrier DDS system, timing reset, or subcarrier reset.
24	30	Rset	I	Controls the amplitudes of the DAC 1, DAC 2, and DAC 3 outputs. For full-drive operation (for example, into a 37.5 Ω load), a 510 Ω resistor must be connected from R _{SET} to AGND. For low drive operation (for example, into a 300 Ω load), a 4.12 k Ω resistor must be connected from R _{SET} to AGND.
23	29	COMP	0	Compensation Pin. Connect a 2.2 nF capacitor from COMP to VAA.
22, 21, 20	28, 27, 26	DAC 1, DAC 2, DAC 3	0	DAC Outputs. Full-drive and low-drive capable DACs.
12	14	SCL/MOSI	1	Multifunctional Pin: I ² C Clock Input/SPI Data Input.
11	13	SDA/SCLK	I/O	Multifunctional Pin: I ² C Data Input/Output. Also, SPI clock input.
10	12	ALSB/SPI_SS	1	Multifunctional Pin: ALSB sets up the LSB ² of the MPU I ² C address/SPI slave select (SPI_SS).
14	20	RESET	1	Resets the on-chip timing generator and sets the ADV739x into its default mode.
19	25	V _{AA}	Р	Analog Power Supply (3.3 V).
5, 28	6, 35	V _{DD}	Р	Digital Power Supply (1.8 V). For dual-supply configurations, V _{DD} can be connected to other 1.8 V supplies through a ferrite bead or suitable filtering.
1	1	$V_{\text{DD_IO}}$	Р	Input/Output Digital Power Supply (3.3 V).
17	23	PV_{DD}	Р	PLL Power Supply (1.8 V). For dual-supply configurations, PV _{DD} can be connected to other 1.8 V supplies through a ferrite bead or suitable filtering.

Pin	Number		Input/	
ADV7390/91	ADV7392/93	Mnemonic	Output	Description
16	22	EXT_LF	I	External Loop Filter for the Internal PLL.
15	21	PGND	G	PLL Ground Pin.
18	24	AGND	G	Analog Ground Pin.
6, 29	7, 36	DGND	G	Digital Ground Pin.
32	40	GND_IO	G	Input/Output Supply Ground Pin.

 $^{^{1}}$ ED = enhanced definition = 525p and 625p. 2 LSB = least significant bit. In the ADV7390, setting the LSB to 0 sets the 12 C address to 0xD4. Setting it to 1 sets the 12 C address to 0xD6. In the ADV7391, setting the LSB to 0 sets the 12 C address to 0x54. Setting it to 1 sets the 12 C address to 0x56.

TYPICAL PERFORMANCE CHARACTERISTICS

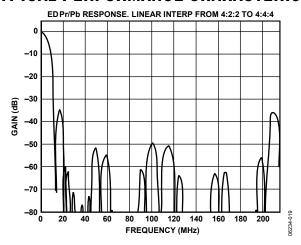


Figure 19. ED 8× Oversampling, PrPb Filter (Linear) Response

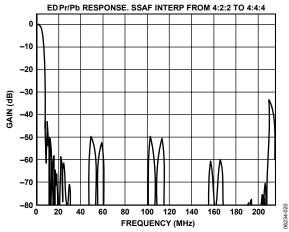


Figure 20. ED 8× Oversampling, PrPb Filter (SSAF) Response

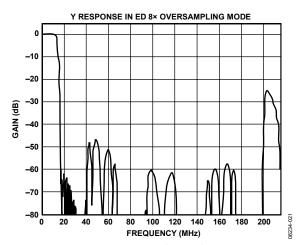


Figure 21. ED $8 \times$ Oversampling, Y Filter Response

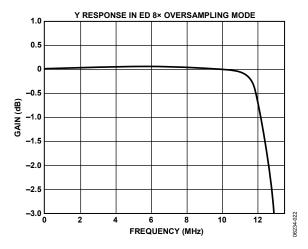


Figure 22. ED 8× Oversampling, Y Filter Response (Focus on Pass Band)

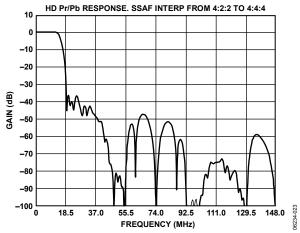


Figure 23. HD 4× Oversampling, PrPb (SSAF) Filter Response (4:2:2 Input)

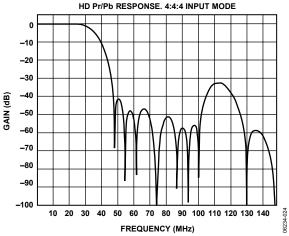


Figure 24. HD 4× Oversampling, PrPb (SSAF) Filter Response (4:4:4 Input)

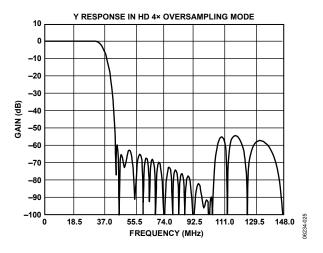


Figure 25. HD 4× Oversampling, Y Filter Response

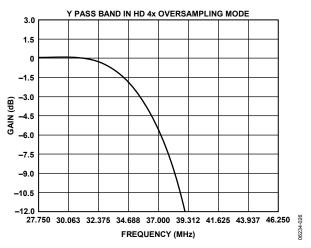


Figure 26. HD 4× Oversampling, Y Filter Response (Focus on Pass Band)

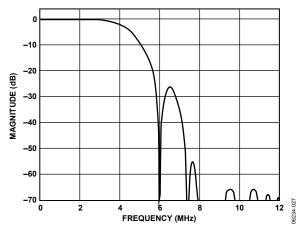


Figure 27. SD NTSC, Luma Low-Pass Filter Response

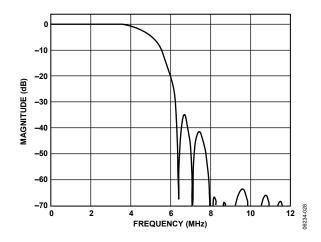


Figure 28. SD PAL, Luma Low-Pass Filter Response

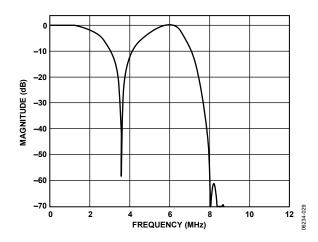


Figure 29. SD NTSC, Luma Notch Filter Response

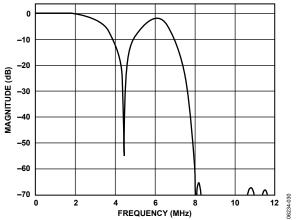


Figure 30. SD PAL, Luma Notch Filter Response

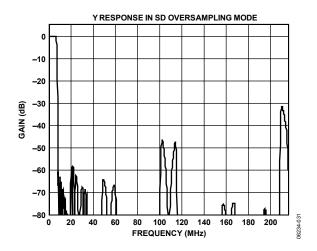


Figure 31. SD 16× Oversampling, Y Filter Response

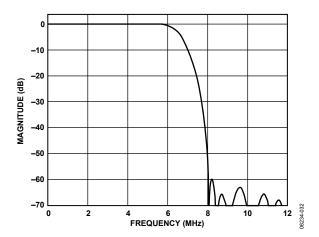


Figure 32. SD Luma SSAF Filter Response up to 12 MHz

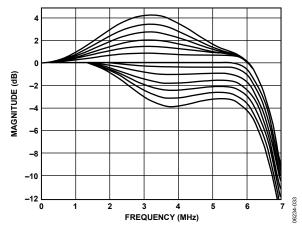


Figure 33. SD Luma SSAF Filter, Programmable Responses

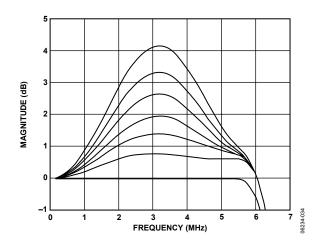


Figure 34. SD Luma SSAF Filter, Programmable Gain

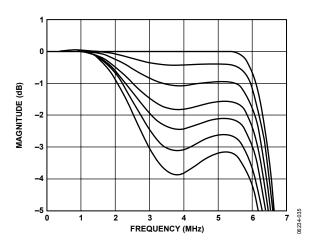


Figure 35. SD Luma SSAF Filter, Programmable Attenuation

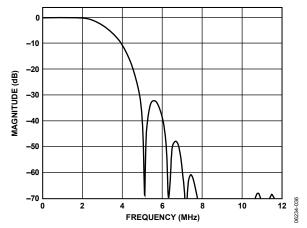


Figure 36. SD Luma CIF Low-Pass Filter Response

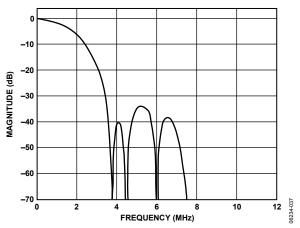


Figure 37. SD Luma QCIF Low-Pass Filter Response

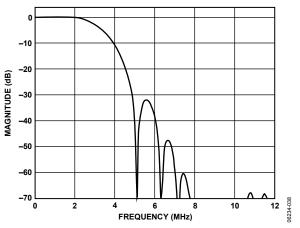


Figure 38. SD Chroma 3.0 MHz Low-Pass Filter Response

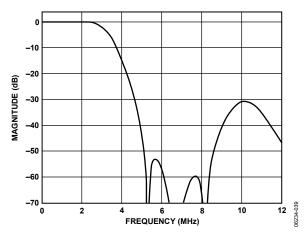


Figure 39. SD Chroma 2.0 MHz Low-Pass Filter Response

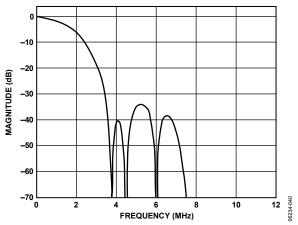


Figure 40. SD Chroma 1.3 MHz Low-Pass Filter Response

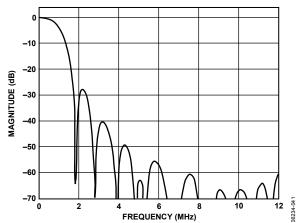


Figure 41. SD Chroma 1.0 MHz Low-Pass Filter Response

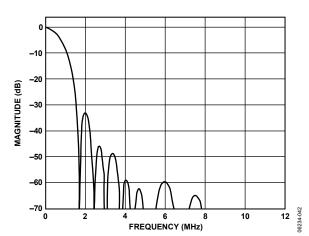


Figure 42. SD Chroma 0.65 MHz Low-Pass Filter Response

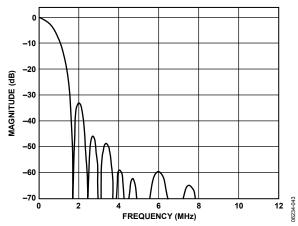


Figure 43. SD Chroma CIF Low-Pass Filter Response

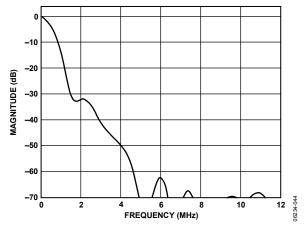


Figure 44. SD Chroma QCIF Low-Pass Filter Response

MPU PORT DESCRIPTION

Devices such as a microprocessor can communicate with the ADV739x through one of the following protocols:

- 2-wire serial (I²C-compatible) bus
- 4-wire serial (SPI-compatible) bus

After power-up or reset, the MPU port is configured for I²C operation. SPI operation can be invoked at any time by following the procedure outlined in the SPI Operation section.

I²C OPERATION

The ADV739x supports a 2-wire serial (I²C-compatible) microprocessor bus driving multiple peripherals. This port operates in an open-drain configuration. Two inputs, serial data (SDA) and serial clock (SCL), carry information between any device connected to the bus and the ADV739x. Each slave device is recognized by a unique address. The ADV739x has four possible slave addresses for both read and write operations. These are unique addresses for each device and are illustrated in Figure 45 and Figure 46. The LSB either sets a read or write operation. Logic 1 corresponds to a read operation, while Logic 0 corresponds to a write operation. A1 is controlled by setting the ALSB/SPI_SS pin of the ADV739x to Logic 0 or Logic 1.

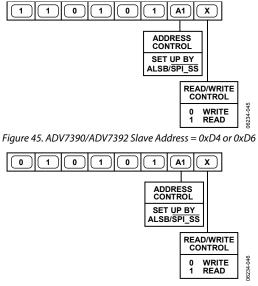


Figure 46. ADV7391/ADV7393 Slave Address = 0x54 or 0x56

To control the various devices on the bus, use the following protocol. The master initiates a data transfer by establishing a start condition, defined by a high-to-low transition on SDA while SCL remains high. This indicates that an address/data stream follows. All peripherals respond to the start condition and shift the next eight bits (7-bit address + R/\overline{W} bit).

The bits are transferred from MSB down to LSB. The peripheral that recognizes the transmitted address responds by pulling the data line low during the ninth clock pulse. This is known as an acknowledge bit. All other devices withdraw from the bus at this point and maintain an idle condition. The idle condition is when the device monitors the SDA and SCL lines waiting for the start condition and the correct transmitted address. The R/\overline{W} bit determines the direction of the data.

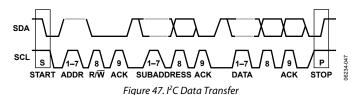
Logic 0 on the LSB of the first byte means that the master writes information to the peripheral. Logic 1 on the LSB of the first byte means that the master reads information from the peripheral.

The ADV739x acts as a standard slave device on the bus. The data on the SDA pin is eight bits long, supporting the 7-bit addresses plus the R/\overline{W} bit. It interprets the first byte as the device address and the second byte as the starting subaddress. There is a subaddress auto-increment facility. This allows data to be written to or read from registers in ascending subaddress sequence starting at any valid subaddress. A data transfer is always terminated by a stop condition. The user can also access any unique subaddress register on a one-by-one basis without updating all the registers.

Stop and start conditions can be detected at any stage during the data transfer. If these conditions are asserted out of sequence with normal read and write operations, they cause an immediate jump to the idle condition. During a given SCL high period, the user should only issue a start condition, a stop condition, or a stop condition followed by a start condition. If an invalid subaddress is issued by the user, the ADV739x does not issue an acknowledge and does return to the idle condition. If the user utilizes the auto-increment method of addressing the encoder and exceeds the highest subaddress, the following actions are taken:

- In read mode, the highest subaddress register contents are output until the master device issues a no acknowledge.
 This indicates the end of a read. A no acknowledge condition occurs when the SDA line is not pulled low on the ninth pulse.
- In write mode, the data for the invalid byte is not loaded into any subaddress register, a no acknowledge is issued by the ADV739x, and the part returns to the idle condition.

Figure 47 shows an example of data transfer for a write sequence and the start and stop conditions. Figure 48 shows bus write and read sequences.



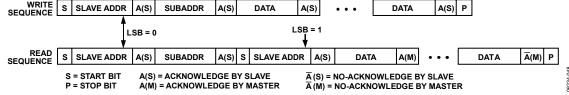


Figure 48. I²C Read and Write Sequence

SPI OPERATION

The ADV739x supports a 4-wire serial (SPI-compatible) bus connecting multiple peripherals. Two inputs, master out slave in (MOSI) and serial clock (SCLK), and one output, master in slave out (MISO), carry information between a master SPI peripheral on the bus and the ADV739x. Each slave device on the bus has a slave select pin that is connected to the master SPI peripheral by a unique slave select line. As such, slave device addressing is not required.

To invoke SPI operation, a master SPI peripheral (for example, a microprocessor) should issue three low pulses on the ADV739x ALSB/SPI_SS pin. When the encoder detects the third rising edge on the ALSB/SPI_SS pin, it automatically switches to SPI communication mode. The ADV739x remains in SPI communication mode until a hardware reset or power-down occurs.

To control the ADV739x, use the following protocol for both read and write transactions. First, the master initiates a data transfer by driving and holding the ADV739x ALSB/SPI_SS pin low. On the first SCLK rising edge after ALSB/SPI_SS has been driven low, the write command, defined as 0xD4, is written to the ADV739x over the MOSI line. The second byte written to the MOSI line is interpreted as the starting subaddress. Data on the MOSI line is written MSB first and clocked on the rising edge of SCLK.

There is a subaddress auto-increment facility. This allows data to be written to or read from registers in ascending subaddress sequence starting at any valid subaddress. The user can also access any unique subaddress register on a one-by-one basis.

In a write data transfer, 8-bit data bytes are written to the ADV739x, MSB first, on the MOSI line immediately after the starting subaddress. The data bytes are clocked into the ADV739x on the rising edge of SCLK. When all data bytes have been written, the master completes the transfer by driving and holding the ADV739x ALSB/SPI_SS pin high.

In a read data transfer, after the subaddress has been clocked in on the MOSI line, the ALSB/SPI_SS pin is driven and held high for at least one clock cycle. Then, the ALSB/SPI_SS pin is driven and held low again. On the first SCLK rising edge after ALSB/SPI_SS has been driven low, the read command, defined as 0xD5, is written, MSB first, to the ADV739x over the MOSI line. Subsequently, 8-bit data bytes are read from the ADV739x, MSB first, on the MISO line. The data bytes are clocked out of the part on the falling edge of SCLK. When all data bytes have been read, the master completes the transfer by driving and holding the ADV739x ALSB/SPI_SS pin high.

REGISTER MAP

A microprocessor can read from or write to all registers of the ADV739x via the MPU port, except for registers that are specified as read-only or write-only registers.

The subaddress register determines the register accessed by the next read or write operation. All communication through the MPU port starts with an access to the subaddress register. A read/write operation is then performed from/to the target address, incrementing to the next address until the transaction is complete.

REGISTER PROGRAMMING

Table 13 to Table 27 describe the functionality of each register. All registers can be read from as well as written to, unless otherwise stated.

SUBADDRESS REGISTER (SR7 TO SR0)

The subaddress register is an 8-bit write-only register. After the MPU port is accessed and a read/write operation is selected, the subaddress is set up. The subaddress register determines which register performs the next operation.

Table 13. Register 0x00

SR7 to					В	it N	umb	er			Register	Reset
SR0	Register	Bit Description	7	6	5	4	3	2	1	0	Setting	Value
0x00	Power Mode Register	Sleep Mode. With this control enabled, the current consumption is reduced to μA level. All DACs and the internal PLL circuit are disabled. Registers can be read from and written to in sleep mode.								0	Sleep mode off. Sleep mode on.	0x12
		PLL and Oversampling Control. This control allows the internal PLL circuit to be powered down and the oversampling to be switched off.							0 1		PLL on. PLL off.	
		DAC 3: Power on/off.						0			DAC 3 off. DAC 3 on.	
		DAC 2: Power on/off.					0				DAC 2 off. DAC 2 on.	
		DAC 1: Power on/off.				0					DAC 1 off. DAC 1 on.	
		Reserved.	0	0	0							

Table 14. Register 0x01 to Register 0x09

SR7 to					В	it N	umb	er				Reset
SRO	Register	Bit Description	7	6	5	4	3	2	1	0	Register Setting	Value
0x01	Mode Select	Reserved.								0		0x00
	Register	DDR Clock Edge Alignment. Note: Only used for ED ¹ and						0	0		Chroma clocked in on rising clock edge and luma clocked in on falling clock edge.	
		HD DDR modes.						0	1		Reserved.	
								1	0		Reserved.	
								1	1		Luma clocked in on rising clock edge and chroma clocked in on falling clock edge.	
		Reserved.					0					
		Input Mode.		0	0	0					SD input.	
		Note: See Reg. 0x30, Bits[7:3]		0	0	1					ED/HD-SDR input ²	
		for ED/HD format selection.		0	1	0					ED/HD-DDR input.	
				0	1	1					Reserved.	
				1	0	0					Reserved.	
				1	0	1					Reserved.	
				1	1	0					Reserved.	
				1	1	1					ED (at 54 MHz) input.	
		Reserved.	0									1
0x02	Mode	Reserved.	Ť						0	0	Zero must be written to these bits.	0x20
ONOL	Register 0	Test Pattern Black Bar. ³						0	Ŭ	<u> </u>	Disabled.	OXEO
		restractem black bar.						1			Enabled.	
		Manual RGB Matrix Adjust.			ļ		0	<u> </u>			Disable manual RGB matrix adjust.	+
		Mariual KGB Matrix Aujust.					1				Enable manual RGB matrix adjust.	
		C DCD					-				·	
		Sync on RGB.				0					No sync.	
						1					Sync on all RGB outputs.	
		RGB/YPrPb Output Select.			0						RGB component outputs.	
					1						YPrPb component outputs.	
		SD Sync Output Enable.		0							No sync output.	
				1							Output SD syncs on HSYNC and VSYNC pins.	
		ED/HD Sync Output Enable.	0								No sync output.	
			1								Output ED/HD syncs on HSYNC and VSYNC	
											pins.	
0x03	ED/HD CSC Matrix 0								х	х	LSBs for GY.	0x03
0x04	ED/HD CSC								Х	х	LSBs for RV.	0xF0
	Matrix 1						х	х			LSBs for BU.	
					х	х					LSBs for GV.	
			х	х							LSBs for GU.	
0x05	ED/HD CSC Matrix 2		х	х	Х	х	х	х	х	х	Bits[9:2] for GY.	0x4E
0x06	ED/HD CSC Matrix 3		х	х	х	х	х	х	х	х	Bits[9:2] for GU.	0x0E
0x07	ED/HD CSC Matrix 4		х	х	х	х	х	х	х	х	Bits[9:2] for GV.	0x24
0x08	ED/HD CSC Matrix 5		х	х	х	х	х	х	х	х	Bits[9:2] for BU.	0x92
0x09	ED/HD CSC Matrix 6		х	х	х	х	х	х	х	х	Bits[9:2] for RV.	0x7C

 ¹ ED = enhanced definition = 525p and 625p.
 ² Available on the ADV7392/ADV7393 (40-pin devices) only.
 ³ Subaddress 0x31, Bit 2 must also be enabled (ED/HD). Subaddress 0x84, Bit 6 must also be enabled (SD).

Table 15. Register 0x0B to Register 0x17

SR7 to						Bit Nu	ımbe	r				Reset
SR0	Register	Bit Description	7	6	5	4	3	2	1	0	Register Setting	Value
0x0B	DAC 1, DAC 2,	Positive Gain to DAC Output Voltage.	0	0	0	0	0	0	0	0	0%	0x00
	DAC 3 Output		0	0	0	0	0	0	0	1	+0.018%	
	Level		0	0	0	0	0	0	1	0	+0.036%	
			0	0	1	1	1	1	1	1	+7.382%	
			0	1	0	0	0	0	0	0	+7.5%	
		Negative Gain to DAC Output	1	1	0	0	0	0	0	0	-7.5%	
		Voltage.	1	1	0	0	0	0	0	1	-7.382%	
			1	0	0	0	0	0	1	0	-7.364%	
										1		
0.00	DACD	DACILLO DO CAMALO	1	1	1	1	1	1	1	1	-0.018%	0.00
0x0D	DAC Power Mode	DAC 1 Low Power Mode.								0	DAC 1 low power disabled	0x00
	Wode	DAC 2 Low Power Mode.							0	1	DAC 1 low power enabled DAC 2 low power disabled	1
		DAC 2 Low Power Mode.							1		DAC 2 low power disabled DAC 2 low power enabled	
		DAC 3 Low Power Mode.						0	 ' -		DAC 3 low power disabled	<u> </u>
		DAC 3 Low Power Mode.						1			DAC 3 low power enabled	
		SD/ED Oversample Rate Select.					0	<u>'</u>			SD = 16×, ED = 8×	
		30/LD Oversample nate select.					1				$SD = 8\times$, $ED = 8\times$	
		Reserved.	0	0	0	0	'				3D - 0X, LD - 1X	1
0x10	Cable Detection	DAC 1 Cable Detect.	<u> </u>	-	<u> </u>	<u> </u>				0	Cable detected on DAC 1	0x00
0,7.10		Read Only.								1	DAC 1 unconnected	o, co
		DAC 2 Cable Detect.							0		Cable detected on DAC 2	1
		Read Only.							1		DAC 2 unconnected	
		Reserved.					0	0				1
		Unconnected DAC auto power-down.				0					DAC auto power-down disable	
						1					DAC auto power-down enable	
		Reserved.	0	0	0							
0x13	Pixel Port	P[7:0] Readback (ADV7390/ADV7391).	Х	х	х	х	х	Х	Х	х	Read only	0xXX
	Readback A ¹	P[15:8] Readback (ADV7392/ADV7393).										
0x14	Pixel Port Readback B ¹	P[7:0] Readback (ADV7392/ADV7393).	х	х	х	х	х	х	х	х	Read only	0xXX
0x16	Control Port	Reserved.						х	х	х	Read only	0xXX
	Readback ¹	VSYNC Readback.					х					
		HSYNC Readback.				х						
		SFL/MISO Readback.			х							
		Reserved.	х	х								
0x17	Software Reset	Reserved.	<u> </u>	<u> </u>						0		0x00
		Software Reset.		1					0	Ť	Writing a 1 resets the	
									1		device; this is a self- clearing bit	
		Reserved.	0	0	0	0	0	0				l

¹ For correct operation, Subaddress 0x01[6:4] must equal the default value of 000.

Table 16. Register 0x30

SR7 to					В	it Nu	ımb	er					Reset
SR0	Register	Bit Description	7	6	5	4	3	2	1	0	Register Setting	Note	Value
0x30	ED/HD Mode Register 1	ED/HD Output Standard.							0	0	EIA-770.2 output EIA-770.3 output	ED HD	0x00
									0	1	EIA-770.1 output		
									1	0	Output levels for full		
											input range		
									1	1	Reserved		
		ED/HD Input						0			External HSYNC, VSYNC		
		Synchronization Format.									and field inputs ¹		
								1			Embedded EAV/SAV codes		
		ED/HD Input Mode.	0	0	0	0	0				SMPTE 293M, ITU-BT.1358	525p @ 59.94 Hz	
			0	0	0	0	1				Nonstandard timing mode		
			0	0	0	1	0				BTA-1004, ITU-BT.1362	525p @ 59.94 Hz	
			0	0	0	1	1				ITU-BT.1358	625p @ 50 Hz	
			0	0	1	0	0				ITU-BT.1362	625p @ 50 Hz	
			0	0	1	0	1				SMPTE 296M-1, SMPTE 274M-2	720p @ 60 Hz/59.94 Hz	
			0	0	1	1	0				SMPTE 296M-3	720p @ 50 Hz	
			0	0	1	1	1				SMPTE 296M-4,	720p @	
				_		_					SMPTE 274M-5	30 Hz/29.97 Hz	
			0	1	0	0	0				SMPTE 296M-6	720p @ 25 Hz	
			0	1	0	0	1				SMPTE 296M-7, SMPTE 296M-8	720p @ 24 Hz/23.98 Hz	
			0	1	0	1	0				SMPTE 240M	1035i @ 60 Hz/59.94 Hz	
			0	1	0	1	1				Reserved		
			0	1	1	0	0				Reserved		
			0	1	1	0	1				SMPTE 274M-4, SMPTE 274M-5	1080i @ 30 Hz/29.97 Hz	
			0	1	1	1	0				SMPTE 274M-6	1080i @ 25 Hz	
			0	1	1	1	1				SMPTE 274M-7, SMPTE 274M-8	1080p @ 30 Hz/29.97 Hz	
			1	0	0	0	0				SMPTE 274M-9	1080p @ 25 Hz	
			1	0	0	0	1				SMPTE 274M-10, SMPTE 274M-11	1080p @ 24 Hz/23.98 Hz	
			1	0	0	1	0				ITU-R BT.709-5	1080Psf @ 24 Hz	
			1	001	1 to	1111	1				Reserved		

 $^{^{1}}$ Synchronization can be controlled with a combination of either $\overline{\text{HSYNC}}$ and $\overline{\text{VSYNC}}$ inputs or $\overline{\text{HSYNC}}$ and field inputs, depending on Subaddress 0x34, Bit 6.

Table 17. Register 0x31 to Register 0x33

SR7 to					В	it Nu	ımb	er				Reset
SR0	Register	Bit Description	7	6	5	4	3	2	1	0	Register Setting	Value
0x31	ED/HD Mode	ED/HD Pixel Data Valid.								0	Pixel data valid off	0x00
	Register 2									1	Pixel data valid on	
		HD Oversample Rate Select.							0		4×	
									1		2×	
		ED/HD Test Pattern Enable.						0			HD test pattern off	
								1			HD test pattern on	
		ED/HD Test Pattern Hatch/Field.					0				Hatch	
							1				Field/frame	
		ED/HD Vertical Blanking Interval (VBI)				0					Disabled	
		Open.				1					Enabled	
		ED/HD Undershoot Limiter.		0	0						Disabled	
				0	1						-11 IRE	
				1	0						−6 IRE	
				1	1						−1.5 IRE	
		ED/HD Sharpness Filter.	0								Disabled	
			1								Enabled	
0x32	ED/HD Mode	ED/HD Y Delay with Respect to Falling						0	0	0	0 clock cycles	0x00
	Register 3	Edge of HSYNC.						0	0	1	1 clock cycle	
								0	1	0	2 clock cycles	
								0	1	1	3 clock cycles	
								1	0	0	4 clock cycles	
		ED/HD Color Delay with Respect to			0	0	0				0 clock cycles	
		Falling Edge of HSYNC.			0	0	1				1 clock cycle	
					0	1	0				2 clock cycles	
					0	1	1				3 clock cycles	
					1	0	0				4 clock cycles	
		ED/HD CGMS Enable.		0							Disabled	
				1							Enabled	
		ED/HD CGMS CRC Enable.	0								Disabled	
			1								Enabled	
0x33	ED/HD Mode	ED/HD Cr/Cb Sequence.								0	Cb after falling edge of HSYNC	0x68
	Register 4									1	Cr after falling edge of HSYNC	
		Reserved.							0		0 must be written to this bit	
		ED/HD Input Format.						0			8-bit input	
								1			10-bit input ¹	
		Sinc Compensation Filter on DAC 1,					0				Disabled	
		DAC 2, DAC 3.		<u> </u>			1	ļ		<u> </u>	Enabled	1
		Reserved.	1	<u> </u>		0		<u> </u>			0 must be written to this bit	1
		ED/HD Chroma SSAF Filter.			0						Disabled	
			1	<u> </u>	1			<u> </u>			Enabled	1
		Reserved.		1				ļ		<u> </u>	1 must be written to this bit	1
		ED/HD Double Buffering.	0								Disable	
			1					1		1	Enabled	

 $^{^{\}rm 1}$ Available on the ADV7392/ADV7393 (40-pin devices) only.

Table 18. Register 0x34 to Register 0x38

SR7 to					В	it N	umb	er				Reset
SR0	Register	Bit Description	7	6	5	4	3	2	1	0	Register Setting	Value
0x34	ED/HD Mode	ED/HD Timing Reset.								0	Internal ED/HD timing counters enabled	0x48
	Register 5									1	Resets the internal ED/HD timing counters	
		ED/HD HSYNC Control. ¹							0		HSYNC output control (refer to Table 50)	
		ED/HD VSYNC Control. ¹						0			VSYNC output control (refer to Table 51)	
		Reserved.					1					
		ED Macrovision Enable. ²				0					ED Macrovision disabled	
						1					ED Macrovision enabled	
		Reserved.			0						0 must be written to this bit	
		ED/HD VSYNC Input/Field		0							0 = Field input	
		Input.		1							$1 = \overline{\text{VSYNC}}$ input	
		ED/HD Horizontal/Vertical	0								Update field/line counter	
		Counter Mode. ³	1								Field/line counter free running	
0x35	ED/HD Mode	Reserved.								0		0x00
	Register 6	Reserved.							0			
		ED/HD Sync on PrPb.						0			Disabled	
								1			Enabled	
		ED/HD Color DAC Swap.					0				DAC 2 = Pb, DAC 3 = Pr	
							1				DAC 2 = Pr, DAC 3 = Pb	
		ED/HD Gamma Correction				0					Gamma Correction Curve A	
		Curve Select.				1					Gamma Correction Curve B	
		ED/HD Gamma			0						Disabled	
		Correction Enable.			1						Enabled	
		ED/HD Adaptive Filter Mode.		0							Mode A	
			<u> </u>	1							Mode B	
		ED/HD Adaptive Filter Enable.	0								Disabled	
0.26	ED/HD Y Level ⁴		1	L.,	L.	 	 	L.,	<u> </u>	 	Enabled Y level value	0,400
0x36 0x37	ED/HD Y Level ⁴	ED/HD Test Pattern Y Level. ED/HD Test Pattern Cr Level.	X	X	X	X	X	X	X	X	Cr level value	0xA0 0x80
			X	X	X	X	X	X	X	Х		
0x38	ED/HD Cb Level ⁴	ED/HD Test Pattern Cb Level.	Χ	Х	Х	Х	Х	Χ	Χ	Х	Cb level value	0x80

 $^{^1}$ Used in conjunction with ED/HD sync output enable in Subaddress 0x02, Bit 7 = 1. 2 Applies to the ADV7390 and ADV7392 only.

³ When set to 0, the horizontal/vertical counters automatically wrap around at the end of the line/field/frame of the selected standard. When set to 1, the horizontal/vertical counters are free running and wrap around when external sync signals indicate to do so.

⁴ For use with ED/HD internal test patterns only (Subaddress 0x31, Bit 2 = 1).

Table 19. Register 0x39 to Register 0x43

SR7 to						Bit Nu	ımber					Reset
SR0	Register	Bit Description	7	6	5	4	3	2	1	0	Register Setting	Value
0x39	ED/HD Mode	Reserved.				0	0	0	0	0		0x00
	Register 7	ED/HD EIA/CEA-861B			0						Disabled	
		Synchronization Compliance.			1						Enabled	
		Reserved.	0	0								
0x40	ED/HD Sharpness	ED/HD Sharpness Filter Gain					0	0	0	0	Gain A = 0	0x00
	Filter Gain	Value A.					0	0	0	1	Gain $A = +1$	
							0	1	1	1	Gain A = +7	
							1	0	0	0	Gain A = −8	
							1	1	1	1	Gain A = −1	
		ED/HD Sharpness Filter Gain	0	0	0	0					Gain B = 0	
		Value B.	0	0	0	1					Gain B = +1	
			0	1	1	1					Gain $B = +7$	
			1	0	0	0					Gain B = −8	
			1	1	1	1					Gain B = −1	
0x41	ED/HD CGMS Data 0	ED/HD CGMS Data Bits.	0	0	0	0	C19	C18	C17	C16	CGMS C19 to C16	0x00
0x42	ED/HD CGMS Data 1	ED/HD CGMS Data Bits.	C15	C14	C13	C12	C11	C10	C9	C8	CGMS C15 to C8	0x00
0x43	ED/HD CGMS Data 2	ED/HD CGMS Data Bits.	C7	C6	C5	C4	C3	C2	C1	C0	CGMS C7 to C0	0x00

Table 20. Register 0x44 to Register 0x57

SR7 to					ı	Bit Nu	ımbe	r			Register	Reset
SR0	Register	Bit Description	7	6	5	4	3	2	1	0	Setting	Value
0x44	ED/HD Gamma A0	ED/HD Gamma Curve A (Point 24).	Х	х	х	Х	Х	Х	Х	Х	A0	0x00
0x45	ED/HD Gamma A1	ED/HD Gamma Curve A (Point 32).	Х	х	х	х	х	х	х	х	A1	0x00
0x46	ED/HD Gamma A2	ED/HD Gamma Curve A (Point 48).	Х	х	х	х	х	х	х	х	A2	0x00
0x47	ED/HD Gamma A3	ED/HD Gamma Curve A (Point 64).	Х	х	х	Х	Х	Х	Х	Х	A3	0x00
0x48	ED/HD Gamma A4	ED/HD Gamma Curve A (Point 80).	Х	х	х	х	х	х	х	х	A4	0x00
0x49	ED/HD Gamma A5	ED/HD Gamma Curve A (Point 96).	Х	х	х	х	х	х	х	х	A5	0x00
0x4A	ED/HD Gamma A6	ED/HD Gamma Curve A (Point 128).	Х	х	х	Х	х	Х	Х	Х	A6	0x00
0x4B	ED/HD Gamma A7	ED/HD Gamma Curve A (Point 160).	Х	х	х	Х	х	Х	Х	Х	A7	0x00
0x4C	ED/HD Gamma A8	ED/HD Gamma Curve A (Point 192).	Х	х	х	х	х	х	х	х	A8	0x00
0x4D	ED/HD Gamma A9	ED/HD Gamma Curve A (Point 224).	х	х	х	х	х	х	х	х	A9	0x00
0x4E	ED/HD Gamma B0	ED/HD Gamma Curve B (Point 24).	Х	х	х	Х	Х	Х	Х	Х	B0	0x00
0x4F	ED/HD Gamma B1	ED/HD Gamma Curve B (Point 32).	Х	х	х	Х	Х	Х	Х	Х	B1	0x00
0x50	ED/HD Gamma B2	ED/HD Gamma Curve B (Point 48).	Х	х	х	х	х	х	х	х	B2	0x00
0x51	ED/HD Gamma B3	ED/HD Gamma Curve B (Point 64).	Х	х	х	Х	х	Х	Х	Х	B3	0x00
0x52	ED/HD Gamma B4	ED/HD Gamma Curve B (Point 80).	Х	х	х	Х	х	Х	Х	Х	B4	0x00
0x53	ED/HD Gamma B5	ED/HD Gamma Curve B (Point 96).	Х	х	х	Х	х	Х	Х	Х	B5	0x00
0x54	ED/HD Gamma B6	ED/HD Gamma Curve B (Point 128).	Х	х	х	Х	х	Х	Х	Х	B6	0x00
0x55	ED/HD Gamma B7	ED/HD Gamma Curve B (Point 160).	х	х	х	х	х	х	х	х	B7	0x00
0x56	ED/HD Gamma B8	ED/HD Gamma Curve B (Point 192).	Х	х	х	х	х	х	х	х	B8	0x00
0x57	ED/HD Gamma B9	ED/HD Gamma Curve B (Point 224).	х	х	х	х	х	х	х	х	B9	0x00

Table 21. Register 0x58 to Register 0x5D

SR7 to						Bit N	umbe	r			Register	Reset
SR0	Register	Bit Description	7	6	5	4	3	2	1	0	Setting	Value
0x58	ED/HD Adaptive Filter Gain 1	ED/HD Adaptive Filter Gain 1,					0	0	0	0	Gain A = 0	0x00
		Value A.					0	0	0	1	Gain $A = +1$	
							0	1	1	1	Gain $A = +7$	
							1	0	0	0	Gain $A = -8$	
							•••	•••	•••	•••		
			_				1	1	1	1	Gain $A = -1$	1
		ED/HD Adaptive Filter Gain 1, Value B.	0	0	0	0					Gain B = 0	
		value b.	0	0	0	1					Gain $B = +1$	
				1	1	1					 Caim D	
			0	1	1	1					Gain $B = +7$ Gain $B = -8$	
			1	0	0	0						
			1	1	1	1					 Gain B = -1	
OvEO	ED/HD Adaptive Filter Cain 2	ED/HD Adaptive Filter Cain 3	+	'	'	'	0	0	0	0	Gain $A = 0$	0,00
0x59	ED/HD Adaptive Filter Gain 2	ED/HD Adaptive Filter Gain 2, Value A.					0	0			Gain A = 0 Gain A = +1	0x00
		value / ii							0	1	Gain A = +1	
							0	1	1	1	 Gain A = +7	
							1	0	1 0	0	Gain $A = +7$ Gain $A = -8$	
							1	1	1	1	 Gain A = -1	
		ED/HD Adaptive Filter Gain 2,	0	0	0	0	<u>'</u>	<u>'</u>	<u> </u>	'	Gain B = 0	1
		Value B.	0	0	0	1					Gain B = +1	
											Gairr b = +1	
			0	1	1	1					Gain B = +7	
			1	0	0	0					Gain B = -8	
			ļ									
			1	1	1	1					Gain $B = -1$	
0x5A	ED/HD Adaptive Filter Gain 3	ED/HD Adaptive Filter Gain 3,					0	0	0	0	Gain A = 0	0x00
	·	Value A.					0	0	0	1	Gain $A = +1$	
							0	1	1	1	Gain $A = +7$	
							1	0	0	0	Gain $A = -8$	
							1	1	1	1	Gain $A = -1$	
		ED/HD Adaptive Filter Gain 3,	0	0	0	0					Gain B = 0	
		Value B.	0	0	0	1					Gain $B = +1$	
			0	1	1	1					Gain $B = +7$	
			1	0	0	0					Gain B = -8	
					•••							
			1	1	1	1					Gain $B = -1$	
0x5B	ED/HD Adaptive Filter Threshold A	ED/HD Adaptive Filter Threshold A.	х	х	Х	х	Х	Х	Х	х	Threshold A	0x00
0x5C	ED/HD Adaptive Filter Threshold B	ED/HD Adaptive Filter Threshold B.	х	х	х	х	х	х	Х	Х	Threshold B	0x00
0x5D	ED/HD Adaptive Filter Threshold C	ED/HD Adaptive Filter Threshold C.	х	х	Х	х	х	Х	Х	х	Threshold C	0x00

Table 22. Register 0x5E to Register 0x6E

SR7 to						Bit Nu	ımber				Register	Reset Value
SR0	Register	Bit Description	Sit Description 7	6	5	4	3	2	1	0	Setting	
0x5E	ED/HD CGMS Type B	ED/HD CGMS Type B								0	Disabled	0x00
	Register 0	Enable.								1	Enabled	
		ED/HD CGMS Type B							0		Disabled	
		CRC Enable.							1		Enabled]
		ED/HD CGMS Type B Header Bits.	H5	H4	H3	H2	H1	H0			H5 to H0	
0x5F	ED/HD CGMS Type B Register 1	ED/HD CGMS Type B Data Bits.	P7	P6	P5	P4	Р3	P2	P1	P0	P7 to P0	0x00
0x60	ED/HD CGMS Type B Register 2	ED/HD CGMS Type B Data Bits.	P15	P14	P13	P12	P11	P10	P9	P8	P15 to P8	0x00
0x61	ED/HD CGMS Type B Register 3	ED/HD CGMS Type B Data Bits.	P23	P22	P21	P20	P19	P18	P17	P16	P23 to P16	0x00
0x62	ED/HD CGMS Type B Register 4	ED/HD CGMS Type B Data Bits.	P31	P30	P29	P28	P27	P26	P25	P24	P31 to P24	0x00
0x63	ED/HD CGMS Type B Register 5	ED/HD CGMS Type B Data Bits.	P39	P38	P37	P36	P35	P34	P33	P32	P39 to P32	0x00
0x64	ED/HD CGMS Type B Register 6	ED/HD CGMS Type B Data Bits.	P47	P46	P45	P44	P43	P42	P41	P40	P47 to P40	0x00
0x65	ED/HD CGMS Type B Register 7	ED/HD CGMS Type B Data Bits.	P55	P54	P53	P52	P51	P50	P49	P48	P55 to P48	0x00
0x66	ED/HD CGMS Type B Register 8	ED/HD CGMS Type B Data Bits.	P63	P62	P61	P60	P59	P58	P57	P56	P63 to P56	0x00
0x67	ED/HD CGMS Type B Register 9	ED/HD CGMS Type B Data Bits.	P71	P70	P69	P68	P67	P66	P65	P64	P71 to P64	0x00
0x68	ED/HD CGMS Type B Register 10	ED/HD CGMS Type B Data Bits.	P79	P78	P77	P76	P75	P74	P73	P72	P79 to P72	0x00
0x69	ED/HD CGMS Type B Register 11	ED/HD CGMS Type B Data Bits.	P87	P86	P85	P84	P83	P82	P81	P80	P87 to P80	0x00
0x6A	ED/HD CGMS Type B Register 12	ED/HD CGMS Type B Data Bits.	P95	P94	P93	P92	P91	P90	P89	P88	P95 to P88	0x00
0x6B	ED/HD CGMS Type B Register 13	ED/HD CGMS Type B Data Bits.	P103	P102	P101	P100	P99	P98	P97	P96	P103 to P96	0x00
0x6C	ED/HD CGMS Type B Register 14	ED/HD CGMS Type B Data Bits.	P111	P110	P109	P108	P107	P106	P105	P104	P111 to P104	0x00
0x6D	ED/HD CGMS Type B Register 15	ED/HD CGMS Type B Data Bits.	P119	P118	P117	P116	P115	P114	P113	P112	P119 to P112	0x00
0x6E	ED/HD CGMS Type B Register 16	ED/HD CGMS Type B Data Bits.	P127	P126	P125	P124	P123	P122	P121	P120	P127 to P120	0x00

Table 23. Register 0x80 to Register 0x83

SR7 to		o to Register 0x83	Bit Number									Reset
SR0	Register	Bit Description	7	6	5	4	3	2	1	0	Register Setting	Value
0x80	SD Mode	SD Standard.							0	0	NTSC	0x10
	Register 1								0	1	PAL B, PAL D, PAL G, PAL H, PAL I	
									1	0	PAL M	
									1	1	PAL N	
		SD Luma Filter.				0	0	0			LPF NTSC	
						0	0	1			LPF PAL	
						0	1	0			Notch NTSC	
						0	1	1			Notch PAL	
						1	0	0			Luma SSAF	
						1	0	1			Luma CIF	
						1	1	0			Luma QCIF	
						1	1	1			Reserved	
		SD Chroma Filter.	0	0	0						1.3 MHz	
			0	0	1						0.65 MHz	
			0	1	0						1.0 MHz	
			0	1	1						2.0 MHz	
			1	0	0						Reserved	
			1	0	1						Chroma CIF	
			1	1	0						Chroma QCIF	
			1	1	1						3.0 MHz	
0x82	SD Mode	SD PrPb SSAF Filter.	1		·					0	Disabled	0x0B
0,102	Register 2	35111 5 33711 1 111.61.								1	Enabled	ONOD
		SD DAC Output 1.	1						0	<u> </u>	Refer to Table 32 in the Output	
		35 BAC Output 1.							1		Configuration section	
		Reserved.	1					0	<u>'</u>			
		SD Pedestal.	1				0	U			Disabled	
		3D redestal.					1				Enabled	
		CD Causes Divol Mode	-			_	<u> </u>				Disabled	
		SD Square Pixel Mode.				0						
		50.1/50.55/01/15	-			1					Enabled	
		SD VCR FF/RW Sync.			0						Disabled	
		60.01.10.11.11	-	_	1						Enabled	
		SD Pixel Data Valid.		0							Disabled	
			<u> </u>	1							Enabled	
		SD Active Video Edge	0								Disabled	
		Control.	1								Enabled	
0x83	SD Mode	SD Pedestal YPrPb Output.									No pedestal on YPrPb	0x04
	Register 3									1	7.5 IRE pedestal on YPrPb	
		SD Output Levels Y.							0		Y = 700 mV/300 mV	
									1		Y = 714 mV/286 mV	
		SD Output Levels PrPb.					0	0			700 mV p-p (PAL), 1000 mV p-p (NTSC)	
							0	1			700 mV p-p	
							1	0			1000 mV p-p	
							1	1			648 mV p-p	
		SD Vertical Blanking				0					Disabled	
		Interval (VBI) Open.				1					Enabled	
		SD Closed Captioning		0	0						Closed captioning disabled	
		Field Control.		0	1						Closed captioning on odd field only	
				1	0						Closed captioning on even field only	
				1	1						Closed captioning on both fields	
		Reserved.	0							1	Reserved	

Table 24 Register 0x84 to Register 0x87

SR7 to					В	it Nu	ımb	er				Reset	
SRO	Register	Bit Description	7	6	5	4	3	2	1	0	Register Setting	Value	
0x84	SD Mode	SD VSYNC-3H.					0	Disabled	0x00				
	Register 4									1	VSYNC= 2.5 lines (PAL),		
											VSYNC= 3 lines (NTSC)		
		SD SFL/SCR/TR Mode Select.						0	0		Disabled		
								0	1		Subcarrier reset mode enabled		
								1	0		Timing reset mode enabled		
								1	1		SFL mode enabled		
		SD Active Video Length.					0				720 pixels	Ī	
							1				710 (NTSC), 702 (PAL)		
		SD Chroma.				0					Chroma enabled	Ī	
						1					Chroma disabled		
		SD Burst.			0						Enabled	1	
					1						Disabled		
		SD Color Bars.		0							Disabled	1	
				1							Enabled		
		SD Luma/Chroma Swap.	0								DAC 2 = luma, DAC 3 = chroma	1	
		· ·	1								DAC 2 = chroma, DAC 3 = luma		
0x86	SD Mode	NTSC Color Subcarrier Adjust (Delay from							0	0	5.17 μs	0x02	
	Register 5	the falling edge of output HSYNC pulse to							0	1	5.31 µs	_	
		start of color burst).							1	0	5.59 µs (must be set for		
											Macrovision compliance)		
									1	1	Reserved		
		Reserved.						0				Ī	
		SD EIA/CEA-861B Synchronization					0				Disabled	1	
		Compliance.					1				Enabled		
		Reserved.			0	0						1	
		SD Horizontal/Vertical Counter Mode. ¹		0							Update field/line counter	Ī	
				1							Field/line counter free running		
		SD RGB Color Swap. ²	0								Normal	Ī	
		·	1								Color reversal enabled		
0x87	SD Mode	SD PrPb Scale.								0	Disabled	0x00	
	Register 6									1	Enabled		
		SD Y Scale.							0		Disabled	1	
									1		Enabled		
		SD Hue Adjust.						0			Disabled	1	
								1			Enabled		
		SD Brightness.					0				Disabled		
							1				Enabled		
		SD Luma SSAF Gain.				0	Ė				Disabled		
						1					Enabled		
			1		-	L'	1		-			1	
		SD Input Standard Auto Detection			n						l Disabled		
		SD Input Standard Auto Detection.			0						Disabled Enabled		
		·		0	1						Enabled		
		SD Input Standard Auto Detection. Reserved. SD RGB Input Enable. ²	0	0								 - -	

¹ When set to 0, the horizontal/vertical counters automatically wrap around at the end of the line/field/frame of the selected standard. When set to 1, the horizontal/vertical counters are free running and wrap around when external sync signals indicate to do so. ² Available on the ADV7392/ADV7393 (40-pin devices) only.

Table 25. Register 0x88 to Register 0x89

SR7 to		Bit Description			В	it Nu	umb	er				Reset Value
SR0	Register		7	6	5	4	3	2	1	0	Register Setting	
0x88	SD Mode	Reserved.								0		0x00
	Register 7	SD Noninterlaced Mode.							0		Disabled	
									1		Enabled	
		SD Double Buffering.						0			Disabled	
								1			Enabled	
		SD Input Format.				0	0				8-bit input	
						0	1				16-bit input ¹	
						1	0				10-bit input ¹	
						1	1				Reserved	
		SD Digital Noise Reduction.			0						Disabled	
					1						Enabled	
		SD Gamma Correction Enable.		0							Disabled	
				1							Enabled	
		SD Gamma Correction Curve Select.	0								Gamma Correction Curve A	
			1								Gamma Correction Curve B	
0x89	SD Mode	SD Undershoot Limiter.							0	0	Disabled	0x00
	Register 8								0	1	-11 IRE	
									1	0	−6 IRE	
									1	1	-1.5 IRE	
		Reserved.						0			0 must be written to this bit	
		SD Black Burst Output on DAC Luma.					0				Disabled	
							1				Enabled	
		SD Chroma Delay.			0	0					Disabled	
					0	1					4 clock cycles	
					1	0					8 clock cycles	
					1	1					Reserved	1
		Reserved.	0	0							0 must be written to these bits	

¹ Available on the ADV7392/ADV7393 (40-pin devices) only.

Table 26. Register 0x8A to Register 0x98

SR7 to						Bit Nu	ımbe	r				Reset
SRO	Register	Bit Description	7	6	5	4	3	2	1	0	Register Setting	Value
0x8A	SD Timing Register 0	SD Slave/Master Mode.								0	Slave mode	0x08
										1	Master mode	
		SD Timing Mode.						0	0		Mode 0	
								0	1		Mode 1	
								1	0		Mode 2	
								1	1		Mode 3	
		Reserved.					1					
		SD Luma Delay.			0	0					No delay	
					0	1					2 clock cycles	
					1	0					4 clock cycles	
					1	1					6 clock cycles	
		SD Minimum Luma Value.		0							-40 IRE	
				1							–7.5 IRE	
		SD Timing Reset.	x								A low-high-low transition resets the internal SD timing counters	
0x8B	SD Timing Register 1	SD HSYNC Width.							0	0	t _a = 1 clock cycle	0x00
ONOD	Note: Applicable in	SETISTIVE WIGHT.							0	1	t _a = 4 clock cycles	ONOO
	master modes only,								1	0	t _a = 16 clock cycles	
	that is, Subaddress								1	1	t _a = 128 clock cycles	
	0x8A, Bit $0 = 1$.	SD HSYNC to VSYNC Delay.					0	0	-		$t_b = 0$ clock cycles	1
		SETISTICE OF VEHICLE CIAY.					0	1			$t_b = 4$ clock cycles	
							1	0			$t_b = 8$ clock cycles	
							1	1			$t_b = 18$ clock cycles	
		SD HSYNC to VSYNC Rising			х	0					$t_c = t_b$	1
		Edge Delay (Mode 1 Only).			x	1					$t_c = t_b + 32 \mu s$	
		VSYNC Width (Mode 2 Only).			0	0					1 clock cycle	1
		V311VC Width (Mode 2 Only).			0	1					4 clock cycles	
					1	0					16 clock cycles	
					1	1					128 clock cycles	
		HSYNC to Pixel Data Adjust.	0	0		•					0 clock cycles	1
		TISTIVE to Fixer Butta Adjust.	0	1							1 clock cycle	
			1	0							2 clock cycles	
			1	1							3 clock cycles	
0x8C	SD F _{sc} Register 0 ¹	Subcarrier Frequency Bits[7:0]	х	х	х	х	х	х	х	х	Subcarrier Frequency Bits[7:0]	0x1F
0x8D	SD F _{sc} Register 1 ¹	Subcarrier Frequency Bits[15:8]	х	х	х	х	х	х	х	х	Subcarrier Frequency Bits[15:8]	0x7C
0x8E	SD F _{sc} Register 2 ¹	Subcarrier Frequency Bits[23:16]	х	х	х	х	х	х	х	х	Subcarrier Frequency Bits[23:16]	0xF0
0x8F	SD F _{sc} Register 3 ¹	Subcarrier Frequency Bits[31:24]	х	х	х	х	х	х	х	х	Subcarrier Frequency Bits[31:24]	0x21
0x90	SD F _{sc} Phase	Subcarrier Phase Bits[9:2]	х	х	х	Х	х	х	х	Х	Subcarrier Phase Bits[9:2]	0x00
0x91	SD Closed Captioning	Extended Data on Even Fields.	х	х	х	х	х	х	х	х	Extended Data Bits[7:0]	0x00
0x92	SD Closed Captioning	Extended Data on Even Fields.	х	х	х	х	х	х	х	х	Extended Data Bits[15:8].	0x00
0x93	SD Closed Captioning	Data on Odd Fields.	Х	х	х	Х	х	х	х	Х	Data Bits[7:0]	0x00
0x94	SD Closed Captioning	Data on Odd Fields.	х	х	х	х	х	х	х	х	Data Bits[15:8]	0x00
0x95	SD Pedestal Register 0	Pedestal on Odd Fields.	17	16	15	14	13	12	11	10	Setting any of these bits	0x00
	SD Pedestal Register 1	Pedestal on Odd Fields.	25	24	23	22	21	20	19	18	to 1 disables pedestal	0x00
0x96												
0x96 0x97	SD Pedestal Register 2	Pedestal on Even Fields.	17	16	15	14	13	12	11	10	on the line number indicated by the bit	0x00

 $^{^{\}rm 1}\,{\rm SD}$ subcarrier frequency registers default to NTSC subcarrier frequency values.

Table 27. Register 0x99 to Register 0xA5

SR7 to	27. Register 0x99 to 1					Bit Nu	ımbe	r				Reset
SRO	Register	Bit Description	7	6	5	4	3	2	1	0	Register Setting	Value
0x99	SD CGMS/WSS 0	SD CGMS Data.					Х	х	х	Х	CGMS Data Bits[C19:C16]	0x00
		SD CGMS CRC.				0					Disabled	
						1					Enabled	
		SD CGMS on Odd Fields.			0						Disabled	1
					1						Enabled	
		SD CGMS on Even Fields.		0							Disabled	
				1							Enabled	
		SD WSS.	0								Disabled	
			1								Enabled	
0x9A	SD CGMS/WSS 1	SD CGMS/WSS Data.			х	х	х	х	х	х	CGMS Data Bits[C13:C8] or WSS Data Bits[W13:W8]	0x00
		SD CGMS Data.	х	х							CGMS Data Bits[C15:C14]	
0x9B	SD CGMS/WSS 2	SD CGMS/WSS Data.	x	x	х	х	х	х	х	х	CGMS Data Bits[C7:C0] or	0x00
											WSS Data Bits[W7:W0]	
0x9C	SD Scale LSB Register	LSBs for SD Y Scale Value.							Х	Х	SD Y Scale Bits[1:0]	0x00
	Register	LSBs for SD Cb Scale Value.					Х	Х			SD Cb Scale Bits[1:0]	
		LSBs for SD Cr Scale Value.			Х	Х					SD Cr Scale Bits[1:0]	
		LSBs for SD F _{SC} Phase.	Х	Х							Subcarrier Phase Bits[1:0]	
0x9D	SD Y Scale Register	SD Y Scale Value.	Х	Х	Х	Х	Х	Х	Х	Х	SD Y Scale Bits[7:2]	0x00
0x9E	SD Cb Scale Register	SD Cb Scale Value.	Х	х	х	Х	Х	Х	Х	Х	SD Cb Scale Bits[7:2]	0x00
0x9F	SD Cr Scale Register	SD Cr Scale Value.	Х	Х	Х	Х	Х	Х	Х	Х	SD Cr Scale Bits[7:2]	0x00
0xA0	SD Hue Register	SD Hue Adjust Value.	х	Х	Х	х	Х	х	х	Х	SD Hue Adjust Bits[7:0]	0x00
0xA1	SD Brightness/WSS	SD Brightness Value.		х	Х	х	Х	х	х	Х	SD Brightness Bits[6:0]	0x00
		SD Blank WSS Data.	0								Disabled Enabled	
0xA2	SD Luma SSAF	SD Luma SSAF Gain/Attenuation.	<u> </u>				0	0	0	0	-4 dB	0x00
OXITE	SD Lama SS/N	Note: Only applicable if										OXOO
		Subaddress 0x87, Bit 4 = 1.					0	1	1	0	0 dB	
								·				
							1	1	0	0	+4 dB	
		Reserved.	0	0	0	0						1
0xA3	SD DNR 0	Coring Gain Border.	Ť		1		0	0	0	0	No gain	0x00
		Note: In DNR mode, the values					0	0	0	1	+1/16 [-1/8]	
		in brackets apply.					0	0	1	0	+2/16 [-2/8]	
							0	0	1	1	+3/16 [-3/8]	
							0	1	0	0	+4/16 [-4/8]	
							0	1	0	1	+5/16 [-5/8]	
							0	1	1	0	+6/16 [-6/8]	
							0	1	1	1	+7/16 [-7/8]	
							1	0	0	0	+8/16 [-1]	
		Coring Gain Data.	0	0	0	0					No gain	1
		Note: In DNR mode, the values	0	0	0	1					+1/16 [-1/8]	
		in brackets apply.	0	0	1	0					+2/16 [-2/8]	
			0	0	1	1					+3/16 [-3/8]	
			0	1	0	0					+4/16 [-4/8]	
			0	1	0	1					+5/16 [-5/8]	
			0	1	1	0					+6/16 [-6/8]	
			0	1	1	1					+7/16 [-7/8]	
			1	0	0	0					+8/16 [-1]	

SR7 to					ı	Bit Nu	ımbe	r				Reset
SR0	Register	Bit Description	7	6	5	4	3	2	1	0	Register Setting	Value
0xA4	SD DNR 1	DNR Threshold.			0	0	0	0	0	0	0	0x00
					0	0	0	0	0	1	1	
					1	1	1	1	1	0	62	
					1	1	1	1	1	1	63	
		Border Area.		0							2 pixels	
				1							4 pixels	
		Block Size.	0								8 pixels	
			1								16 pixels	
0xA5	SD DNR 2	DNR Input Select.						0	0	1	Filter A	0x00
								0	1	0	Filter B	
								0	1	1	Filter C	
								1	0	0	Filter D	
		DNR Mode.				0					DNR mode	
						1					DNR sharpness mode	
		DNR Block Offset.	0	0	0	0					0 pixel offset	
			0	0	0	1					1 pixel offset	
			1	1	1	0					14 pixel offset	
			1	1	1	1					15 pixel offset	

Table 28. Register 0xA6 to Register 0xBB

SR7 to					Bi	t Nun	nber					Reset
SRO	Register	Bit Description	7	6	5	4	3	2	1	0	Register Setting	Value
0xA6	SD Gamma A0	SD Gamma Curve A (Point 24).	х	х	х	х	Х	Х	х	Х	A0	0x00
0xA7	SD Gamma A1	SD Gamma Curve A (Point 32).	х	х	х	Х	х	х	х	Х	A1	0x00
0xA8	SD Gamma A2	SD Gamma Curve A (Point 48).	х	х	х	Х	х	х	х	Х	A2	0x00
0xA9	SD Gamma A3	SD Gamma Curve A (Point 64).	х	х	х	х	Х	Х	х	Х	A3	0x00
0xAA	SD Gamma A4	SD Gamma Curve A (Point 80).	Х	Х	Х	Х	х	х	х	Х	A4	0x00
0xAB	SD Gamma A5	SD Gamma Curve A (Point 96).	х	х	х	х	Х	Х	х	Х	A5	0x00
0xAC	SD Gamma A6	SD Gamma Curve A (Point 128).	Х	Х	Х	Х	х	х	Х	Х	A6	0x00
0xAD	SD Gamma A7	SD Gamma Curve A (Point 160).	Х	Х	Х	Х	х	х	х	Х	A7	0x00
0xAE	SD Gamma A8	SD Gamma Curve A (Point 192).	х	х	х	х	Х	Х	х	Х	A8	0x00
0xAF	SD Gamma A9	SD Gamma Curve A (Point 224).	Х	Х	Х	Х	х	х	Х	Х	A9	0x00
0xB0	SD Gamma B0	SD Gamma Curve B (Point 24).	Х	Х	Х	Х	х	х	Х	Х	B0	0x00
0xB1	SD Gamma B1	SD Gamma Curve B (Point 32).	Х	Х	Х	Х	х	х	Х	Х	B1	0x00
0xB2	SD Gamma B2	SD Gamma Curve B (Point 48).	Х	Χ	Х	Х	х	х	Х	Х	B2	0x00
0xB3	SD Gamma B3	SD Gamma Curve B (Point 64).	х	Х	х	Х	х	Х	х	Х	B3	0x00
0xB4	SD Gamma B4	SD Gamma Curve B (Point 80).	Х	Х	Х	Х	х	х	Х	Х	B4	0x00
0xB5	SD Gamma B5	SD Gamma Curve B (Point 96).	х	Х	х	Х	х	Х	х	Х	B5	0x00
0xB6	SD Gamma B6	SD Gamma Curve B (Point 128).	х	Х	х	Х	х	Х	х	Х	B6	0x00
0xB7	SD Gamma B7	SD Gamma Curve B (Point 160).	х	Х	х	Х	х	х	х	Х	B7	0x00
0xB8	SD Gamma B8	SD Gamma Curve B (Point 192).	Х	Х	Х	Х	х	х	Х	Х	B8	0x00
0xB9	SD Gamma B9	SD Gamma Curve B (Point 224).	Х	Х	Х	Х	х	х	Х	Х	B9	0x00
0xBA	SD Brightness Detect	SD Brightness Value.	х	х	х	Х	х	Х	Х	Х	Read only	0xXX
0xBB	Field Count Register	Field Count.						х	Х	Х	Read only	0x0X
		Reserved.			0	0	0				Reserved	
		Revision Code.	0	0							Read only	

Table 29. Register 0xE0 to Register 0xF1

SR7 to						Bit N	umbe	r				Reset
SR0	Register ¹	Bit Description	7	6	5	4	3	2	1	0	Register Setting	Value
0xE0	Macrovision	MV Control Bits.	Х	Х	Х	Х	Х	Х	Х	Х		0x00
0xE1	Macrovision	MV Control Bits.	х	Х	Х	Х	Х	Х	Х	х		0x00
0xE2	Macrovision	MV Control Bits.	х	Х	Х	Х	Х	Х	Х	х		0x00
0xE3	Macrovision	MV Control Bits.	Х	Х	Х	Х	Х	Х	Х	Х		0x00
0xE4	Macrovision	MV Control Bits.	Х	Х	Х	Х	Х	Х	Х	Х		0x00
0xE5	Macrovision	MV Control Bits.	Х	Х	Х	х	х	Х	Х	х		0x00
0xE6	Macrovision	MV Control Bits.	х	х	Х	х	х	Х	х	х		0x00
0xE7	Macrovision	MV Control Bits.	Х	Х	Х	Х	Х	Х	Х	Х		0x00
0xE8	Macrovision	MV Control Bits.	Х	Х	Х	Х	Х	Х	Х	Х		0x00
0xE9	Macrovision	MV Control Bits.	х	х	Х	х	х	х	х	х		0x00
0xEA	Macrovision	MV Control Bits.	х	х	Х	х	х	х	х	х		0x00
0xEB	Macrovision	MV Control Bits.	Х	Х	Х	Х	Х	Х	Х	Х		0x00
0xEC	Macrovision	MV Control Bits.	Х	Х	Х	х	х	Х	Х	х		0x00
0xED	Macrovision	MV Control Bits.	х	х	Х	х	х	Х	х	х		0x00
0xEE	Macrovision	MV Control Bits.	х	х	х	х	х	х	х	х		0x00
0xEF	Macrovision	MV Control Bits.	х	х	х	х	х	х	х	х		0x00
0xF0	Macrovision	MV Control Bits.	х	х	Х	х	х	х	х	х		0x00
0xF1	Macrovision	MV Control Bit.	0	0	0	0	0	0	0	х	Bits[7:1] must be 0	0x00

 $^{^{\}rm 1}$ Macrovision registers are only available on the ADV7390 and the ADV7392.

ADV7390/ADV7391 INPUT CONFIGURATION

The ADV7390/ADV7391 supports a number of different input modes. The desired input mode is selected using Subaddress 0x01, Bits[6:4]. The ADV7390/ADV7391 defaults to standard definition (SD) mode upon power-up. Table 30 provides an overview of all possible input configurations. Each input mode is described in detail in this section.

Table 30. ADV7390/ADV7391 Input Configuration

Inpu	t Mode	P7	P6	P5	P4	P2	P2	P1	P0
000	SD				YCı	Сb			
010	ED/HD-DDR	YCrCb							
111	ED (at 54 MHz)	YCrCb							

STANDARD DEFINITION

Subaddress 0x01, Bits[6:4] = 000

SD YCrCb data can be input in an interleaved 4:2:2 format over an 8-bit bus rate of 27 MHz.

A 27 MHz clock signal must be provided on the CLKIN pin. If required, external synchronization signals can be provided on the HSYNC and VSYNC pins. Embedded EAV/SAV timing codes are also supported. The ITU-R BT.601/656 input standard is supported.

The interleaved pixel data is input on Pin P7 to Pin P0, with P0 being the LSB.

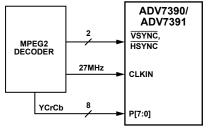


Figure 49. SD Example Application

ENHANCED DEFINITION/HIGH DEFINITION

Subaddress 0x01, Bits[6:4] = 010

ED or HD YCrCb data can be input in an interleaved 4:2:2 format over an 8-bit DDR bus.

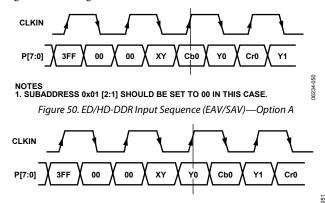
The clock signal must be provided on the CLKIN pin. If required, external synchronization signals can be provided on the HSYNC and VSYNC pins. Embedded EAV/SAV timing codes are also supported.

8-Bit 4:2:2 ED/HD YCrCb Mode (DDR)

In 8-bit DDR 4:2:2 YCrCb input mode, the Y pixel data is input on Pin P7 to Pin P0 upon either the rising or falling edge of CLKIN. P0 is the LSB.

The CrCb pixel data is also input on Pin P7 to Pin P0 upon the opposite edge of CLKIN. P0 is the LSB.

Whether the Y data is clocked in upon the rising or falling edge of CLKIN is determined by Subaddress 0x01, Bits[2:1] (see Figure 50 and Figure 51).



NOTES
1. SUBADDRESS 0x01 [2:1] SHOULD BE SET TO 11 IN THIS CASE.

Figure 51. ED/HD-DDR Input Sequence (EAV/SAV)—Option B

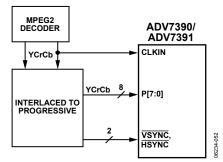


Figure 52. ED/HD-DDR Example Application

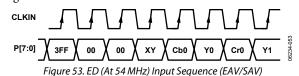
ENHANCED DEFINITION (AT 54 MHz)

Subaddress 0x01, Bits[6:4] = 111

ED YCrCb data can be input in an interleaved 4:2:2 format over an 8-bit bus rate of 54 MHz.

A 54 MHz clock signal must be provided on the CLKIN pin. Embedded EAV/SAV timing codes are supported. External synchronization signals are not supported in this mode.

The interleaved pixel data is input on Pin P7 to Pin P0, with P0 being the LSB.



ADV7392/ADV7393 INPUT CONFIGURATION

The ADV7392/ADV7393 supports a number of different input modes. The desired input mode is selected using Subaddress 0x01, Bits[6:4]. The ADV7392/ADV7393 defaults to standard definition (SD) mode upon power-up. Table 31 provides an overview of all possible input configurations. Each input mode is described in detail in this section.

STANDARD DEFINITION

Subaddress 0x01, Bits[6:4] = 000

SD YCrCb data can be input in 4:2:2 format over an 8-, 10-, or 16-bit bus. SD RGB data can be input in 4:4:4 format over a 16-bit bus.

A 27 MHz clock signal must be provided on the CLKIN pin. If required, external synchronization signals can be provided on the HSYNC and VSYNC pins. Embedded EAV/SAV timing codes are also supported in 8-bit and 10-bit modes.

8-Bit 4:2:2 YCrCb Mode

Subaddress 0x87, Bit 7 = 0 Subaddress 0x88, Bits[4:3] = 00

In 8-bit 4:2:2 YCrCb input mode, the interleaved pixel data is input on Pin P15 to Pin P8, with P8 being the LSB. The ITU-R BT.601/656 input standard is supported.

10-Bit 4:2:2 YCrCb Mode

Subaddress 0x87, Bit 7 = 0 Subaddress 0x88, Bits[4:3] = 10

In 10-bit 4:2:2 YCrCb input mode, the interleaved pixel data is input on Pin P15 to Pin P6, with P6 being the LSB. The ITU-R BT.601/656 input standard is supported.

16-Bit 4:2:2 YCrCb Mode

Subaddress 0x87, Bit 7 = 0 Subaddress 0x88, Bits[4:3] = 01

In 16-bit 4:2:2 YCrCb input mode, the Y pixel data is input on Pin P15 to Pin P8, with P8 being the LSB.

The CrCb pixel data is input on Pin P7 to Pin P0, with P0 being the LSB.

The pixel data is updated at half the rate of the clock, that is, at a rate of 13.5 MHz (see Figure 3).

16-Bit 4:4:4 RGB Mode

Subaddress 0x87, Bit 7 = 1

In 16-bit 4:4:4 RGB input mode, the red pixel data is input on Pin P4 to Pin P0, the green pixel data is input on Pin P10 to Pin P5, and the blue pixel data is input on Pin P15 to Pin P11. P0, P5, and P11 are the respective bus LSBs.

The pixel data is updated at half the rate of the clock, that is, at a rate of 13.5 MHz (see Figure 4).

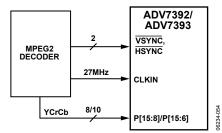


Figure 54. SD Example Application

Table 31. ADV7392/ADV7393 Input Configuration

Input	Mode ¹	P15	P14	P13	P12	P11	P10	P9	P8	P7	P6	P5	P4	Р3	P2	P1	P0
000	SD ²						SD RGB I	nput E	nable	(0x87[7]) = 0	•					
	8-Bit		YCrCb														
	10-Bit					YCrCk)										
	16-Bit³				Υ								Cr	Cb			
						9	SD RGB I	nput E	nable	(0x87[7]) = 1						
	16-Bit ³			В					G	i					R		
001	ED/HD-SDR (16-Bit)		Υ					CrCb									
010	ED/HD-DDR⁴						ED/HD I	nput F	ormat	(0x33[2]) = 0						
	8-Bit				YCrO	Cb											
							ED/HD I	nput F	ormat	(0x33[2]) = 1						
	10-Bit					YCrCk)										
111	ED (At 54 MHz)		ED/HD Input Format (0x33[2]) = 0														
	8-Bit		YCrCb														
		ED/HD Input Format (0x33[2]) =					2]) = 1										
	10-Bit	YCrCb															

¹ The input mode is determined by Subaddress 0x01, Bits[6:4].

² In SD mode, the width of the input data is determined by Subaddress 0x88, Bits[4:3].

³ External synchronization signals must be used in this input mode. Embedded EAV/SAV timing codes are not supported.

⁴ ED = enhanced definition = 525p and 625p.

ENHANCED DEFINITION/HIGH DEFINITION

Subaddress 0x01, Bits[6:4] = 001 or 010

ED or HD YCrCb data can be input in a 4:2:2 format over an 8-/10-bit DDR bus or a 16-bit SDR bus.

The clock signal must be provided on the CLKIN pin. If required, external synchronization signals can be provided on the $\overline{\text{HSYNC}}$ and $\overline{\text{VSYNC}}$ pins. Embedded EAV/SAV timing codes are also supported.

16-Bit 4:2:2 YCrCb Mode (SDR)

In 16-bit 4:2:2 YCrCb input mode, the Y pixel data is input on Pin P15 to Pin P8, with P8 being the LSB.

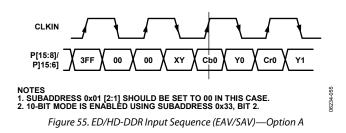
The CrCb pixel data is input on Pin P7 to Pin P0, with P0 being the LSB.

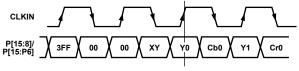
8-/10-Bit 4:2:2 YCrCb Mode (DDR)

In 8-/10-bit DDR 4:2:2 YCrCb input mode, the Y pixel data is input on Pin P15 to Pin P8/P6 upon either the rising or falling edge of CLKIN. P8/P6 is the LSB.

The CrCb pixel data is also input on Pin P15 to Pin P8/P6 upon the opposite edge of CLKIN. P8/P6 is the LSB.

10-bit mode is enabled using Subaddress 0x33, Bit 2. Whether the Y data is clocked in upon the rising or falling edge of CLKIN is determined by Subaddress 0x01, Bits[2:1] (see Figure 55 and Figure 56).





NOTES
1. SUBADDRESS 0x01 [2:1] SHOULD BE SET TO 11 IN THIS CASE.
2. 10-BIT MODE IS ENABLED USING SUBADDRESS 0x33, BIT 2.

Figure 56. ED/HD-DDR Input Sequence (EAV/SAV)—Option B

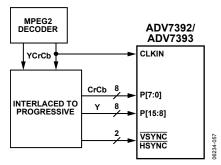


Figure 57. ED/HD-SDR Example Application

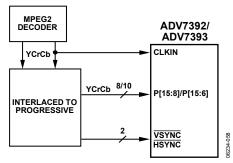


Figure 58. ED/HD-DDR Example Application

ENHANCED DEFINITION (AT 54 MHz)

Subaddress 0x01, Bits[6:4] = 111

ED YCrCb data can be input in an interleaved 4:2:2 format on an 8-/10-bit bus at a rate of 54 MHz.

A 54 MHz clock signal must be provided on the CLKIN pin. Embedded EAV/SAV timing codes are supported. External synchronization signals are not supported in this mode.

The interleaved pixel data is input on Pin P15 to Pin P8/P6, with P8/P6 being the LSB.

10-bit mode is enabled using Subaddress 0x33, Bit 2.

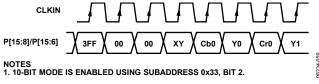


Figure 59. ED (At 54 MHz) Input Sequence (EAV/SAV)

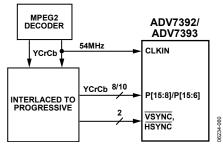


Figure 60. ED (At 54 MHz) Example Application

OUTPUT CONFIGURATION

The ADV739x supports a number of different output configurations. Table 32 to Table 34 lists all possible output configurations.

Table 32. SD Output Configurations

RGB/YPrPb Output Select ¹ (0x02, Bit 5)	SD DAC Output 1 (0x82, Bit 1)	SD Luma/Chroma Swap (0x84, Bit 7)	DAC 1	DAC 2	DAC 3
0	0	0	G	В	R
1	0	0	Υ	Pb	Pr
1	1	0	CVBS	Luma	Chroma
1	1	1	CVBS	Chroma	Luma

¹ If SD RGB output is selected, a color reversal is possible using Subaddress 0x86, Bit 7.

Table 33. ED/HD Output Configurations

RGB/YPrPb Output Select (0x02, Bit 5)	ED/HD Color DAC Swap (0x35, Bit 3)	DAC 1	DAC 2	DAC 3
0	0	G	В	R
0	1	G	R	В
1	0	Υ	Pb	Pr
1	1	Υ	Pr	Pb

Table 34. ED (at 54 MHz) Output Configurations

(, r8				
RGB/YPrPb Output Select (0x02, Bit 5)	ED/HD Color DAC Swap (0x35, Bit 3)	DAC 1	DAC 2	DAC 3
0	0	G	В	R
0	1	G	R	В
1	0	Υ	Pb	Pr
1	1	Υ	Pr	Pb

FEATURES

OUTPUT OVERSAMPLING

The ADV739x include an on-chip phase-locked loop (PLL) that allows for oversampling of SD, ED, and HD video data. By default, the PLL is disabled. The PLL can be enabled using Subaddress 0x00, Bit 1=0.

Table 35 shows the various oversampling rates supported in the ADV739x.

ED/HD NONSTANDARD TIMING MODE Subaddress 0x30, Bits[7:3] = 00001

For any ED/HD input data that does not conform to the standards listed in the ED/HD input mode table (Subaddress 0x30, Bits[7:3]), the ED/HD nonstandard timing mode can be used to interface to the ADV739x. ED/HD nonstandard timing mode can be enabled by setting Subaddress 0x30, Bits[7:3] to 00001.

A clock signal must be provided on the CLKIN pin. HSYNC and VSYNC must be toggled by the user to generate the appropriate horizontal and vertical synchronization pulses on the analog output from the encoder. Figure 61 illustrates the

various output levels that can be generated. Table 36 lists the transitions required to generate the various output levels.

Embedded EAV/SAV timing codes are not supported in ED/HD nonstandard timing mode.

The user must ensure that appropriate pixel data is applied to the encoder where the blanking level is expected at the output.

Macrovision (ADV7390/ADV7392 only) and output oversampling are not available in ED/HD nonstandard timing mode. The PLL must be disabled (Subaddress 0x00, Bit 1=1) in ED/HD nonstandard timing mode.

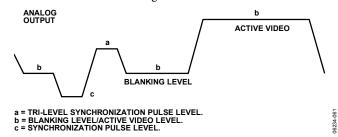


Figure 61. ED/HD Nonstandard Timing Mode Output Levels

Table 35. Output Oversampling Modes and Rates

Input Mo (0x01, Bi		PLL and Oversampling Control (0x00, Bit 1)	SD/ED Oversample Rate Select (0x0D, Bit 3)	HD Oversample Rate Select (0x31, Bit 1)	Oversampling Mode and Rate
000	SD	1	х	х	SD (2×)
000	SD	0	1	х	SD (8×)
000	SD	0	0	x	SD (16×)
001/010	ED	1	x	x	ED (1×)
001/010	ED	0	1	x	ED (4×)
001/010	ED	0	0	х	ED (8×)
001/010	HD	1	x	x	HD (1x)
001/010	HD	0	x	1	HD (2×)
001/010	HD	0	x	0	HD (4×)
111	ED (at 54 MHz)	1	x	х	ED (@ 54 MHz) (1×)
111	ED (at 54 MHz)	0	1	x	ED (@ 54 MHz) (4×)
111	ED (at 54 MHz)	0	0	х	ED (@ 54 MHz) (8×)

Table 36. ED/HD Nonstandard Timing Mode Synchronization Signal Generation

Output Level Transition ¹	HSYNC	VSYNC
$b \rightarrow c$	1 → 0	$1 \rightarrow 0 \text{ or } 0^2$
$c \rightarrow a$	0	$0 \rightarrow 1$
$a \rightarrow b$	$0 \rightarrow 1$	1
$c \rightarrow b$	$0 \rightarrow 1$	0

 $^{^{1}}$ a = Tri-level synchronization pulse level; b = blanking level/active video level; c = synchronization pulse level. See Figure 61.

² If VSYNC = 1, it should transition to 0. If VSYNC = 0, it should remain at 0. If tri-level synchronization pulse generation is not required, VSYNC should always be 0.

ED/HD TIMING RESET

Subaddress 0x34, Bit 0

An ED/HD timing reset is achieved by setting the ED/HD timing reset control bit (Subaddress 0x34, Bit 0) to 1. In this state, the horizontal and vertical counters remain reset. When this bit is set back to 0, the internal counters resume counting. This timing reset applies to the ED/HD timing counters only.

SD SUBCARRIER FREQUENCY LOCK, SUBCARRIER RESET, AND TIMING RESET

Subaddress 0x84, Bits[2:1]

Together with the SFL/MISO pin and SD Mode Register 4 (Subaddress 0x84, Bits[2:1]), the ADV739x can be used in timing reset mode, subcarrier phase reset mode, or SFL mode.

In timing reset (TR) mode (Subaddress 0x84, Bits[2:1] = 10),
 a timing reset is achieved in a low-to-high transition on the
 SFL/MISO pin. In this state, the horizontal and vertical
 counters remain reset. Upon releasing this pin (set to low),
 the internal counters resume counting, starting with Field 1,
 and the subcarrier phase is reset.

The minimum time the pin must be held high is one clock cycle; otherwise, this reset signal may not be recognized. This timing reset applies to the SD timing counters only.

• In subcarrier reset (SCR) mode (Subaddress 0x84, Bits[2:1] = 01), a low-to-high transition on the SFL/MISO pin resets the subcarrier phase to 0 on the field following the subcarrier phase reset.

This reset signal must be held high for a minimum of one clock cycle.

Because the field counter is not reset, it is recommended to apply the reset signal in Field 7 (PAL) or Field 3 (NTSC). The reset of the phase then occurs on the next field, that is, Field 1, which is lined up correctly with the internal counters. The field count register at Subaddress 0xBB can be used to identify the number of the active field.

• In subcarrier frequency lock (SFL) mode (Subaddress 0x84, Bits[2:1] = 11), the ADV739x can be used to lock to an external video source. The SFL mode allows the ADV739x to automatically alter the subcarrier frequency to compensate for line length variations. When the part is connected to a device such as an ADV7403 video decoder that outputs a digital data stream in the SFL format, the part automatically changes to the compensated subcarrier frequency on a line-by-line basis (see Figure 64). This digital data stream is 67 bits wide and the subcarrier is contained in Bit 0 to Bit 21. Each bit is two clock cycles long.

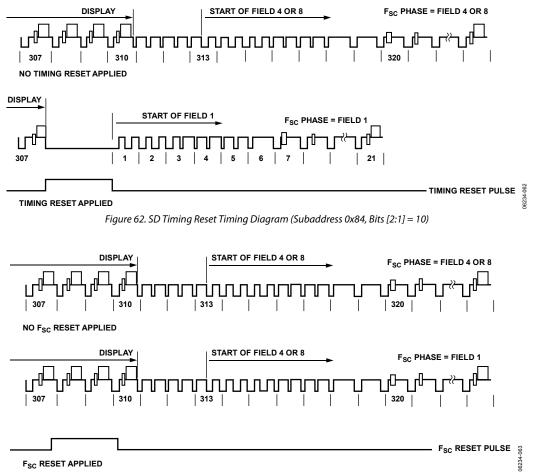


Figure 63. SD Subcarrier Phase Reset Timing Diagram (Subaddress 0x84, Bits [2:1] = 01)

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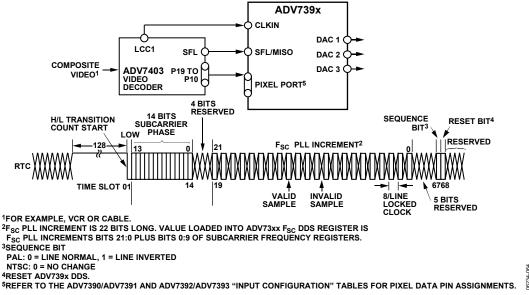


Figure 64. SD Subcarrier Frequency Lock Timing and Connections Diagram (Subaddress 0x84, Bits [2:1] = 11)

SD VCR FF/RW SYNC

Subaddress 0x82, Bit 5

In DVD record applications where the encoder is used with a decoder, the VCR FF/RW sync control bit can be used for non-standard input video, that is, in fast forward or rewind modes.

In fast forward mode, the sync information at the start of a new field in the incoming video usually occurs before the correct number of lines/fields is reached. In rewind mode, this sync signal usually occurs after the total number of lines/fields is reached. Conventionally, this means that the output video has corrupted field signals because one signal is generated by the incoming video and another is generated when the internal line/field counters reach the end of a field.

When the VCR FF/RW sync control is enabled (Subaddress 0x82, Bit 5), the <u>line/field</u> counters are updated according to the incoming <u>VSYNC</u> signal and when the analog output matches the incoming <u>VSYNC</u> signal.

This control is available in all slave-timing modes except Slave Mode 0.

VERTICAL BLANKING INTERVAL

Subaddress 0x31, Bit 4; Subaddress 0x83, Bit 4

The ADV739x is able to accept input data that contains vertical blanking interval (VBI) data (such as CGMS, WSS, VITS) in SD, ED, and HD modes.

If VBI is disabled (Subaddress 0x31, Bit 4 for ED/HD; Subaddress 0x83, Bit 4 for SD), VBI data is not present at the output and the entire VBI is blanked. These control bits are valid in all master and slave timing modes.

For the SMPTE 293M (525p) standard, VBI data can be inserted on Line 13 to Line 42 of each frame, or on Line 6 to Lind 43 for the ITU-R BT.1358 (625p) standard.

VBI data can be present on Line 10 to Line 20 for NTSC and on Line 7 to Line 22 for PAL.

In SD Timing Mode 0 (slave option), if VBI is enabled, the blanking bit in the EAV/SAV code is overwritten. It is possible to use VBI in this timing mode as well.

If CGMS is enabled and VBI is disabled, the CGMS data is nevertheless available at the output.

SD SUBCARRIER FREQUENCY REGISTERS Subaddress 0x8C to Subaddress 0x8F

Four 8-bit registers are used to set up the subcarrier frequency. The value of these registers is calculated using the following equation:

Subcarrier Frequency Register =

Number of subcarrier periods in one video line

Number of 27 MHz clock cycles in one video line

× 2³²

where the sum is rounded to the nearest integer.

For example, in NTSC mode:

Subcarrier Register Value =
$$\left(\frac{227.5}{1716}\right) \times 2^{32} = 569408543$$

where:

Subcarrier Register Value = 569408543d = 0×21F07C1F

SD F_{SC} Register 0: 0x1F SD F_{SC} Register 1: 0x7C SD F_{SC} Register 2: 0xF0

SD F_{SC} Register 3: 0x21

Programming the F_{sc}

The subcarrier frequency register value is divided into four F_{SC} registers as shown in the previous example. The four subcarrier frequency registers must be updated sequentially, starting with Subcarrier Frequency Register 0 and ending with Subcarrier Frequency Register 3. The subcarrier frequency updates only after the last subcarrier frequency register byte has been received by the ADV739x.

Typical F_{sc} Values

Table 37 outlines the values that should be written to the subcarrier frequency registers for NTSC and PAL B/D/G/H/I.

Table 37. Typical F_{SC} Values

Subaddress	Description	NTSC	PAL B/D/G/H/I
0x8C	F _{SC} 0	0x1F	0xCB
0x8D	F _{SC} 1	0x7C	0x8A
0x8E	F _{SC} 2	0xF0	0x09
0x8F	F _{SC} 3	0x21	0x2A

SD NONINTERLACED MODE

Subaddress 0x88, Bit 1

The ADV739x supports a SD noninterlaced mode. Using this mode, progressive inputs at twice the frame rate of NTSC and PAL (240p/59.94 Hz and 288p/50 Hz, respectively) can be input into the ADV739x. The SD noninterlaced mode can be enabled using Subaddress 0x88, Bit 1.

A 27 MHz clock signal must be provided on the CLKIN pin. Embedded EAV/SAV timing codes or external horizontal and vertical synchronization signals provided on the HSYNC and VSYNC pins can be used to synchronize the input pixel data.

All input configurations, output configurations, and features available in NTSC and PAL modes are available in SD noninterlaced mode.

For 240p/59.94 Hz input, the ADV739x should be configured for NTSC operation and Subaddress 0x88, Bit 1 should be set to 1.

For 288p/50 Hz input, the ADV739x should be configured for PAL operation and Subaddress 0x88, Bit 1 should be set to 1.

SD SQUARE PIXEL MODE

Subaddress 0x82, Bit 4

The ADV739x can be used to operate in square pixel mode (Subaddress 0x82, Bit 4). For NTSC operation, an input clock of 24.5454 MHz is required. Alternatively, for PAL operation, an input clock of 29.5 MHz is required. The internal timing logic adjusts accordingly for square pixel mode operation.

In square pixel mode, the timing diagrams shown in Figure 65 and Figure 66 apply.

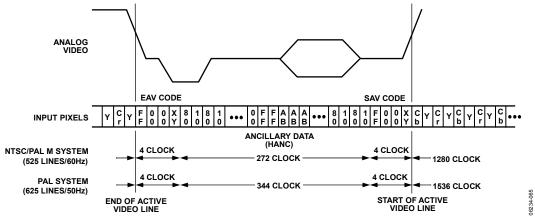


Figure 65. Square Pixel Mode EAV/SAV Embedded Timing

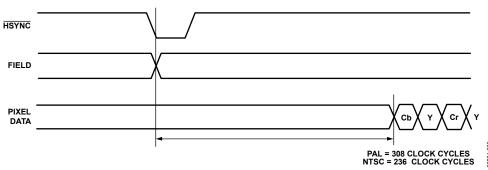


Figure 66. Square Pixel Mode Active Pixel Timing

FILTERS

Table 38 shows an overview of the programmable filters available on the ADV739x.

Table 38. Selectable Filters

Filter	Subaddress
SD Luma LPF NTSC	0x80
SD Luma LPF PAL	0x80
SD Luma Notch NTSC	0x80
SD Luma Notch PAL	0x80
SD Luma SSAF	0x80
SD Luma CIF	0x80
SD Luma QCIF	0x80
SD Chroma 0.65 MHz	0x80
SD Chroma 1.0 MHz	0x80
SD Chroma 1.3 MHz	0x80
SD Chroma 2.0 MHz	0x80
SD Chroma 3.0 MHz	0x80
SD Chroma CIF	0x80
SD Chroma QCIF	0x80
SD PrPb SSAF	0x82
ED/HD Sinc Compensation Filter	0x33
ED/HD Chroma SSAF	0x33

SD Internal Filter Response

Subaddress 0x80, Bits[7:2]; Subaddress 0x82, Bit 0

The Y filter supports several different frequency responses, including two low-pass responses, two notch responses, an extended (SSAF) response with or without gain boost attenuation, a CIF response, and a QCIF response. The PrPb filter supports several different frequency responses, including six low-pass responses, a CIF response, and a QCIF response, as shown in Figure 36 and Figure 37.

If SD Luma SSAF gain is enabled (Subaddress 0x87, Bit 4), there are 13 response options in the range -4 dB to +4 dB. The desired response can be programmed using Subaddress 0xA2. The variation of frequency responses are shown in Figure 33 to Figure 35.

In addition to the chroma filters listed in Table 38, the ADV739x contains an SSAF filter specifically designed for the color difference component outputs, Pr and Pb. This filter has a cutoff frequency of \sim 2.7 MHz and a gain of -40 dB at 3.8 MHz (see Figure 67). This filter can be controlled with Subaddress 0x82, Bit 0.

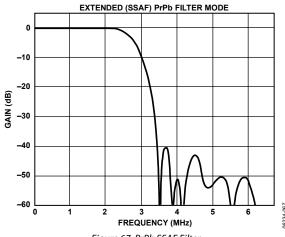


Figure 67. PrPb SSAF Filter

If this filter is disabled, one of the chroma filters shown in Table 39 can be selected and used for the CVBS or luma/chroma signal.

Table 39. Internal Filter Specifications

Filter	Pass-Band Ripple (dB) ¹	3 dB Bandwidth (MHz) ²
Luma LPF NTSC	0.16	4.24
Luma LPF PAL	0.1	4.81
Luma Notch NTSC	0.09	2.3/4.9/6.6
Luma Notch PAL	0.1	3.1/5.6/6.4
Luma SSAF	0.04	6.45
Luma CIF	0.127	3.02
Luma QCIF	Monotonic	1.5
Chroma 0.65 MHz	Monotonic	0.65
Chroma 1.0 MHz	Monotonic	1
Chroma 1.3 MHz	0.09	1.395
Chroma 2.0 MHz	0.048	2.2
Chroma 3.0 MHz	Monotonic	3.2
Chroma CIF	Monotonic	0.65
Chroma QCIF	Monotonic	0.5

 $^{^1}$ Pass-band ripple is the maximum fluctuation from the 0 dB response in the pass band, measured in dB. The pass band is defined to have 0 Hz to fc (Hz) frequency limits for a low-pass filter, and 0 Hz to f1 (Hz) and f2 (Hz) to infinity for a notch filter, where fc, f1, and f2 are the -3 dB points.

² 3 dB bandwidth refers to the –3 dB cutoff frequency.

ED/HD Sinc Compensation Filter Response Subaddress 0x33, Bit 3

The ADV739x includes a filter designed to counter the effect of sinc roll-off in DAC 1, DAC 2, and DAC 3 while operating in ED/HD mode. This filter is enabled by default. It can be disabled using Subaddress 0x33, Bit 3. The benefit of the filter is illustrated in Figure 68 and Figure 69.

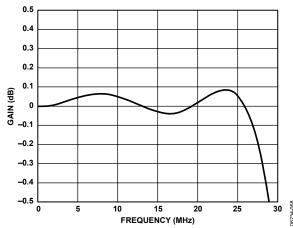


Figure 68. ED/HD Sinc Compensation Filter Enabled

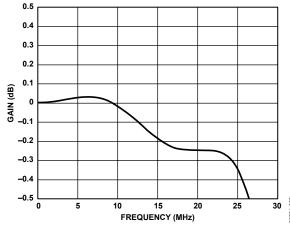


Figure 69. ED/HD Sinc Compensation Filter Disabled

ED/HD TEST PATTERN COLOR CONTROLS Subaddress 0x36 to Subaddress 0x38

Three 8-bit registers at Subaddress 0x36 to Subaddress 0x38 are used to program the output color of the internal ED/HD test pattern generator (Subaddress 0x31, Bit 2=1), whether it be the lines of the cross hatch pattern or the uniform field test pattern. They are not functional as color controls for external pixel data input.

The values for the luma (Y) and color difference (Cr and Cb) signals used to obtain white, black, and saturated primary and complementary colors conform to the ITU-R BT.601-4 standard.

Table 40 shows sample color values that can be programmed into the color registers when the output standard selection is set to EIA770.2/EIA770.3 (Subaddress 0x30, Bits[1:0] = 00).

Table 40. Sample Color Values for EIA770.2/EIA770.3 ED/HD Output Standard Selection

Sample Color	Y	Value	Cr	Value	Cb	Value
White	235	(0xEB)	128	(0x80)	128	(0x80)
Black	16	(0x10)	128	(0x80)	128	(0x80)
Red	81	(0x51)	240	(0xF0)	90	(0x5A)
Green	145	(0x91)	34	(0x22)	54	(0x36)
Blue	41	(0x29)	110	(0x6E)	240	(0xF0)
Yellow	210	(0xD2)	146	(0x92)	16	(0x10)
Cyan	170	(0xAA)	16	(0x10)	166	(0xA6)
Magenta	106	(0x6A)	222	(0xDE)	202	(0xCA)

COLOR SPACE CONVERSION MATRIX

Subaddress 0x03 to Subaddress 0x09

The internal color space conversion (CSC) matrix automatically performs all color space conversions based on the input mode programmed in the mode select register (Subaddress 0x01, Bits[6:4]). Table 41 and Table 42 show the options available in this matrix.

An SD color space conversion from RGB-in to YPrPb-out is possible on the ADV7392/ADV7393. An ED/HD color space conversion from RGB-in to YPrPb-out is not possible.

Table 41. SD Color Space Conversion Options

Input	Output ¹	YPrPb/RGB Out (Reg. 0x02, Bit 5)	RGB In/YCrCb In (Reg. 0x87, Bit 7)
YCrCb	YPrPb	1	0
YCrCb	RGB	0	0
RGB^2	YPrPb	1	1
RGB^2	RGB	0	1

¹ CVBS/YC outputs are available for all CSC combinations.

Table 42. ED/HD Color Space Conversion Options

Input	Output	YPrPb/RGB Out (Reg. 0x02, Bit 5)
YCrCb	YPrPb	1
YCrCb	RGB	0

ED/HD Manual CSC Matrix Adjust Feature

The ED/HD manual CSC matrix adjust feature provides custom coefficient manipulation for color space conversions and is used in ED and HD modes only. The ED/HD manual CSC matrix adjust feature can be enabled using Subaddress 0x02, Bit 3.

Normally, there is no need to enable this feature because the CSC matrix automatically performs the color space conversion based on the input mode chosen (ED or HD) and the output color space selected (see Table 42). For this reason, the ED/HD manual CSC matrix adjust feature is disabled by default.

² Available on the ADV7392/ADV7393 (40-pin devices) only.

If RGB output is selected, the ED/HD CSC matrix scalar uses the following equations:

$$R = GY \times Y + RV \times Pr$$

$$G = GY \times Y - (GU \times Pb) - (GV \times Pr)$$

$$B = GY \times Y + BU \times Pb$$

Note that subtractions are implemented in hardware.

If YPrPb output is selected, the following equations are used:

$$Y = GY \times Y$$

 $Pr = RV \times Pr$
 $Pb = BU \times Pb$

where:

GY = Subaddress 0x05, Bits[7:0] and Subaddress 0x03, Bits[1:0].

GU = Subaddress 0x06, Bits[7:0] and Subaddress 0x04, Bits[7:6].

GV = Subaddress 0x07, Bits[7:0] and Subaddress 0x04, Bits[5:4].

BU = Subaddress 0x08, Bits[7:0] and Subaddress 0x04, Bits[3:2].

RV = Subaddress 0x09, Bits[7:0] and Subaddress 0x04, Bits[1:0].

Upon power-up, the CSC matrix is programmed with the default values shown in Table 43.

Table 43. ED/HD Manual CSC Matrix Default Values

Subaddress	Default
0x03	0x03
0x04	0xF0
0x05	0x4E
0x06	0x0E
0x07	0x24
0x08	0x92
0x09	0x7C

When the ED/HD manual CSC matrix adjust feature is enabled, the default coefficient values in Subaddress 0x03 to Subaddress 0x09 are correct for the HD color space only. The color components are converted according to the following 1080i and 720p standards (SMPTE 274M, SMPTE 296M):

$$R = Y + 1.575Pr$$

 $G = Y - 0.468Pr - 0.187Pb$
 $B = Y + 1.855Pb$

The conversion coefficients should be multiplied by 315 before being written to the ED/HD CSC matrix registers. This is reflected in the default values for GY = 0x13B, GU = 0x03B, GV = 0x093, BU = 0x248, and RV = 0x1F0.

If the ED/HD manual CSC matrix adjust feature is enabled and another input standard (such as ED) is used, the scale values for GY, GU, GV, BU, and RV must be adjusted according to this input standard color space. The user should consider that the color component conversion might use different scale values.

For example, SMPTE 293M uses the following conversion:

$$R = Y + 1.402Pr$$

 $G = Y - 0.714Pr - 0.344Pb$
 $B = Y + 1.773Pb$

The programmable CSC matrix is used for external ED/HD pixel data and is not functional when internal test patterns are enabled.

Programming the CSC Matrix

If custom manipulation of the ED/HD CSC matrix coefficients is required for a YCrCb-to-RGB color space conversion, follow the following procedure:

- 1. Enable the ED/HD manual CSC matrix adjust feature (Subaddress 0x02, Bit 3).
- 2. Set the output to RGB (Subaddress 0x02, Bit 5).
- 3. Disable sync on PrPb (Subaddress 0x35, Bit 2).
- 4. Enable sync on RGB (optional) (Subaddress 0x02, Bit 4).

The GY value controls the green signal output level, the BU value controls the blue signal output level, and the RV value controls the red signal output level.

SD LUMA AND COLOR CONTROL Subaddress 0x9C to Subaddress 0x9F

SD Y Scale, SD Cb Scale, and SD Cr Scale are three 10-bit control registers that scale the SD Y, Cb, and Cr output levels.

Each of these registers represent the value required to scale the Cb or Cr level from 0.0 to 2.0 and the Y level from 0.0 to 1.5 times its initial level. The value of these 10 bits is calculated using the following equation:

Y, Cb, or Cr Scale Value = Scale $Factor \times 512$

For example, if $Scale\ Factor = 1.3$

Y, *Cb*, or *Cr Scale Value* = $1.3 \times 512 = 665.6$

Y, *Cb*, *or Cr Scale Value* = 666 (*rounded to the nearest integer*)

Y, *Cb*, *or Cr Scale Value* = 1010 0110 10b

Subaddress 0x9C, SD Scale LSB Register = 0x2A Subaddress 0x9D, SD Y Scale Register = 0xA6 Subaddress 0x9E, SD Cb Scale Register = 0xA6 Subaddress 0x9F, SD Cr Scale Register = 0xA6

Note that this feature affects all interlaced output signals, that is, CVBS, Y-C, YPrPb, and RGB.

SD HUE ADJUST CONTROL

Subaddress 0xA0

When enabled, the SD hue adjust control register (Subaddress 0xA0) is used to adjust the hue on the SD composite and chroma outputs. This feature can be enabled using Subaddress 0x87, Bit 2.

Subaddress 0xA0 contains the bits required to vary the hue of the video data, that is, the variance in phase of the subcarrier during active video with respect to the phase of the subcarrier during the color burst. The ADV739x provides a range of ±22.5° in increments of 0.17578125°. For normal operation (zero adjustment), this register is set to 0x80. Values 0xFF and 0x00 represent the upper and lower limits, respectively, of the attainable adjustment in NTSC mode. Values 0xFF and 0x01 represent the upper and lower limits, respectively, of the attainable adjustment in PAL mode.

The hue adjust value is calculated using the following equation:

Hue Adjust (°) =
$$0.17578125^{\circ}$$
 (HCR_d - 128)

where = HCR_d hue adjust control register (decimal)

For example, to adjust the hue by $+4^{\circ}$, write 0x97 to the hue adjust control register:

$$\left(\frac{4}{0.17578125}\right) + 128 \approx 151d = 0x97$$

where the sum is rounded to the nearest integer.

To adjust the hue by -4° , write 0x69 to the hue adjust control register:

$$\left(\frac{-4}{0.17578125}\right) + 128 \approx 105d = 0 \times 69$$

where the sum is rounded to the nearest integer.

SD BRIGHTNESS DETECT

Subaddress 0xBA

The ADV739x allows monitoring of the brightness level of the incoming video data. The SD brightness detect register (Subaddress 0xBA) is a read-only register.

SD BRIGHTNESS CONTROL

Subaddress 0xA1, Bits[6:0]

When this feature is enabled, the SD brightness/WSS control register (Subaddress 0xA1) is used to control brightness by adding a programmable setup level onto the scaled Y data. This feature can be enabled using Subaddress 0x87, Bit 3.

For NTSC with pedestal, the setup can vary from 0 IRE to 22.5 IRE. For NTSC without pedestal (see Figure 70) and for PAL, the setup can vary from -7.5 IRE to +15 IRE.

The SD brightness control register is an 8-bit register. The seven LSBs of this 8-bit register are used to control the brightness level, which can be a positive or negative value.

For example,

To add +20 IRE brightness level to an NTSC signal with pedestal, write 0x28 to Subaddress 0xA1.

$$0 \times (SD Brightness Value) =$$

$$0 \times (IRE\ Value \times 2.015631) =$$

$$0 \times (20 \times 2.015631) = 0 \times (40.31262) \approx 0x28$$

To add –7 IRE brightness level to a PAL signal, write 0x72 to Subaddress 0xA1.

$$0 \times (SD Brightness Value) =$$

$$0 \times (IRE\ Value \times 2.075631) =$$

$$0 \times (7 \times 2.015631) = 0x(14.109417) \approx 0001110b$$

0001110b into two's complement = 1110010b = 0x72

Table 44. Sample Brightness Control Values¹

Setup Level (NTSC) with Pedestal	Setup Level (NTSC) Without Pedestal	Setup Level (PAL)	Brightness Control Value
22.5 IRE	15 IRE	15 IRE	0x1E
15 IRE	7.5 IRE	7.5 IRE	0x0F
7.5 IRE	0 IRE	0 IRE	0x00
0 IRE	-7.5 IRE	-7.5 IRE	0x71

¹ Values in the range of 0x3F to 0x44 can result in an invalid output signal.

SD INPUT STANDARD AUTO DETECTION Subaddress 0x87, Bit 5

The ADV739x include an SD input standard auto detect feature that can be enabled by setting Subaddress 0x87, Bit 5 to Bit 1.

When enabled, the ADV739x can automatically identify an NTSC or PAL B/D/G/H/I input stream. The ADV739x automatically updates the subcarrier frequency registers with the appropriate value for the identified standard. The ADV739x is also configured to correctly encode the identified standard.

The SD standard bits (Subaddress 0x80, Bits[1:0]) and the subcarrier frequency registers are not updated to reflect the identified standard. All registers retain their default or user-defined values.

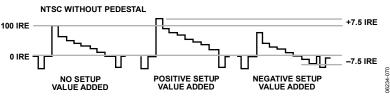


Figure 70. Examples of Brightness Control Values

DOUBLE BUFFERING

Subaddress 0x33, Bit 7 for ED/HD, Subaddress 0x88, Bit 2 for SD

Double-buffered registers are updated once per field. Double buffering improves overall performance because modifications to register settings are not be made during active video, but take effect prior to the start of the active video on the next field.

Using Subaddress 0x33, Bit 7, double buffering can be activated on the following ED/HD registers: ED/HD Gamma A and Gamma B curves, and ED/HD CGMS registers.

Using Subaddress 0x88, Bit 2, double buffering can be activated on the following SD registers: SD Gamma A and Gamma B curves, SD Y scale, SD Cr scale, SD Cb scale, SD brightness, SD closed captioning, and SD Macrovision Bits[5:0] (Subaddress 0xE0, Bits[5:0]).

PROGRAMMABLE DAC GAIN CONTROL

Subaddress 0x0B

It is possible to adjust the DAC output signal gain up or down from its absolute level. This is illustrated in Figure 71.

DAC 1 to DAC 3 are controlled by Register 0x0B.

CASE A

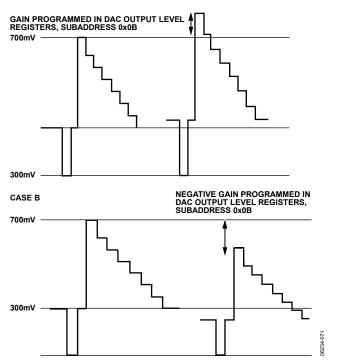


Figure 71. Programmable DAC Gain—Positive and Negative Gain

In Case A of Figure 71, the video output signal is gained. The absolute level of the sync tip and blanking level both increase with respect to the reference video output signal. The overall gain of the signal is increased from the reference signal.

In Case B of Figure 71, the video output signal is reduced. The absolute level of the sync tip and blanking level both decrease with respect to the reference video output signal. The overall gain of the signal is reduced from the reference signal.

The range of this feature is specified for $\pm 7.5\%$ of the nominal output from the DACs. For example, if the output current of the DAC is 4.33 mA, the DAC gain control feature can change this output current from 4.008 mA (-7.5%) to 4.658 mA (+7.5%).

The reset value of the control registers is 0x00, that is, nominal DAC current is output. Table 45 is an example of how the output current of the DACs varies for a nominal 4.33 mA output current.

Table 45. DAC Gain Control

Subaddress 0x0B	DAC Current (mA)	% Gain	Note
	` '		Note
0100 0000 (0x40)	4.658	7.5000%	
0011 1111 (0x3F)	4.653	7.3820%	
0011 1110 (0x3E)	4.648	7.3640%	
0000 0010 (0x02)	4.43	0.0360%	
0000 0001 (0x01)	4.38	0.0180%	
0000 0000 (0x00)	4.33	0.0000%	Reset value, nominal
1111 1111 (0xFF)	4.25	-0.0180%	
1111 1110 (0xFE)	4.23	-0.0360%	
1100 0010 (0xC2)	4.018	-7.3640%	
1100 0001 (0xC1)	4.013	-7.3820%	
1100 0000 (0xC0)	4.008	-7.5000%	

GAMMA CORRECTION

Subaddress 0x44 to Subaddress 0x57 for ED/HD, Subaddress 0xA6 to Subaddress 0xB9 for SD

Generally, gamma correction is applied to compensate for the nonlinear relationship between signal input and output brightness level (as perceived on a CRT). It can also be applied wherever nonlinear processing is used.

Gamma correction uses the function

 $Signal_{OUT} = (Signal_{IN})^{\gamma}$

where y = gamma correction factor.

Gamma correction is available for SD and ED/HD video. For both variations, there are 20, 8-bit registers. They are used to program Gamma Correction Curve A and Curve B.

ED/HD gamma correction is enabled using Subaddress 0x35, Bit 5. ED/HD Gamma Correction Curve A is programmed at Subaddress 0x44 to Subaddress 0x4D, and ED/HD Gamma Correction Curve B is programmed at Subaddress 0x4E to Subaddress 0x57.

SD gamma correction is enabled using Subaddress 0x88, Bit 6. SD Gamma Correction Curve A is programmed at Subaddress 0xA6 to Subaddress 0xAF, and SD Gamma Correction Curve B is programmed at Subaddress 0xB0 to Subaddress 0xB9.

Gamma correction is performed on the luma data only. The user can choose one of two correction curves, Curve A or Curve B. Only one of these curves can be used at a time. For ED/HD gamma correction, curve selection is controlled using Subaddress 0x35, Bit 4. For SD gamma correction, curve selection is controlled using Subaddress 0x88, Bit 7.

The shape of the gamma correction curve is controlled by defining the curve response at 10 different locations along the curve. By altering the response at these locations, the shape of the gamma correction curve can be modified. Between these points, linear interpolation is used to generate intermediate values. Considering the curve to have a total length of 256 points, the 10 programmable locations are at points 24, 32, 48, 64, 80, 96, 128, 160, 192, and 224. Locations 0, 16, 240, and 255 are fixed and cannot be changed.

From curve locations 16 to 240, the values at the programmable locations and, therefore, the response of the gamma correction curve, should be calculated to produce the following result:

$$x_{DESIRED} = (x_{INPUT})^{\gamma}$$

where:

 $x_{DESIRED}$ = desired gamma corrected output x_{INPUT} = linear input signal y = gamma correction factor

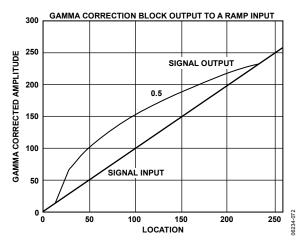


Figure 72. Signal Input (Ramp) and Signal Output for Gamma 0.5

To program the gamma correction registers, calculate the 10 programmable curve values using the following formula:

$$\gamma_n = \left(\left(\frac{n-16}{240-16} \right)^{\gamma} \times (240-16) \right) + 16$$

where:

 y_n = value to be written into the gamma correction register for point n on the gamma correction curve n = 24, 32, 48, 64, 80, 96, 128, 160, 192, or 224 <math>y = gamma correction factor

For example, setting $\gamma = 0.5$ for all programmable curve data points results in the following y_n values:

$$y_{24} = [(8/224)^{0.5} \times 224] + 16 = 58$$

$$y_{32} = [(16/224)^{0.5} \times 224] + 16 = 76$$

$$y_{48} = [(32/224)^{0.5} \times 224] + 16 = 101$$

$$y_{64} = [(48/224)^{0.5} \times 224] + 16 = 120$$

$$y_{80} = [(64/224)^{0.5} \times 224] + 16 = 136$$

$$y_{96} = [(80/224)^{0.5} \times 224] + 16 = 150$$

$$y_{128} = [(112/224)^{0.5} \times 224] + 16 = 174$$

$$y_{160} = [(144/224)^{0.5} \times 224] + 16 = 195$$

$$y_{192} = [(176/224)^{0.5} \times 224] + 16 = 214$$

$$y_{224} = [(208/224)^{0.5} \times 224] + 16 = 232$$

where the sum of each equation is rounded to the nearest integer.

The gamma curves in Figure 72 and Figure 73 are examples only; any user-defined curve in the range from 16 to 240 is acceptable.

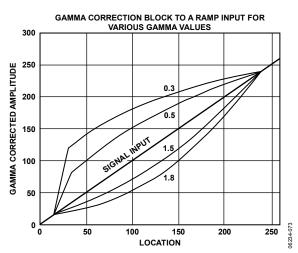


Figure 73. Signal Input (Ramp) and Selectable Output Curves

ED/HD SHARPNESS FILTER AND ADAPTIVE FILTER CONTROLS

Subaddress 0x40, Subaddress 0x58 to Subaddress 0x5D

There are three filter modes available on the ADV739x: sharpness filter mode and two adaptive filter modes.

ED/HD Sharpness Filter Mode

To enhance or attenuate the Y signal in the frequency ranges shown in Figure 74, the ED/HD sharpness filter must be enabled (Subaddress 0x31, Bit 7 = 1) and the ED/HD adaptive filter must be disabled (Subaddress 0x35, Bit 7 = 0).

To select one of the 256 individual responses, the corresponding gain values, ranging from –8 to +7 for each filter, must be programmed into the ED/HD sharpness filter gain register at Subaddress 0x40.

ED/HD Adaptive Filter Mode

In ED/HD adaptive filter mode, the following registers are used:

- ED/HD Adaptive Filter Threshold A
- ED/HD Adaptive Filter Threshold B
- ED/HD Adaptive Filter Threshold C
- ED/HD Adaptive Filter Gain 1
- ED/HD Adaptive Filter Gain 2
- ED/HD Adaptive Filter Gain 3
- ED/HD sharpness filter gain register

To activate the adaptive filter control, the ED/HD sharpness filter and the ED/HD adaptive filter must be enabled (Subaddress 0x31, Bit 7 = 1, and Subaddress 0x35, Bit 7 = 1, respectively).

The derivative of the incoming signal is compared to the three programmable threshold values: ED/HD Adaptive Filter Threshold A, Threshold B, and Threshold C (Subaddress 0x5B, Subaddress 0x5C, and Subaddress 0x5D). The recommended threshold range is 16 to 235, although any value in the range of 0 to 255 can be used.

The edges can then be attenuated with the settings in the ED/HD Adaptive Filter Gain 1, Gain 2, and Gain 3 registers (Subaddress 0x58, Subaddress 0x59 and Subaddress 0x5A), and the ED/HD sharpness filter gain register (Subaddress 0x40).

There are two adaptive filter modes available. The mode is selected using the ED/HD adaptive filter mode control (Subaddress 0x35, Bit 6):

- Mode A is used when the ED/HD adaptive filter mode control is set to 0. In this case, Filter B (LPF) is used in the adaptive filter block. In addition, only the programmed values for Gain B in the ED/HD sharpness filter gain register and ED/HD Adaptive Filter Gain 1, Gain 2, and Gain 3 registers are applied when needed. The Gain A values are fixed and cannot be changed.
- Mode B is used when ED/HD adaptive filter mode control is set to 1. In this mode, a cascade of Filter A and Filter B is used. Both settings for Gain A and Gain B in the ED/HD sharpness filter gain register and ED/HD Adaptive Filter Gain 1, Gain 2, and Gain 3 registers become active when needed.

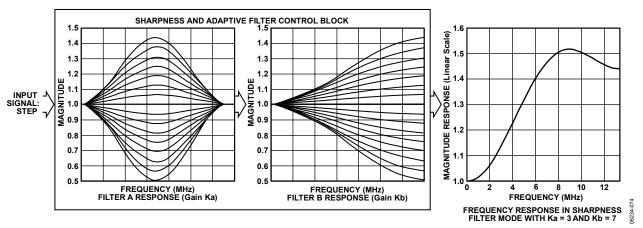


Figure 74. ED/HD Sharpness and Adaptive Filter Control Block

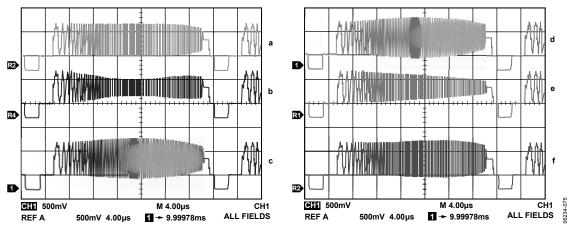


Figure 75. ED/HD Sharpness Filter Control with Different Gain Settings for ED/HD Sharpness Filter Gain Values

ED/HD SHARPNESS FILTER AND ADAPTIVE FILTER APPLICATION EXAMPLES

Sharpness Filter Application

The ED/HD sharpness filter can be used to enhance or attenuate the Y video output signal. The register settings in Table 46 were used to achieve the results shown in Figure 75. Input data was generated by an external signal source.

Table 46. ED/HD Sharpness Control

1 more 10, 22, 112 0 mm prives 00 mrei			
Subaddress	Register Setting	Reference ¹	
0x00	0xFC		
0x01	0x10		
0x02	0x20		
0x30	0x00		
0x31	0x81		
0x40	0x00	a	
0x40	0x08	b	
0x40	0x04	С	
0x40	0x40	d	
0x40	0x80	е	
0x40	0x22	f	

¹ See Figure 75.

Adaptive Filter Control Application

The register settings in Table 47 are used to obtain the results shown in Figure 77, that is, to remove the ringing on the input Y signal, as shown in Figure 76. Input data is generated by an external signal source.

Table 47. Register Settings for Figure 77

Subaddress	Register Setting	
0x00	0xFC	
0x01	0x38	
0x02	0x20	
0x30	0x00	
0x31	0x81	
0x35	0x80	
0x40	0x00	
0x58	0xAC	
0x59	0x9A	
0x5A	0x88	
0x5B	0x28	
0x5C	0x3F	
0x5D	0x64	

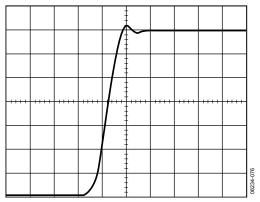


Figure 76. Input Signal to ED/HD Adaptive Filter

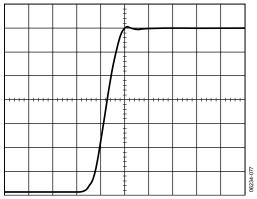


Figure 77. Output Signal from ED/HD Adaptive Filter (Mode A)

When changing the adaptive filter mode to Mode B (Subaddress 0x35, Bit 6), the output shown in Figure 78 can be obtained.

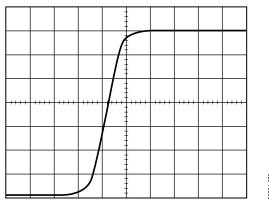


Figure 78. Output Signal from ED/HD Adaptive Filter (Mode B)

SD DIGITAL NOISE REDUCTION Subaddress 0xA3 to Subaddress 0xA5

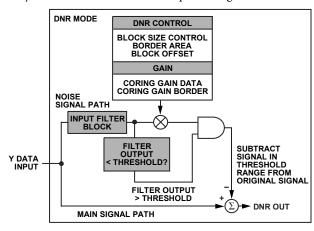
Digital noise reduction (DNR) is applied to the Y data only. A filter block selects the high frequency, low amplitude components of the incoming signal (DNR input select). The absolute value of the filter output is compared to a programmable threshold value (DNR threshold control). There are two DNR modes available: DNR mode and DNR sharpness mode.

In DNR mode, if the absolute value of the filter output is smaller than the threshold, it is assumed to be noise. A programmable amount (coring gain border, coring gain data) of this noise signal is subtracted from the original signal. In DNR sharpness mode, if the absolute value of the filter output is less than the programmed threshold, it is assumed to be noise as before. However, if the level exceeds the threshold, now being identified as a valid signal, a fraction of the signal (coring gain border, coring gain data) is added to the original signal to boost high frequency components and sharpen the video image.

In MPEG systems, it is common to process the video information in blocks of 8 pixels \times 8 pixels for MPEG2 systems, or 16 pixels \times 16 pixels for MPEG1 systems (block size control). DNR can be applied to the resulting block transition areas known to contain noise. Generally, the block transition area contains two pixels. It is possible to define this area to contain four pixels (border area).

It is also possible to compensate for variable block positioning or differences in YCrCb pixel timing with the use of the DNR block offset.

The digital noise reduction registers are three 8-bit registers. They are used to control the DNR processing.



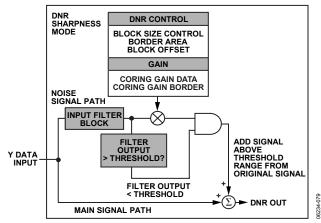


Figure 79. SD DNR Block Diagram

Coring Gain Border—Subaddress 0xA3, Bits[3:0]

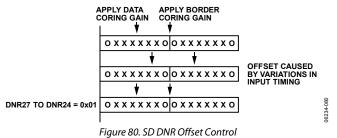
These four bits are assigned to the gain factor applied to border areas. In DNR mode, the range of gain values is 0 to 1 in increments of 1/8. This factor is applied to the DNR filter output that lies below the set threshold range. The result is then subtracted from the original signal.

In DNR sharpness mode, the range of gain values is 0 to 0.5 in increments of 1/16. This factor is applied to the DNR filter output that lies above the threshold range. The result is added to the original signal.

Coring Gain Data—Subaddress 0xA3, Bits[7:4]

These four bits are assigned to the gain factor applied to the luma data inside the MPEG pixel block. In DNR mode, the range of gain values is 0 to 1 in increments of 1/8. This factor is applied to the DNR filter output that lies below the set threshold range. The result is then subtracted from the original signal.

In DNR sharpness mode, the range of gain values is 0 to 0.5 in increments of 1/16. This factor is applied to the DNR filter output that lies above the threshold range. The result is added to the original signal.



DNR Threshold—Subaddress 0xA4, Bits[5:0]

These six bits are used to define the threshold value in the range of 0 to 63. The range is an absolute value.

Border Area—Subaddress 0xA4, Bit 6

When this bit is set to Logic 1, the block transition area can be defined to consist of four pixels. If this bit is set to Logic 0, the border transition area consists of two pixels, where one pixel refers to two clock cycles at 27 MHz.

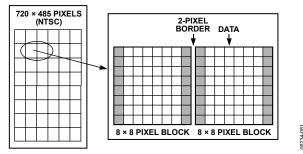


Figure 81. SD DNR Border Area

Block Size—Subaddress 0xA4, Bit 7

This bit is used to select the size of the data blocks to be processed. Setting the block size control function to Logic 1 defines a 16 pixel \times 16 pixel data block, and Logic 0 defines an 8 pixel \times 8 pixel data block, where one pixel refers to two clock cycles at 27 MHz.

DNR Input Select—Subaddress 0xA5, Bits[2:0]

These three bits are assigned to select the filter that is applied to the incoming Y data. The signal that lies in the pass band of the selected filter is the signal processed by DNR. Figure 82 shows the filter responses selectable with this control.

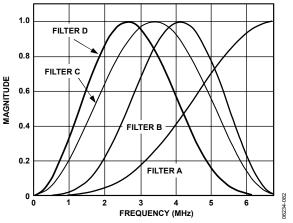


Figure 82. SD DNR Input Select

DNR Mode—Subaddress 0xA5, Bit 4

This bit controls the DNR mode selected. Logic 0 selects DNR mode; Logic 1 selects DNR sharpness mode.

DNR works on the principle of defining low amplitude, high frequency signals as probable noise and subtracting this noise from the original signal.

In DNR mode, it is possible to subtract a fraction of the signal that lies below the set threshold, assumed to be noise, from the original signal. The threshold is set in DNR Register 1.

When DNR sharpness mode is enabled, it is possible to add a fraction of the signal that lies above the set threshold to the original signal because this data is assumed to be valid data and not noise. The overall effect is that the signal is boosted (similar to using the extended SSAF filter).

Block Offset Control—Subaddress 0xA5, Bits[7:4]

Four bits are assigned to this control that allows a shift in the data block of 15 pixels maximum. The coring gain positions are fixed. The block offset shifts the data in steps of one pixel such that the border coring gain factors can be applied at the same position regardless of variations in input timing of the data.

SD ACTIVE VIDEO EDGE CONTROL

Subaddress 0x82, Bit 7

The ADV739x is able to control fast rising and falling signals at the start and end of active video to minimize ringing.

When the active video edge control feature is enabled (Subaddress 0x82, Bit 7 = 1), the first three pixels and the last three pixels of the active video on the luma channel are scaled so that maximum transitions on these pixels are not possible.

At the start of active video, the first three pixels are multiplied by 1/8, 1/2, and 7/8, respectively. Approaching the end of active video, the last three pixels are multiplied by 7/8, 1/2, and 1/8, respectively. All other active video pixels pass through unprocessed.

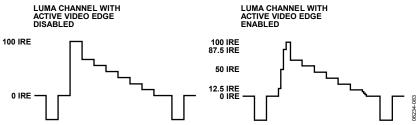


Figure 83. Example of Active Video Edge Functionality

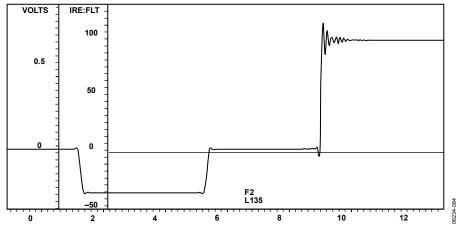


Figure 84. Example of Video Output with Subaddress 0x82, Bit 7 = 0

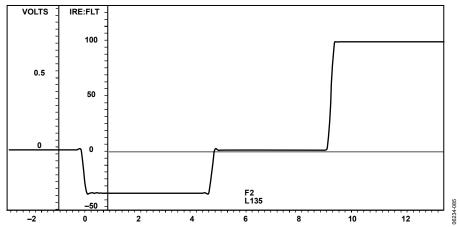


Figure 85. Example of Video Output with Subaddress 0x82, Bit 7 = 1

EXTERNAL HORIZONTAL AND VERTICAL SYNCHRONIZATION CONTROL

For timing synchronization purposes, the ADV739x is able to accept either EAV/SAV time codes embedded in the input pixel data or external synchronization signals provided on the \overline{HSYNC} and \overline{VSYNC} pins (see Table 48). It is also possible to output synchronization signals on the \overline{HSYNC} and \overline{VSYNC} pins (see Table 49 to Table 51).

Table 48. Timing Synchronization Signal Input Options

Signal	Pin	Condition
SD HSYNC In	HSYNC	SD Slave Timing Mode 1, Mode 2, or Mode 3 Selected (Subaddress 0x8A[2:0]). ¹
SD VSYNC/FIELD In	VSYNC	SD Slave Timing Mode 1, Mode 2, or Mode 3 Selected (Subaddress 0x8A[2:0]). ¹
ED/HD HSYNC In	HSYNC	ED/HD Timing Synchronization Inputs Enabled (Subaddress $0x30$, Bit $2 = 0$).
ED/HD VSYNC/FIELD In	VSYNC	ED/HD Timing Synchronization Inputs Enabled (Subaddress $0x30$, Bit $2 = 0$).

 $^{^{1}}$ SD and ED/HD timing synchronization outputs must also be disabled (Subaddress 0x02[7:6] = 00).

Table 49. Timing Synchronization Signal Output Options

Signal	Pin	Condition
SD HSYNC Out	HSYNC	SD Timing Synchronization Outputs enabled (Subaddress 0x02, Bit 6 = 1).1
SD VSYNC/FIELD Out	VSYNC	SD Timing Synchronization Outputs enabled (Subaddress 0x02, Bit 6 = 1).1
ED/HD HSYNC Out	HSYNC	ED/HD Timing Synchronization Outputs enabled (Subaddress $0x02$, Bit $7 = 1$). ²
ED/HD VSYNC/FIELD Out	VSYNC	ED/HD Timing Synchronization Outputs enabled (Subaddress 0x02, Bit 7 = 1). ²

 $^{^{1}}$ ED/HD timing synchronization outputs must also be disabled (Subaddress 0x02, Bit 7 = 0).

Table 50. HSYNC Output Control¹

ED/HD Input Sync Format (0x30, Bit 2)	ED/HD HSYNC Control (0x34, Bit 1)	ED/HD Sync Output Enable (0x02, Bit 7)	SD Sync Output Enable (0x02, Bit 6)	Signal on HSYNC Pin	Duration
х	х	0	0	Tristate.	_
х	х	0	1	Pipelined SD HSYNC.	See Error! Reference source not found
0	0	1	х	Pipelined ED/HD HSYNC.	As per HSYNC timing.
1	0	1	x	Pipelined ED/HD HSYNC based on AV Code H bit.	Same as line blanking interval.
х	1	1	х	Pipelined ED/HD HSYNC based on horizontal counter.	Same as embedded HSYNC.

¹ In all ED/HD standards where there is a HSYNC output, the start of the HSYNC pulse is aligned with the falling edge of the embedded HSYNC in the output video.

Table 51. VSYNC Output Control¹

ED/HD Input Sync Format (0x30, Bit 2)	ED/HD VSYNC Control (0x34, Bit 2)	ED/HD Sync Output Enable (0x02, Bit 7)	SD Sync Output Enable (0x02, Bit 6)	Video Standard	Signal on VSYNC Pin	Duration
Х	х	0	0	х	Tristate.	-
Х	x	0	1	Interlaced	Pipelined SD VSYNC/Field.	See Error! Reference source not found
0	0	1	x	х	Pipelined ED/HD VSYNC or field signal.	As per VSYNC or Field signal timing.
1	0	1	х	All HD interlaced standards	Pipelined Field signal based on AV Code F bit.	Field.
1	0	1	х	All ED/HD progressive standards	Pipelined VSYNC based on AV Code V bit.	Vertical blanking interval.
х	1	1	x	All ED/HD standards except 525p	Pipelined ED/HD VSYNC based on vertical counter.	Aligned with serration lines.
х	1	1	x	525p	Pipelined ED/HD VSYNC based on vertical counter.	Vertical blanking interval.

 $^{^{1}}$ In all ED/HD standards where there is a $\overline{\text{VSYNC}}$ output, the start of the $\overline{\text{VSYNC}}$ pulse is aligned with the falling edge of the embedded $\overline{\text{VSYNC}}$ in the output video.

² ED/HD timing synchronization inputs must also be disabled, that is, embedded EAV/SAV timing codes must be enabled (Subaddress 0x30, Bit 2 = 1).

LOW POWER MODE

Subaddress 0x0D, Bits[2:0]

For power sensitive applications, the ADV739x supports an Analog Devices, Inc. proprietary low power mode of operation. To utilize this low power mode, the DACs must be operating in full-drive mode ($R_{\text{SET}}=510~\Omega,\,R_{\text{L}}=37.5~\Omega).$ Low power mode is not available in low drive mode ($R_{\text{SET}}=4.12~k\Omega,\,R_{\text{L}}=300~\Omega).$ Low power mode can be independently enabled or disabled on each DAC using Subaddress 0x0D, Bits[2:0]. Low power mode is disabled by default on all DACs.

In low power mode, DAC current consumption is content dependent, and on a typical video stream, it can be reduced by as much as 40%. For applications requiring the highest possible video performance, low power mode should be disabled.

CABLE DETECTION

Subaddress 0x10, Bits[1:0]

The ADV739x includes an Analog Devices, Inc. proprietary cable detection feature.

The cable detection feature is available on DAC 1 and DAC 2 when operating in full-drive mode ($R_{SET}=510~\Omega,~R_L=37.5~\Omega,$ assuming a connected cable). The feature is not available in low-drive mode ($R_{SET}=4.12~k\Omega,~R_L=300~\Omega$). For a DAC to be monitored, the DAC must be powered up in Subaddress 0x00.

The cable detection feature can be used with all SD, ED, and HD video standards. It is available for all output configurations, that is, CVBS, YC, YPrPb, and RGB output configurations.

For CVBS/YC output configurations, both DAC 1 and DAC 2 are monitored, that is, the CVBS and YC luma outputs are monitored. For YPrPb and RGB output configurations, only DAC 1 is monitored, that is, the luma or green output is monitored.

Once per frame, the ADV739x monitors DAC 1 and/or DAC 2, updating Subaddress 0x10, Bit 0 and/or Bit 1, respectively. If a cable is detected on one of the DACs, the relevant bit is set to 0. If not, the bit is set to 1.

DAC AUTO POWER-DOWN

Subaddress 0x10, Bit 4

For power sensitive applications, a DAC auto power-down feature can be enabled using Subaddress 0x10, Bit 4. This feature is only available when the cable detection feature is enabled.

With this feature enabled, the cable detection circuitry monitors DAC 1 and/or DAC 2 once per frame, and if they are unconnected, automatically powers down some or all of the DACs. Which DAC or DACs are powered down depends on the selected output configuration.

For CVBS/YC output configurations, if DAC 1 is unconnected, only DAC 1 powers down. If DAC 2 is unconnected, DAC 2 and DAC 3 power down.

For YPrPb and RGB output configurations, if DAC 1 is unconnected, all three DACs are powered down. DAC 2 is not monitored for YPrPb and RGB output configurations.

Once per frame, DAC 1 and/or DAC 2 are monitored. If a cable is detected, the appropriate DAC or DACs remain powered up for the duration of the frame. If no cable is detected, the appropriate DAC or DACs power down until the next frame, when the process is repeated.

PIXEL AND CONTROL PORT READBACK

Subaddress 0x13, Subaddress 0x14, Subaddress 0x16

The ADV739x supports the readback of most digital inputs via the I²C/SPI MPU port. This feature is useful for board-level connectivity testing with upstream devices.

The pixel port (P[15:0] or P[7:0]), HSYNC, VSYNC, and SFL/MISO are available for readback via the MPU port. The readback registers are located at Subaddress 0x13, Subaddress 0x14, and Subaddress 0x16.

When using this feature, a clock signal should be applied to the CLKIN pin to register the levels applied to the input pins.

The SD input mode (Subaddress 0x01, Bits[6:4] = 000) must be selected when using this feature.

RESET MECHANISMS

Subaddress 0x17, Bit 1

A hardware reset is activated with a high-to-low transition on the \overline{RESET} pin in accordance with the timing specifications. This resets all registers to their default values. After a hardware reset, the MPU port is configured for I²C operation. For correct device operation, a hardware reset is necessary after power-up.

The ADV739x also has a software reset accessible via the I^2C/SPI MPU port. A software reset is activated by writing a 1 to Subaddress 0x17, Bit 1. This resets all registers to their default values. This bit is self-clearing, that is, after a 1 has been written to the bit, the bit automatically returns to 0.

When operating in SPI mode, a software reset does not cause the device to revert to I²C mode. For this to occur, a hardware reset via the RESET pin or a power-down needs to occur.

A hardware reset is necessary after power-up for correct device operation. If no hardware reset functionality is required by the application, the RESET pin can be connected to a RC network to provide the hardware reset necessary after power-up. After power-up, the time constant of the RC network holds the RESET pin low for long enough to cause a reset to take place. All subsequent resets can be done via software.

PRINTED CIRCUIT BOARD LAYOUT AND DESIGN

DAC CONFIGURATIONS

The ADV739x contains three DACs. All three DACs can be configured to operate in full-drive mode. Full-drive mode is defined as 34.7 mA full-scale current into a 37.5 Ω load, R_L. Full-drive is the recommended mode of operation for the DACs.

Alternatively, all three DACs can be configured to operate in low drive mode. Low drive mode is defined as 4.33 mA full-scale current into a 300 Ω load, R_L

The ADV739x contains a R_{SET} pin. A resistor connected between the R_{SET} pin and AGND is used to control the full-scale output current and, therefore, the output voltage levels of DAC 1, DAC 2, and DAC 3. For full-drive operation, R_{SET} must have a value of 510 Ω and RL must have a value of 37.5 Ω . For low drive operation, R_{SET} must have a value of 4.12 k Ω , and R_L must have a value of 300 Ω .

The resistor connected to the R_{SET} pin should have a 1% tolerance.

The ADV739x contains a compensation pin, COMP. A 2.2 nF compensation capacitor should be connected from the COMP pin to V_{AA}.

VIDEO OUTPUT BUFFER AND OPTIONAL **OUTPUT FILTER**

An output buffer is necessary on any DAC that operates in low drive mode ($R_{SET} = 4.12 \text{ k}\Omega$, $R_L = 300 \Omega$). Analog Devices Inc. produces a range of op amps suitable for this application, for example, the AD8061. For more information about line driver buffering circuits, see the relevant op amp data sheet.

An optional reconstruction (anti-imaging) low-pass filter (LPF) may be required on the ADV739x DAC outputs. The filter specifications vary with the application. The use of $16 \times (SD)$, 8× (ED), or 4× (HD) oversampling can remove the requirement for a reconstruction filter altogether.

For applications requiring an output buffer and reconstruction filter, the ADA4430-1 and ADA4411-3 integrated video filter buffers should be considered.

Table 52. ADV739x Output Rates

Input Mode (0x01, Bits[6:4])	Oversampling	Output Rate (MHz)				
SD	Off	27	(2×)			
	On	108	(8×)			
	On	216	(16×)			
ED	Off	27	(1×)			
	On	108	(4×)			
	On	216	(8×)			
HD	Off	74.25	(1×)			
	On	148.5	(2×)			
	On	297	(4×)			

Table 53. Output Filter Requirements

Application	Oversampling	Cutoff Frequency (MHz)	Attenuation -50 dB @ (MHz)
SD	2×	> 6.5	20.5
	8×	> 6.5	101.5
	16×	> 6.5	209.5
ED	1×	> 12.5	14.5
	4×	> 12.5	95.5
	8×	> 12.5	203.5
HD	1×	> 30	44.25
	2×	> 30	118.5
	4×	> 30	267

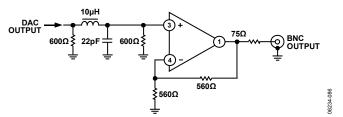


Figure 86. Example of Output Filter for SD, 16× Oversampling

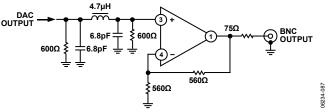


Figure 87. Example of Output Filter for ED, 8× Oversampling

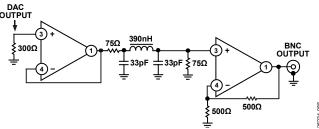


Figure 88. Example of Output Filter for HD, 4× Oversampling

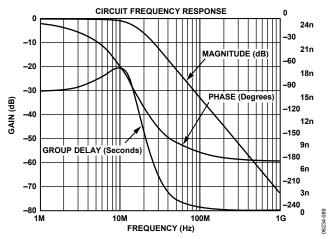


Figure 89. Output Filter Plot for SD, 16× Oversampling

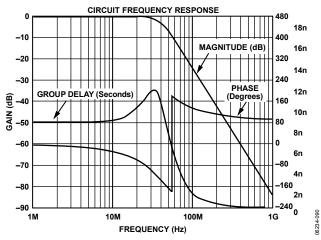


Figure 90. Output Filter Plot for ED, 8× Oversampling

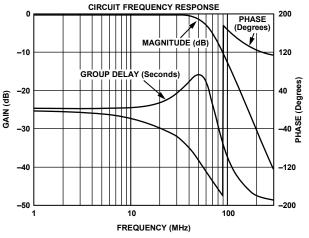


Figure 91. Output Filter Plot for HD, 4× Oversampling

PRINTED CIRCUIT BOARD (PCB) LAYOUT

The ADV739x is a highly integrated circuit containing both precision analog and high speed digital circuitry. It has been designed to minimize interference effects on the integrity of the analog circuitry by the high speed digital circuitry. It is imperative that these same design and layout techniques be applied to the system-level design so that optimal performance is achieved.

The layout should be optimized for lowest noise on the ADV739x power and ground planes by shielding the digital inputs and providing good power supply decoupling.

It is recommended to use a 4-layer printed circuit board with ground and power planes separating the signal trace layer and the solder side layer.

Component Placement

Component placement should be carefully considered to separate noisy circuits, such as clock signals and high speed digital circuitry from analog circuitry.

The external loop filter components and components connected to the COMP and R_{SET} pins should be placed as close as possible to and on the same side of the PCB as the ADV739x. Adding vias to the PCB to get the components closer to the ADV739x is not recommended.

It is recommended that the ADV739x be placed as close as possible to the output connector, with the DAC output traces as short as possible.

The termination resistors on the DAC output traces should be placed as close as possible to and on the same side of the PCB as the ADV739x. The termination resistors should overlay the PCB ground plane.

External filter and buffer components connected to the DAC outputs should be placed as close as possible to the ADV739x to minimize the possibility of noise pickup from neighboring circuitry, and to minimize the effect of trace capacitance on output bandwidth. This is particularly important when operating in low drive mode ($R_{\text{SET}} = 4.12 \text{ k}\Omega$, $R_{\text{L}} = 300 \Omega$).

Power Supplies

It is recommended that a separate regulated supply be provided for each power domain (V_{AA} , V_{DD} , V_{DD_IO} , and PV_{DD}). For optimal performance, linear regulators rather than switch mode regulators should be used. If switch mode regulators must be used, care must be taken with regard to the quality of the output voltage in terms of ripple and noise. This is particularly true for the V_{AA} and PV_{DD} power domains. Each power supply should be individually connected to the system power supply at a single point through a suitable filtering device, such as a ferrite bead.

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Power Supply Decoupling

It is recommended that each power supply pin be decoupled with 10 nF and 0.1 μF ceramic capacitors. The $V_{AA},\,PV_{DD},\,V_{DD_IO},$ and both V_{DD} pins should be individually decoupled to ground. The decoupling capacitors should be placed as close as possible to the ADV739x with the capacitor leads kept as short as possible to minimize lead inductance.

A 1 μF tantalum capacitor is recommended across the V_{AA} supply in addition to the 10 nF and 0.1 μF ceramic capacitors.

Power Supply Sequencing

The ADV739x is robust to all power supply sequencing combinations. Any particular sequence can be used.

Digital Signal Interconnect

The digital signal traces should be isolated as much as possible from the analog outputs and other analog circuitry. Digital signal traces should not overlay the V_{AA} or PV_{DD} power planes.

Due to the high clock rates used, avoid long clock traces to the ADV739x to minimize noise pickup.

Any pull-up termination resistors for the digital inputs should be connected to the $V_{\rm DD}$ power supply.

Any unused digital inputs should be tied to ground.

Analog Signal Interconnect

DAC output traces should be treated as transmission lines with appropriate measures taken to ensure optimal performance (for example, impedance matched traces). The DAC output traces should be kept as short as possible. The termination resistors on the DAC output traces should be placed as close as possible to and on the same side of the PCB as the ADV739x.

To avoid crosstalk between the DAC outputs, it is recommended that as much space as possible be left between the traces connected to the DAC output pins. Adding ground traces between the DAC output traces is also recommended.

TYPICAL APPLICATION CIRCUIT

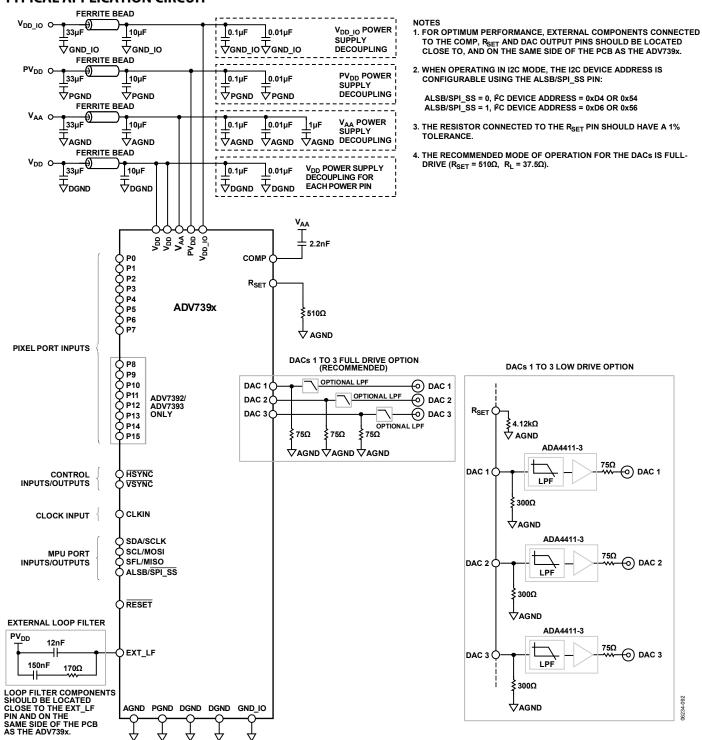


Figure 92. ADV739x Typical Application Circuit

AGND PGND DGND GND_IO

APPENDIX 1—COPY GENERATION MANAGEMENT SYSTEM

SD CGMS

Subaddress 0x99 to Subaddress 0x9B

The ADV739x supports copy generation management system (CGMS) that conforms to the EIAJ CPR-1204 and ARIB TR-B15 standards. CGMS data is transmitted on Line 20 of the odd fields and Line 283 of even fields. Subaddress 0x99, Bits[6:5] control whether CGMS data is output on odd or even fields or both.

SD CGMS data can only be transmitted when the ADV739x is configured in NTSC mode. The CGMS data is 20 bits long. The CGMS data is preceded by a reference pulse of the same amplitude and duration as a CGMS bit (see Figure 93).

FD CGMS

Subaddress 0x41 to Subaddress 0x43 Subaddress 0x5E to Subaddress 0x6E

525p

The ADV739x supports copy generation management system (CGMS) in 525p mode in accordance with EIAJ CPR-1204-1.

When ED CGMS is enabled (Subaddress 0x32, Bit 6 = 1), 525p CGMS data is inserted on Line 41. The 525p CGMS data registers are at Subaddress 0x41, Subaddress 0x42, and Subaddress 0x43.

The ADV739x also supports CGMS Type B packets in 525p mode in accordance with CEA-805-A.

When ED CGMS Type B is enabled (Subaddress 0x5E, Bit 0 = 1), 525p CGMS Type B data is inserted on Line 40. The 525p CGMS Type B data registers are at Subaddress 0x5E to Subaddress 0x6E.

625p

The ADV739x supports copy generation management system (CGMS) in 625p mode in accordance with IEC 62375 (2004).

When ED CGMS is enabled (Subaddress 0x32, Bit 6 = 1), 625p CGMS data is inserted on Line 43. The 625p CGMS data registers are at Subaddress 0x42 and Subaddress 0x43.

HD CGMS

Subaddress 0x41 to Subaddress 0x43 Subaddress 0x5E to Subaddress 0x6E

The ADV739x supports copy generation management system (CGMS) in HD mode (720p and 1080i) in accordance with EIAI CPR-1204-2.

When HD CGMS is enabled (Subaddress 0x32, Bit 6 = 1), 720p CGMS data is applied to Line 24 of the luminance vertical blanking interval.

When HD CGMS is enabled (Subaddress 0x32, Bit 6 = 1), 1080i CGMS data is applied to Line 19 and Line 582 of the luminance vertical blanking interval.

The HD CGMS data registers are at Subaddress 0x41, Subaddress 0x42, and Subaddress 0x43.

The ADV739x also supports CGMS Type B packets in HD mode (720p and 1080i) in accordance with CEA-805-A.

When HD CGMS Type B is enabled (Subaddress 0x5E, Bit 0 = 1), 720p CGMS data is applied to Line 23 of the luminance vertical blanking interval.

When HD CGMS Type B is enabled (Subaddress 0x5E, Bit 0 = 1), 1080i CGMS data is applied to Line 18 and Line 581 of the luminance vertical blanking interval.

The HD CGMS Type B data registers are at Subaddress 0x5E to Subaddress 0x6E.

CGMS CRC FUNCTIONALITY

If SD CGMS CRC (Subaddress 0x99, Bit 4) or ED/HD CGMS CRC (Subaddress 0x32, Bit 7) is enabled, the upper six CGMS data bits (C19 to C14) that comprise the 6-bit CRC check sequence are automatically calculated on the ADV739x. This calculation is based on the lower 14 bits (C13 to C0) of the data in the CGMS data registers, and the result is output with the remaining 14 bits to form the complete 20 bits of the CGMS data. The calculation of the CRC sequence is based on the polynomial $x^6 + x + 1$ with a preset value of 111111.

If SD CGMS CRC or ED/HD CGMS CRC is disabled, all 20 bits (C19 to C0) are output directly from the CGMS registers (CRC must be calculated by the user manually).

If ED/HD CGMS Type B CRC (Subaddress 0x5E, Bit 1) is enabled, the upper six CGMS Type B data bits (P122 to P127) that comprise the 6-bit CRC check sequence are automatically calculated on the ADV739x. This calculation is based on the lower 128 bits (H0 to H5 and P0 to P121) of the data in the CGMS Type B data registers. The result is output with the remaining 128 bits to form the complete 134 bits of the CGMS Type B data. The calculation of the CRC sequence is based on the polynomial $x^6 + x + 1$ with a preset value of 111111.

If ED/HD CGMS Type B CRC is disabled, all 134 bits (H0 to H5 and P0 to P127) are output directly from the CGMS Type B registers (CRC must be calculated by the user manually).

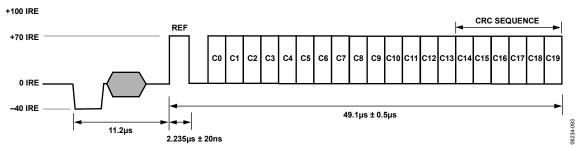


Figure 93. Standard Definition CGMS Waveform

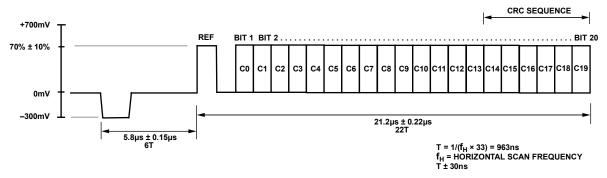


Figure 94. Enhanced Definition (525p) CGMS Waveform

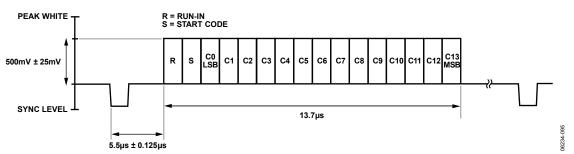


Figure 95. Enhanced Definition (625p) CGMS Waveform

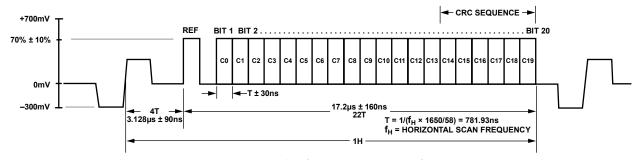


Figure 96. High Definition (720p) CGMS Waveform

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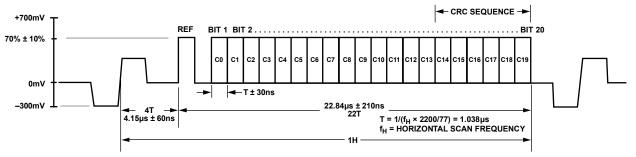


Figure 97. High Definition (1080i) CGMS Waveform

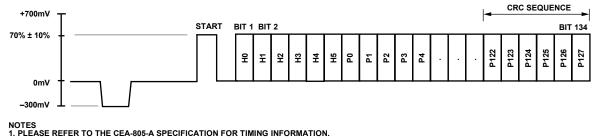


Figure 98. Enhanced Definition (525p) CGMS Type B Waveform

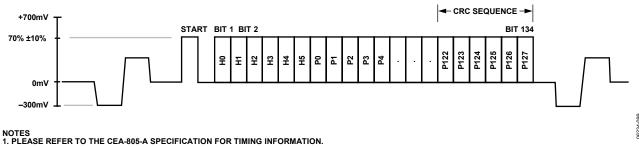


Figure 99. High Definition (720p and 1080i) CGMS Type B Waveform

APPENDIX 2-SD WIDE SCREEN SIGNALING

Subaddress 0x99, Subaddress 0x9A, Subaddress 0x9B

The ADV739x supports wide screen signaling (WSS) conforming to the ETSI 300 294 standard. WSS data is transmitted on Line 23. WSS data can only be transmitted when the device is configured in PAL mode. The WSS data is 14 bits long. The function of each of these bits is shown in Table 54. The WSS data is preceded by a run-in sequence and a start code

(see Figure 100). The latter portion of Line 23 (after 42.5 μ s from the falling edge of \overline{HSYNC}) is available for the insertion of video. WSS data transmission on Line 23 can be enabled using Subaddress 0x99, Bit 7. It is possible to blank the WSS portion of Line 23 with Subaddress 0xA1, Bit 7.

Table 54. Function of WSS Bits

	Bit Number														
Bit Description	13	12	11	10	9	8	7	6	5	4	3	2	1	0	Setting
Aspect Ratio, Format, Position											1	0	0	0	4:3, full format, N/A
											0	0	0	1	14:9, letterbox, center
											0	0	1	0	14:9, letterbox, top
											1	0	1	1	16:9, letterbox, center
											0	1	0	0	16:9, letterbox, top
											1	1	0	1	>16:9, letterbox, center
											1	1	1	0	14:9, full format, center
											0	1	1	1	16:0, N/A, N/A
Mode										0					Camera mode
										1					Film mode
Color Encoding									0						Normal PAL
									1						Motion Adaptive ColorPlus
Helper Signals								0							Not present
								1							Present
Reserved							0								
Teletext Subtitles						0									No
						1									Yes
Open Subtitles				0	0										No
				0	1										Subtitles in active image area
				1	0										Subtitles out of active image area
				1	1										Reserved
Surround Sound			0												No
			1												Yes
Copyright		0													No copyright asserted or unknown
		1													Copyright asserted
Copy Protection	0														Copying not restricted
	1														Copying restricted

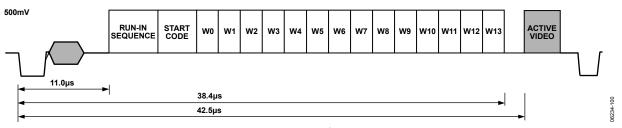


Figure 100. WSS Waveform Diagram

APPENDIX 3-SD CLOSED CAPTIONING

Subaddress 0x91 to Subaddress 0x94

The ADV739x supports closed captioning conforming to the standard television synchronizing waveform for color transmission. When enabled, closed captioning is transmitted during the blanked active line time of Line 21 of the odd fields and Line 284 of the even fields. Closed captioning can be enabled using Subaddress 0x83, Bits[6:5].

Closed captioning consists of a 7-cycle sinusoidal burst that is frequency and phase-locked to the caption data. After the clock run-in signal, the blanking level is held for two data bits and is followed by a Logic 1 start bit. Sixteen bits of data follow the start bit. The data consists of two 8-bit bytes (seven data bits, and one odd parity bit per byte). The data for these bytes is stored in SD closed captioning registers (Subaddress 0x93 to Subaddress 0x94).

The ADV739x also supports the extended closed captioning operation, which is active during even fields and encoded on Line 284. The data for this operation is stored in SD closed captioning registers (Subaddress 0x91 to Subaddress 0x92).

The ADV739x automatically generates all clock run-in signals and timing that support closed captioning on Line 21 and Line 284.

All pixels inputs are ignored on Line 21 and Line 284 if closed captioning is enabled.

The FCC Code of Federal Regulations (CFR) Title 47 Section 15.119 and EIA-608 describe the closed captioning information for Line 21 and Line 284.

The ADV739x uses a single buffering method. This means that the closed captioning buffer is only 1-byte deep. Therefore, there is no frame delay in outputting the closed captioning data unlike other 2-byte deep buffering systems. The data must be loaded one line before it is output on Line 21 and Line 284. A typical implementation of this method is to use \$\overline{VSYNC}\$ to interrupt a microprocessor, which in turn loads the new data (2 bytes) in every field. If no new data is required for transmission, 0s must be inserted in both data registers; this is called nulling. It is also important to load control codes, all of which are double bytes, on Line 21. Otherwise, a TV does not recognize them. If there is a message such as "Hello World" that has an odd number of characters, it is important to add a blank character at the end to make sure that the end-of-caption, 2-byte control code lands in the same field.

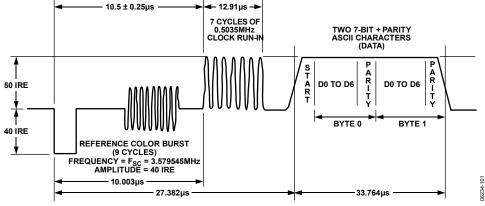


Figure 101. SD Closed Captioning Waveform, NTSC

APPENDIX 4—INTERNAL TEST PATTERN GENERATION

SD TEST PATTERNS

The ADV739x is able to generate SD color bar and black bar test patterns.

The register settings in Table 55 are used to generate an SD NTSC 75% color bar test pattern. All other registers are set as normal/default. Component YPrPb output is available on DAC 1 to DAC 3. Upon power-up, the subcarrier frequency registers default to the appropriate values for NTSC.

Table 55. SD NTSC Color Bar Test Pattern Register Writes

Subaddress	Setting
0x00	0x1C
0x82	0xC9
0x84	0x40

For CVBS and S-Video (Y/C) output, 0xCB instead of 0xC9 should be written to Subaddress 0x82.

For component RGB output rather than YPrPb output, 0 should be written to Subaddress 0x02, Bit 5.

To generate an SD NTSC black bar test pattern, the same settings shown in Table 55 should be used with an additional write of 0x24 to Subaddress 0x02.

For PAL output of either test pattern, the same settings are used, except that Subaddress 0x80 is programmed to 0x11 and the subcarrier frequency (F_{SC}) registers are programmed as shown in Table 56.

Table 56. PAL F_{SC} Register Writes

Subaddress	Description	Setting
0x8C	F _{SC} 0	0xCB
0x8D	F _{sc} 1	0x8A
0x8E	F _{SC} 2	0x09
0x8F	Fsc3	0x2A

Note that when programming the F_{SC} registers, the user must write the values in the sequence $F_{SC}0$, $F_{SC}1$, $F_{SC}2$, $F_{SC}3$. The full F_{SC} value to be written is only accepted after the $F_{SC}3$ write is complete.

ED/HD TEST PATTERNS

The ADV739x is able to generate ED/HD color bar, black bar, and hatch test patterns.

The register settings in Table 57 are used to generate an ED 525p hatch test pattern. All other registers are set as normal/default. Component YPrPb output is available on DAC 1 to DAC 3. For component RGB output rather than YPrPb output, 0 should be written to Subaddress 0x02, Bit 5.

Table 57. ED 525p Hatch Test Pattern Register Writes

Subaddress	Setting
0x00	0x1C
0x01	0x10
0x31	0x05

To generate an ED 525p black bar test pattern, the same settings as shown in Table 57 should be used with an additional write of 0x24 to Subaddress 0x02.

To generate an ED 525p flat field test pattern, the same settings shown in Table 57 should be used, except that 0x0D should be written to Subaddress 0x31.

The Y, Cr, and Cb levels for the hatch and flat field test patterns can be controlled using Subaddress 0x36, Subaddress 0x37, and Subaddress 0x38, respectively.

For ED/HD standards other than 525p, the same settings as shown in Table 57 (and subsequent comments) are used except that Subaddress 0x30, Bits[7:3] are updated as appropriate.

APPENDIX 5—SD TIMING

Mode 0 (CCIR-656)—Slave Option (Subaddress 0x8A = X X X X X 0 0 0)

The ADV739x is controlled by the SAV (start of active video) and EAV (end of active video) time codes embedded in the pixel data. All timing information is transmitted using a 4-byte synchronization pattern. A synchronization pattern is sent immediately before and after each line during active picture and retrace. If the VSYNC and HSYNC pins are not used, they should be tied high when using this mode.

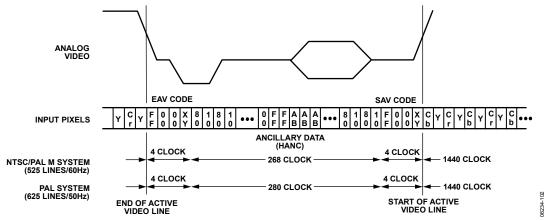


Figure 102. SD Timing Mode 0, Slave Option

Mode 0 (CCIR-656)—Master Option (Subaddress 0x8A = X X X X X 0 0 1)

The ADV739x generates H and F signals required for the SAV and EAV time codes in the CCIR-656 standard. The H bit is output on HSYNC and the F bit is output on VSYNC.

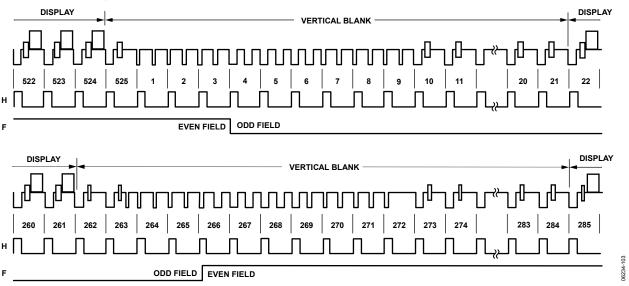


Figure 103. SD Timing Mode 0, Master Option, NTSC

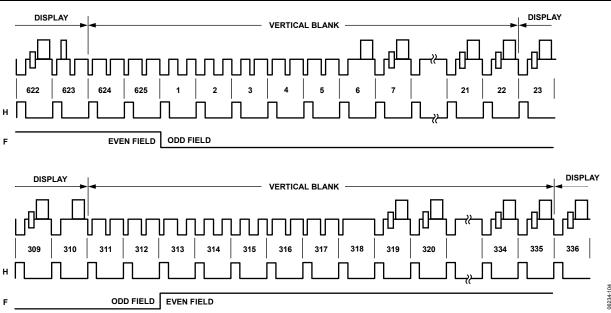


Figure 104. SD Timing Mode 0, Master Option, PAL

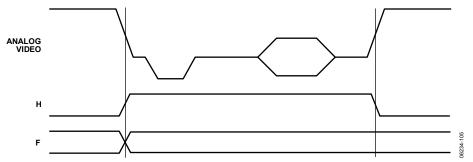


Figure 105. SD Timing Mode 0, Master Option, Data Transitions

Mode 1—Slave Option (Subaddress 0x8A = XXXXX 0 1 0)

In this mode, the ADV739x accepts horizontal synchronization and odd/even field signals. When $\overline{\text{HSYNC}}$ is low, a transition of the field input indicates a new frame, that is, vertical retrace. The ADV739x automatically blanks all normally blank lines as per CCIR-624. $\overline{\text{HSYNC}}$ and FIELD are input on the $\overline{\text{HSYNC}}$ and $\overline{\text{VSYNC}}$ pins, respectively.

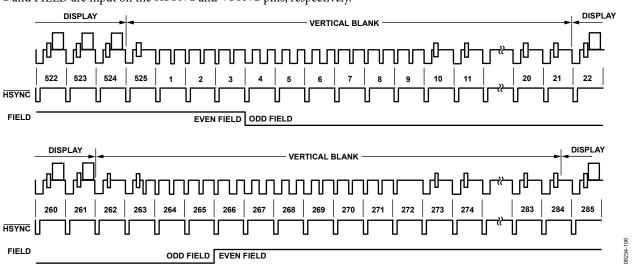


Figure 106. SD Timing Mode 1, Slave Option, NTSC

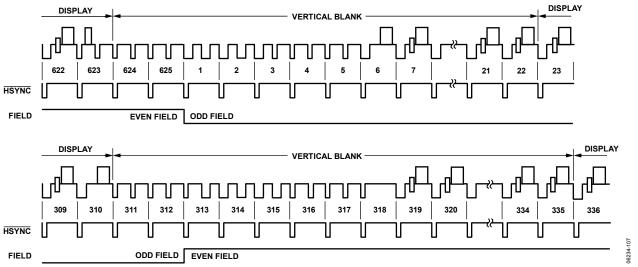


Figure 107. SD Timing Mode 1, Slave Option, PAL

Mode 1—Master Option (Subaddress 0x8A = XXXXX 0 1 1)

In this mode, the ADV739x can generate horizontal synchronization and odd/even field signals. When HSYNC is low, a transition of the field input indicates a new frame, that is, vertical retrace. The ADV739x automatically blanks all normally blank lines as per CCIR-624. Pixel data is latched on the rising clock edge following the timing signal transitions. HSYNC and FIELD are output on the HSYNC and VSYNC pins, respectively.

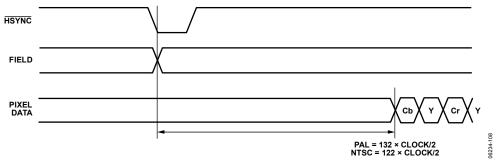


Figure 108. SD Timing Mode 1, Odd/Even Field Transitions (Master/Slave)

Mode 2— Slave Option (Subaddress 0x8A = X X X X X 1 0 0)

In this mode, the ADV739x accepts horizontal and vertical synchronization signals. A coincident low transition of both HSYNC and VSYNC inputs indicates the start of an odd field. A VSYNC low transition when HSYNC is high indicates the start of an even field. The ADV739x automatically blanks all normally blank lines as per CCIR-624. HSYNC and VSYNC are input on the HSYNC and VSYNC pins, respectively.

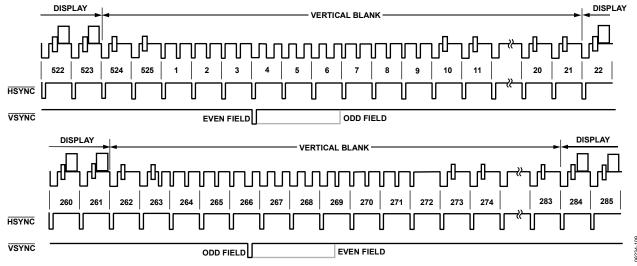
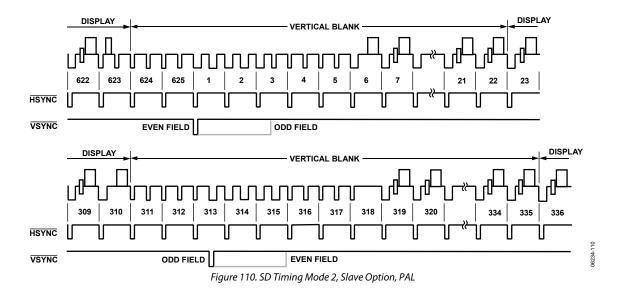


Figure 109. SD Timing Mode 2, Slave Option, NTSC



Mode 2—Master Option (Subaddress 0x8A = X X X X X 1 0 1)

In this mode, the ADV739x can generate horizontal and vertical synchronization signals. A coincident low transition of both $\overline{\text{HSYNC}}$ and $\overline{\text{VSYNC}}$ inputs indicates the start of an odd field.

A VSYNC low transition when HSYNC is high indicates the start of an even field. The ADV739x automatically blanks all normally blank lines as per CCIR-624. HSYNC and VSYNC are output on the HSYNC and VSYNC pins, respectively.

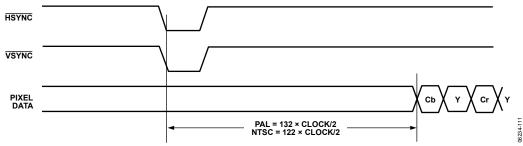


Figure 111. SD Timing Mode 2, Even-to-Odd Field Transition (Master/Slave)

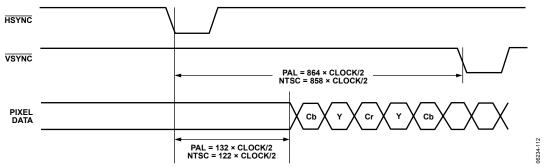


Figure 112. SD Timing Mode 2, Odd-to-Even Field Transition (Master/Slave)

Mode 3—Master/Slave Option (Subaddress 0x8A = XXXXX 1 1 0 or XXXXX 1 1 1)

In this mode, the ADV739x accepts or generates horizontal synchronization and odd/even field signals. When $\overline{\text{HSYNC}}$ is high, a transition of the field input indicates a new frame, that is, vertical retrace. The ADV739x automatically blanks all normally blank lines as per CCIR-624. $\overline{\text{HSYNC}}$ and $\overline{\text{VSYNC}}$ are output in master mode and input in slave mode on the $\overline{\text{HSYNC}}$ and $\overline{\text{VSYNC}}$ pins, respectively.

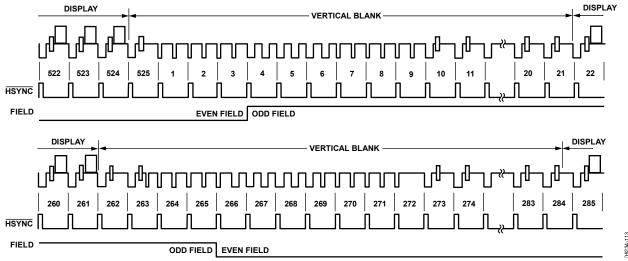


Figure 113. SD Timing Mode 3, NTSC

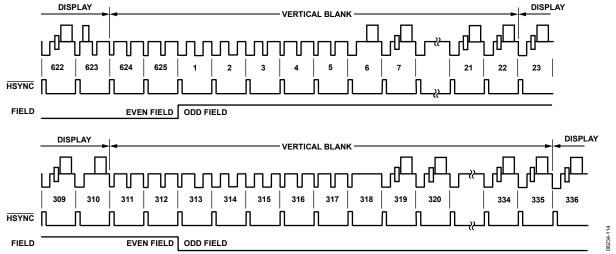
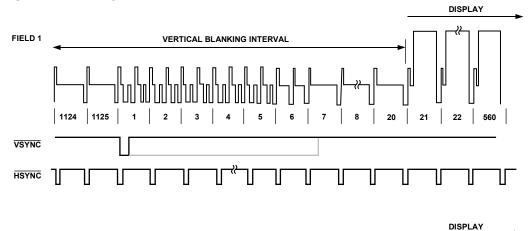


Figure 114. SD Timing Mode 3, PAL

APPENDIX 6-HD TIMING



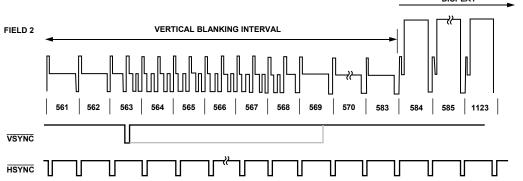
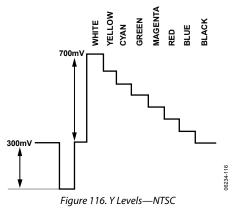


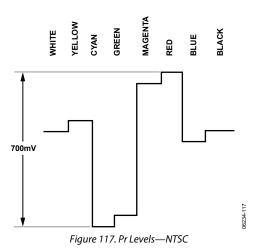
Figure 115. 1080i HSYNC and VSYNC Input Timing

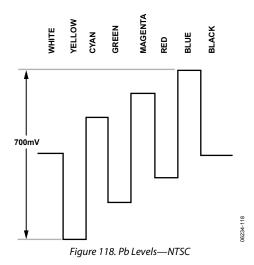
APPENDIX 7-VIDEO OUTPUT LEVELS

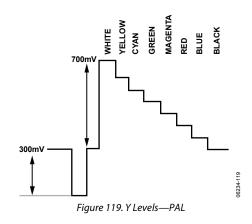
SD YPrPb OUTPUT LEVELS—SMPTE/EBU N10

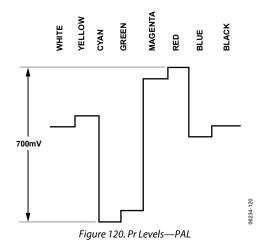
Pattern: 100% Color Bars

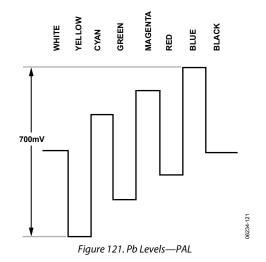












ED/HD YPrPb OUTPUT LEVELS

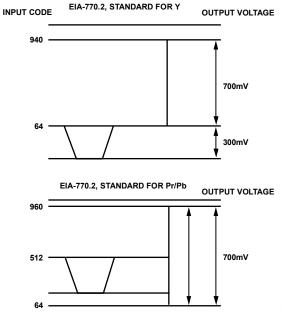


Figure 122. EIA-770.2 Standard Output Signals (525p/625p)

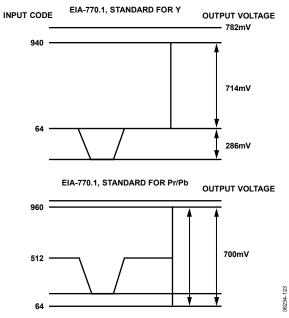


Figure 123. EIA-770.1 Standard Output Signals (525p/625p)

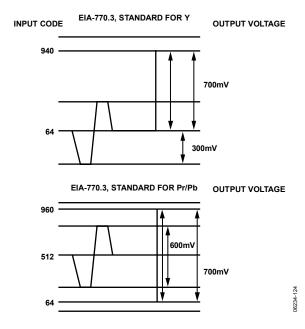


Figure 124. EIA-770.3 Standard Output Signals (1080i/720p)

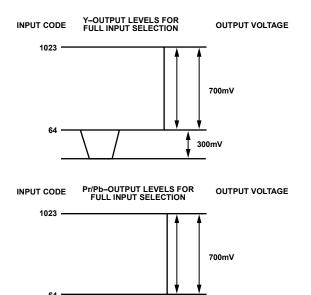


Figure 125. Output Levels for Full Input Selection

300mV

SD/ED/HD RGB OUTPUT LEVELS

Pattern: 100%/75% Color Bars

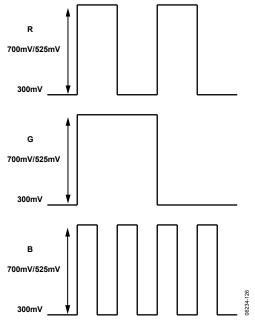


Figure 126. SD/ED RGB Output Levels—RGB Sync Disabled

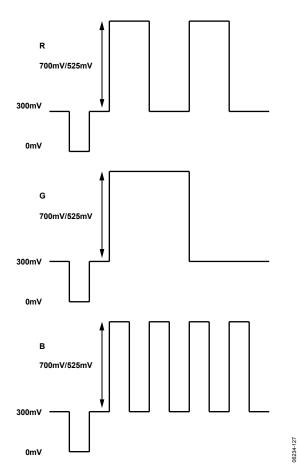


Figure 127. SD/ED RGB Output Levels—RGB Sync Enabled

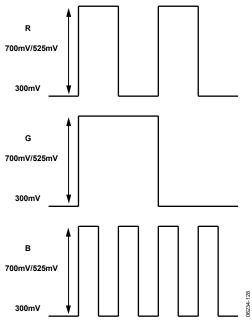


Figure 128. HD RGB Output Levels—RGB Sync Disabled

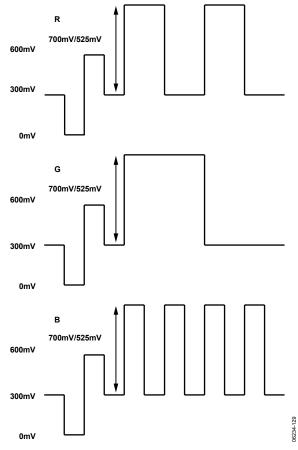


Figure 129. HD RGB Output Levels—RGB Sync Enabled

SD OUTPUT PLOTS

SLOW CLAMP TO 0.00V AT 6.72µs

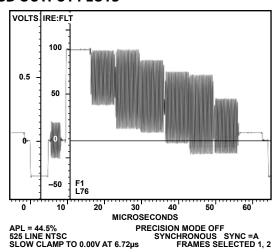


Figure 130. NTSC Color Bars (75%)

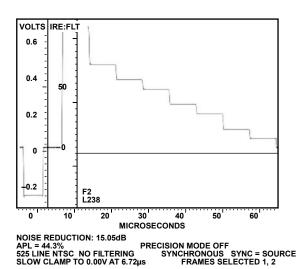


Figure 131. NTSC Luma

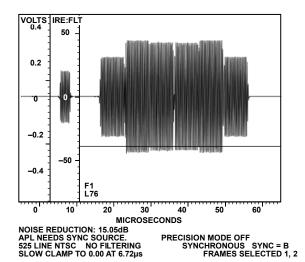


Figure 132. NTSC Chroma

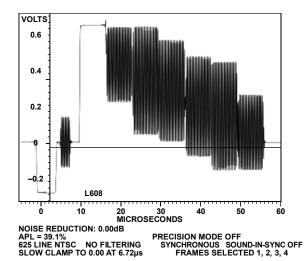


Figure 133. PAL Color Bars (75%)

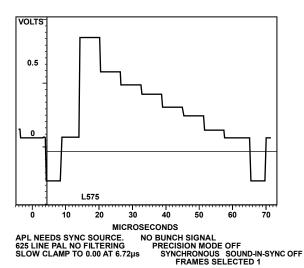


Figure 134. PAL Luma

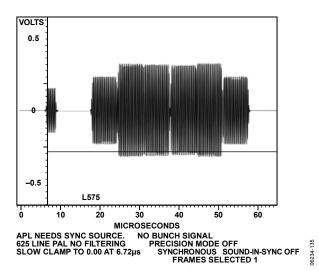
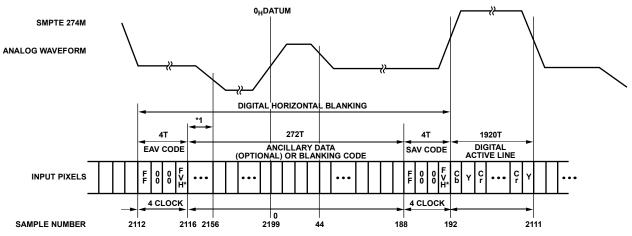


Figure 135. PAL Chroma

APPENDIX 8-VIDEO STANDARDS



FVH* = FVH AND PARITY BITS SAV/EAV: LINE 1–562: F = 0 SAV/EAV: LINE 563–1125: F = 1 SAV/EAV: LINE 1–20: 561–583; 1124–1125: V = 1 SAV/EAV: LINE 21–560; 584–1123: V = 0

FOR A FRAME RATE OF 30Hz: 40 SAMPLES FOR A FRAME RATE OF 25Hz: 480 SAMPLES

Figure 136. EAV/SAV Input Data Timing Diagram (SMPTE 274M)

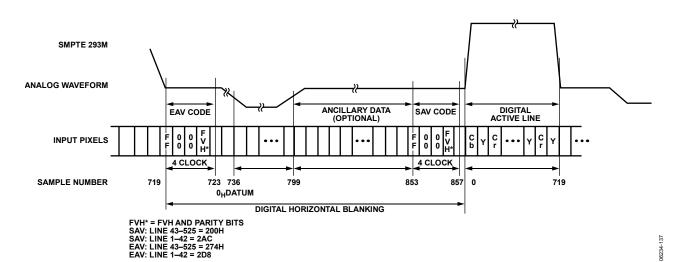
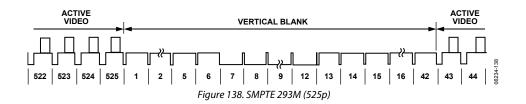
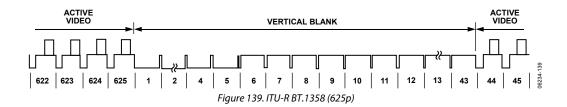
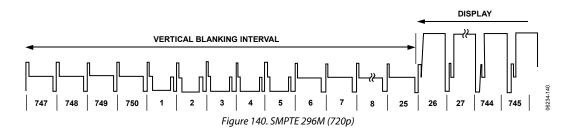


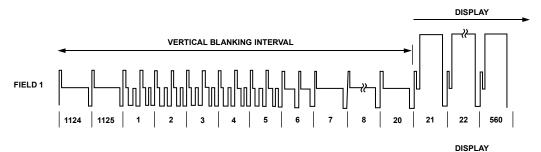
Figure 137. EAV/SAV Input Data Timing Diagram (SMPTE 293M)

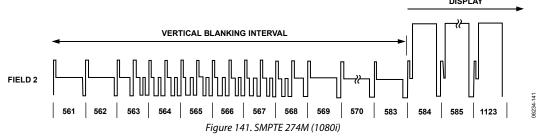


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APPENDIX 9-CONFIGURATION SCRIPTS

The scripts listed in the following pages can be used to configure the ADV739x for basic operation. Certain features are enabled by default. If required for a specific application, further features can be enabled. Table 58 lists the scripts available for SD modes of operation. Similarly, Table 89 and Table 106 list the scripts available for ED and HD modes of operation, respectively.

STANDARD DEFINITION

Table 58. SD Configuration Scripts

Input Format	Input Data Width	Synchronization Format	Input Color Space	Output Color Space	Table Number
525i (NTSC)	8-Bit SDR	EAV/SAV	YCrCb	YPrPb	Table 59
525i (NTSC)	8-Bit SDR	EAV/SAV	YCrCb	CVBS/Y-C (S-Video)	Table 60
525i (NTSC)	8-Bit SDR	HSYNC/VSYNC	YCrCb	YPrPb	Table 61
525i (NTSC)	8-Bit SDR	EAV/SAV	YCrCb	RGB	Table 62
525i (NTSC)	8-Bit SDR	HSYNC/VSYNC	YCrCb	RGB	Table 63
525i (NTSC)	10-Bit SDR	EAV/SAV	YCrCb	YPrPb	Table 64
525i (NTSC)	10-Bit SDR	HSYNC/VSYNC	YCrCb	YPrPb	Table 65
525i (NTSC)	10-Bit SDR	HSYNC/VSYNC	YCrCb	CVBS/ Y-C (S-Video)	Table 66
525i (NTSC)	10-Bit SDR	EAV/SAV	YCrCb	RGB	Table 67
525i (NTSC)	10-Bit SDR	HSYNC/VSYNC	YCrCb	RGB	Table 68
525i (NTSC)	16-Bit SDR	HSYNC/VSYNC	YCrCb	YPrPb	Table 69
525i (NTSC)	16-Bit SDR	HSYNC/VSYNC	YCrCb	RGB	Table 70
525i (NTSC)	16-Bit SDR	HSYNC/VSYNC	RGB	YPrPb	Table 71
525i (NTSC)	16-Bit SDR	HSYNC/VSYNC	RGB	CVBS/ Y-C (S-Video)	Table 72
525i (NTSC)	16-Bit SDR	HSYNC/VSYNC	RGB	RGB	Table 73
625i (PAL)	8-Bit SDR	EAV/SAV	YCrCb	YPrPb	Table 74
625i (PAL)	8-Bit SDR	EAV/SAV	YCrCb	CVBS/Y-C (S-Video)	Table 75
625i (PAL)	8-Bit SDR	HSYNC/VSYNC	YCrCb	YPrPb	Table 76
625i (PAL)	8-Bit SDR	EAV/SAV	YCrCb	RGB	Table 77
625i (PAL)	8-Bit SDR	HSYNC/VSYNC	YCrCb	RGB	Table 78
625i (PAL)	10-Bit SDR	EAV/SAV	YCrCb	YPrPb	Table 79
625i (PAL)	10-Bit SDR	HSYNC/VSYNC	YCrCb	YPrPb	Table 80
625i (PAL)	10-Bit SDR	HSYNC/VSYNC	YCrCb	CVBS/Y-C (S-Video)	Table 81
625i (PAL)	10-Bit SDR	EAV/SAV	YCrCb	RGB	Table 82
625i (PAL)	10-Bit SDR	HSYNC/VSYNC	YCrCb	RGB	Table 83
625i (PAL)	16-Bit SDR	HSYNC/VSYNC	YCrCb	YPrPb	Table 84
625i (PAL)	16-Bit SDR	HSYNC/VSYNC	YCrCb	RGB	Table 85
625i (PAL)	16-Bit SDR	HSYNC/VSYNC	RGB	YPrPb	Table 86
625i (PAL)	16-Bit SDR	HSYNC/VSYNC	RGB	CVBS/Y-C (S-Video)	Table 87
625i (PAL)	16-Bit SDR	HSYNC/VSYNC	RGB	RGB	Table 88

Table 59. 8-Bit 525i YCrCb In (EAV/SAV), YPrPb Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x80	0x10	NTSC standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xC9	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled. Pedestal enabled.

Table 60. 8-Bit 525i YCrCb In (EAV/SAV), CVBS/Y-C Out

	Subaddress	Setting	Description
	0x17	0x02	Software reset
	0x00	0x1C	All DACs enabled. PLL enabled (16×).
	0x01	0x00	SD input mode.
-	0x80	0x10	NTSC standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
	0x82	0xCB	Pixel data valid. CVBS/S-Video out. SSAF PrPb filter enabled. Active video edge control enabled. Pedestal enabled.

Table 61. 8-Bit 525i YCrCb In, YPrPb Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x80	0x10	NTSC standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xC9	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled. Pedestal enabled.
0x8A	0x0C	Timing Mode 2 (Slave). HSYNC/VSYNC synchronization.

Table 62. 8-Bit 525i YCrCb In (EAV/SAV), RGB Out

Subaddress	Setting	Description	
0x17	0x02	Software reset.	
0x00	0x1C	All DACs enabled. PLL enabled (16×).	
0x01	0x00	SD input mode.	
0x02	0x10	RGB output enabled. RGB output sync enabled.	
0x80	0x10	NTSC standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.	
0x82	0xC9	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled. Pedestal enabled.	

Table 63. 8-Bit 525i YCrCb In, RGB Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x02	0x10	RGB output enabled. RGB output sync enabled.
0x80	0x10	NTSC standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xC9	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled. Pedestal enabled.
0x8A	0x0C	Timing Mode 2 (Slave). HSYNC/VSYNC synchronization.

Table 64. 10-Bit 525i YCrCb In (EAV/SAV), YPrPb Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x80	0x10	NTSC standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xC9	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled. Pedestal enabled.
0x88	0x10	10-bit input enabled.

Table 65. 10-Bit 525i YCrCb In, YPrPb Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x80	0x10	NTSC standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xC9	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled. Pedestal enabled.
0x88	0x10	10-bit input enabled.
0x8A	0x0C	Timing Mode 2 (Slave). HSYNC/VSYNC synchronization.

Table 66. 10-Bit 525i YCrCb In, CVBS/Y-C Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x80	0x10	NTSC standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xCB	Pixel data valid. CVBS/S-Video out. SSAF PrPb filter enabled. Active video edge control enabled. Pedestal enabled.
0x88	0x10	10-bit input enabled.
0x8A	0x0C	Timing Mode 2 (Slave). HSYNC/VSYNC synchronization.

Table 67. 10-Bit 525i YCrCb In (EAV/SAV), RGB Out

(,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,			
Subaddress	Setting	Description	
0x17	0x02	Software reset.	
0x00	0x1C	All DACs enabled. PLL enabled (16×).	
0x01	0x00	SD input mode.	
0x02	0x10	RGB output enabled. RGB output sync enabled.	
0x80	0x10	NTSC standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.	
0x82	0xC9	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled. Pedestal enabled.	
0x88	0x10	10-bit input enabled.	

Table 68. 10-Bit 525i YCrCb In, RGB Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x02	0x10	RGB output enabled. RGB output sync enabled.
0x80	0x10	NTSC standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xC9	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled. Pedestal enabled.
0x88	0x10	10-bit input enabled.
0x8A	0x0C	Timing Mode 2 (Slave). HSYNC/VSYNC synchronization.

Table 69. 16-Bit 525i YCrCb In, YPrPb Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x80	0x10	NTSC standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xC9	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled. pedestal enabled.
0x88	0x08	16-bit input enabled.
0x8A	0x0C	Timing Mode 2 (Slave). HSYNC/VSYNC synchronization.

Table 70. 16-Bit 525i YCrCb In, RGB Out

Subaddress	Setting	Description
0x17	0x02	Software reset
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x02	0x10	RGB output enabled. RGB output sync enabled.
0x80	0x10	NTSC standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xC9	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled. Pedestal enabled.
0x88	0x08	16-bit input enabled.
0x8A	0x0C	Timing Mode 2 (Slave). HSYNC/VSYNC synchronization.

Table 71. 16-Bit 525i RGB In, YPrPb Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x80	0x10	NTSC standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xC9	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled. Pedestal enabled.
0x87	0x80	RGB input enabled.
0x88	0x08	16-bit input enabled.
0x8A	0x0C	Timing Mode 2 (Slave). HSYNC/VSYNC synchronization.

Table 72. 16-Bit 525i RGB In, CVBS/Y-C Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x80	0x10	NTSC standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xCB	Pixel data valid. CVBS/S-Video out. SSAF PrPb filter enabled. Active video edge control enabled. Pedestal enabled.
0x87	0x80	RGB input enabled.
0x88	0x08	16-bit input enabled.
0x8A	0x0C	Timing Mode 2 (Slave). HSYNC/VSYNC synchronization.

Table 73. 16-Bit 525i RGB In, RGB Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x02	0x10	RGB output enabled. RGB output sync enabled.
0x80	0x10	NTSC standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xC9	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled. Pedestal enabled.
0x87	0x80	RGB input enabled.
0x88	0x08	16-bit input enabled.
0x8A	0x0C	Timing Mode 2 (Slave). HSYNC/VSYNC synchronization.

Table 74. 8-Bit 625i YCrCb In (EAV/SAV), YPrPb Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x80	0x11	PAL standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xC1	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled.
0x8C	0xCB	PAL F _{SC} value.
0x8D	0x8A	PAL F _{SC} value.
0x8E	0x09	PAL F _{SC} value.
0x8F	0x2A	PAL F _{SC} value.

Table 75. 8-Bit 625i YCrCb In (EAV/SAV), CVBS/Y-C Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x80	0x11	PAL standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xC3	Pixel data valid. CVBS/S-Video out. SSAF PrPb filter enabled. Active video edge control enabled.
0x8C	0xCB	PAL F _{SC} value.
0x8D	0x8A	PAL F _{SC} value.
0x8E	0x09	PAL F _{SC} value.
0x8F	0x2A	PAL F _{SC} value.

Table 76. 8-Bit 625i YCrCb In, YPrPb Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x80	0x11	PAL standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xC1	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled.
0x8A	0x0C	Timing Mode 2 (Slave). HSYNC/VSYNC synchronization.
0x8C	0xCB	PAL F _{SC} value.
0x8D	0x8A	PAL F _{SC} value.
0x8E	0x09	PAL F _{SC} value.
0x8F	0x2A	PAL F _{SC} value.

Table 77. 8-Bit 625i YCrCb In (EAV/SAV), RGB Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x02	0x10	RGB output enabled. RGB output sync enabled.
0x80	0x11	PAL standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xC1	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled.
0x8C	0xCB	PAL F _{SC} value.
0x8D	0x8A	PAL F _{SC} value.
0x8E	0x09	PAL F _{SC} value.
0x8F	0x2A	PAL F _{SC} value.

Table 78. 8-Bit 625i YCrCb In, RGB Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x02	0x10	RGB output enabled. RGB output sync enabled.
0x80	0x11	PAL standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xC1	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled.
0x8A	0x0C	Timing Mode 2 (Slave). HSYNC/VSYNC synchronization.
0x8C	0xCB	PAL F _{SC} value.
0x8D	0x8A	PAL F _{SC} value.
0x8E	0x09	PAL F _{SC} value.
0x8F	0x2A	PAL F _{SC} value.

Table 79. 10-Bit 625i YCrCb In (EAV/SAV), YPrPb Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x80	0x11	PAL standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xC1	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled.
0x88	0x10	10-bit input enabled.

Table 80. 10-Bit 625i YCrCb In, YPrPb Out

1401c 00: 10 Dit 0231 10100 III, 11110 Out		
Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x80	0x11	PAL standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xC1	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled.
0x88	0x10	10-bit input enabled.
0x8A	0x0C	Timing Mode 2 (Slave). HSYNC/VSYNC synchronization.
0x8C	0xCB	PAL F _{SC} value.
0x8D	0x8A	PAL F _{SC} value.
0x8E	0x09	PAL F _{SC} value.
0x8F	0x2A	PAL F _{SC} value.

Table 81. 10-Bit 625i YCrCb In, CVBS/Y-C Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x80	0x11	PAL standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xC3	Pixel Data Valid. CVBS/S-Video Out. SSAF PrPb Filter Enabled. Active Video Edge Control Enabled.
0x88	0x10	10-bit input enabled.
0x8A	0x0C	Timing Mode 2 (Slave). HSYNC/VSYNC synchronization.
0x8C	0xCB	PAL F _{SC} value.
0x8D	0x8A	PAL F _{SC} value.
0x8E	0x09	PAL F _{sc} value.
0x8F	0x2A	PAL F _{SC} value.

Table 82. 10-Bit 625i YCrCb In (EAV/SAV), RGB Out

Subaddress	Setting	Description	
0x17	0x02	Software reset.	
0x00	0x1C	All DACs enabled. PLL enabled (16×).	
0x01	0x00	SD input mode.	
0x02	0x10	RGB output enabled. RGB output sync enabled.	
0x80	0x11	PAL standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.	
0x82	0xC1	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled.	
0x88	0x10	10-bit input enabled.	
0x8C	0xCB	PAL F _{SC} value.	
0x8D	0x8A	PAL F _{SC} value.	
0x8E	0x09	PAL F _{SC} value.	
0x8F	0x2A	PAL F _{SC} value.	

Table 83. 10-Bit 625i YCrCb In, RGB Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x02	0x10	RGB output enabled. RGB output sync enabled.
0x80	0x11	PAL standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xC1	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled.
0x88	0x10	10-bit input enabled.
0x8A	0x0C	Timing Mode 2 (Slave). HSYNC/VSYNC synchronization.
0x8C	0xCB	PAL F _{SC} value.
0x8D	0x8A	PAL F _{SC} value.
0x8E	0x09	PAL F _{SC} value.
0x8F	0x2A	PAL F _{SC} value.

Table 84. 16-Bit 625i YCrCb In, YPrPb Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x80	0x11	PAL standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xC1	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled.
0x88	0x08	16-bit input enabled.
0x8A	0x0C	Timing Mode 2 (Slave). HSYNC/VSYNC synchronization.
0x8C	0xCB	PAL F _{SC} value.
0x8D	0x8A	PAL F _{SC} value.
0x8E	0x09	PAL F _{SC} value.
0x8F	0x2A	PAL F _{SC} value.

Table 85. 16-Bit 625i YCrCb In, RGB Out

Table 65. 10-bit 6251 TCICD III, KGD Out		
Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x02	0x10	RGB output enabled. RGB output sync enabled.
0x80	0x11	PAL standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xC1	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled.
0x88	0x08	16-bit input enabled.
0x8A	0x0C	Timing Mode 2 (Slave). HSYNC/VSYNC synchronization.
0x8C	0xCB	PAL F _{SC} value.
0x8D	0x8A	PAL F _{SC} value.
0x8E	0x09	PAL F _{SC} value.
0x8F	0x2A	PAL F _{SC} value.

Table 86. 16-Bit 625i RGB In, YPrPb Out

1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1			
Subaddress	Setting	Description	
0x17	0x02	Software reset.	
0x00	0x1C	All DACs enabled. PLL enabled (16×).	
0x01	0x00	SD input mode.	
0x80	0x11	PAL standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.	
0x82	0xC1	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled.	
0x87	0x80	RGB input enabled.	
0x88	0x08	16-bit input enabled.	
0x8A	0x0C	Timing Mode 2 (Slave). HSYNC/VSYNC synchronization.	
0x8C	0xCB	PAL F _{SC} value.	
0x8D	0x8A	PAL F _{SC} value.	
0x8E	0x09	PAL F _{SC} value.	
0x8F	0x2A	PAL F _{SC} value.	

Table 87. 16-Bit 625i RGB In, CVBS/Y-C Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x80	0x11	PAL standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xC3	Pixel data valid. CVBS/S-Video out. SSAF PrPb filter enabled. Active video edge control enabled.
0x87	0x80	RGB input enabled.
0x88	0x08	16-bit input enabled.
0x8A	0x0C	Timing Mode 2 (Slave). HSYNC/VSYNC synchronization.
0x8C	0xCB	PAL F _{SC} value.
0x8D	0x8A	PAL F _{SC} value.
0x8E	0x09	PAL F _{SC} value.
0x8F	0x2A	PAL F _{SC} value.

Table 88. 16-Bit 625i RGB In, RGB Out

1 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2		
Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (16×).
0x01	0x00	SD input mode.
0x02	0x10	RGB output enabled. RGB output sync enabled.
0x80	0x11	PAL standard. SSAF luma filter enabled. 1.3 MHz chroma filter enabled.
0x82	0xC1	Pixel data valid. YPrPb out. SSAF PrPb filter enabled. Active video edge control enabled.
0x87	0x80	RGB input enabled.
0x88	0x08	16-bit input enabled.
0x8A	0x0C	Timing Mode 2 (Slave). HSYNC/VSYNC synchronization.
0x8C	0xCB	PAL F _{SC} value.
0x8D	0x8A	PAL F _{SC} value.
0x8E	0x09	PAL F _{SC} value.
0x8F	0x2A	PAL F _{SC} value.

ENHANCED DEFINITION

Table 89. ED Configuration Scripts

Input Format	Input Data Width	Synchronization Format	Input Color Space	Output Color Space	Table Number
525p	8-Bit DDR	EAV/SAV	YCrCb	YPrPb	Table 98
525p	8-Bit DDR	EAV/SAV	YCrCb	RGB	Table 100
525p	10-Bit DDR	EAV/SAV	YCrCb	YPrPb	Table 99
525p	10-Bit DDR	EAV/SAV	YCrCb	RGB	Table 101
525p	16-Bit SDR	EAV/SAV	YCrCb	YPrPb	Table 90
525p	16-Bit SDR	HSYNC/VSYNC	YCrCb	YPrPb	Table 91
525p	16-Bit SDR	EAV/SAV	YCrCb	RGB	Table 92
525p	16-Bit SDR	HSYNC/VSYNC	YCrCb	RGB	Table 93
625p	8-Bit DDR	EAV/SAV	YCrCb	YPrPb	Table 102
625p	8-Bit DDR	EAV/SAV	YCrCb	RGB	Table 104
625p	10-Bit DDR	EAV/SAV	YCrCb	YPrPb	Table 103
625p	10-Bit DDR	EAV/SAV	YCrCb	RGB	Table 105
625p	16-Bit SDR	EAV/SAV	YCrCb	YPrPb	Table 94
625p	16-Bit SDR	HSYNC/VSYNC	YCrCb	YPrPb	Table 95
625p	16-Bit SDR	EAV/SAV	YCrCb	RGB	Table 96
625p	16-Bit SDR	HSYNC/VSYNC	YCrCb	RGB	Table 97

Table 90. 16-Bit 525p YCrCb In (EAV/SAV), YPrPb Out

Subaddress	Setting	Description	
0x17	0x02	Software reset.	
0x00	0x1C	All DACs enabled. PLL enabled ($8\times$).	
0x01	0x10	ED-SDR input mode.	
0x30	0x04	525p @ 59.94 Hz. EAV/SAV synchroni- zation. EIA-770.2 output levels.	
0x31	0x01	Pixel data valid.	

Table 91. 16-Bit 525p YCrCb In, YPrPb Out

Subaddress	Setting	Description	
0x17	0x02	Software reset.	
0x00	0x1C	All DACs enabled. PLL enabled (8×).	
0x01	0x10	ED-SDR input mode.	
0x30	0x00	525p @ 59.94 Hz. HSYNC/VSYNC synch-	
		ronization. EIA-770.2 output levels.	
0x31	0x01	Pixel data valid.	

Table 92. 16-Bit 525p YCrCb In (EAV/SAV), RGB Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (8×).
0x01	0x10	ED-SDR input mode.
0x02	0x10	RGB output enabled. RGB output sync enabled.
0x30	0x04	525p @ 59.94 Hz. EAV/SAV synchroni- zation. EIA-770.2 output levels.
0x31	0x01	Pixel data valid.

Table 93. 16-Bit 525p YCrCb In, RGB Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (8×).
0x01	0x10	ED-SDR input mode.
0x02	0x10	RGB output enabled. RGB output sync enabled.
0x30	0x00	525p @ 59.94 Hz. HSYNC/VSYNC synchronization. EIA-770.2 output levels.
0x31	0x01	Pixel data valid.

Table 94. 16-Bit 625p YCrCb In (EAV/SAV), YPrPb Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (8×).
0x01	0x10	ED-SDR input mode.
0x30	0x1C	625p @ 50 Hz. EAV/SAV synchroni- zation. EIA-770.2 output levels.
0x31	0x01	Pixel data valid.

Table 95. 16-Bit 625p YCrCb In, YPrPb Out

i		
Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (8×).
0x01	0x10	ED-SDR input mode.
0x30	0x18	625p @ 50 Hz. HSYNC/VSYNC synch-
		ronization. EIA-770.2 output levels.
0x31	0x01	Pixel data valid.

Table 96. 16-Bit 625p YCrCb In (EAV/SAV), RGB Out

Subaddress	Setting	Description	
0x17	0x02	Software reset.	
0x00	0x1C	All DACs enabled. PLL enabled (8×).	
0x01	0x10	ED-SDR input mode.	
0x02	0x10	RGB output enabled. RGB output sync enabled.	
0x30	0x1C	625p @ 50 Hz. EAV/SAV synchronization. EIA-770.2 output levels.	
0x31	0x01	Pixel data valid.	

Table 97. 16-Bit 625p YCrCb In, RGB Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (8×).
0x01	0x10	ED-SDR input mode.
0x02	0x10	RGB output enabled. RGB output sync enabled.
0x30	0x18	625p @ 50 Hz. HSYNC/VSYNC synchronization. EIA-770.2 output levels.
0x31	0x01	Pixel data valid.

Table 98. 8-Bit 525p YCrCb In (EAV/SAV), YPrPb Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled ($8\times$).
0x01	0x20	ED-DDR input mode. Luma data clocked on falling edge of CLKIN.
0x30	0x04	525p @ 59.94 Hz. EAV/SAV synchro- nization. EIA-770.2 output levels.
0x31	0x01	Pixel data valid.

Table 99. 10-Bit 525p YCrCb In (EAV/SAV), YPrPb Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (8×).
0x01	0x20	ED-DDR input mode. Luma data clocked on falling edge of CLKIN.
0x30	0x04	525p @ 59.94 Hz. EAV/SAV synchro- nization. EIA-770.2 output levels.
0x31	0x01	Pixel data valid.
0x33	0x6C	10-bit input enabled.

Table 100. 8-Bit 525p YCrCb In (EAV/SAV), RGB Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (8×).
0x01	0x20	ED-DDR input mode. Luma data clocked on falling edge of CLKIN.
0x02	0x10	RGB output enabled. RGB output sync enabled.
0x30	0x04	525p @ 59.94 Hz. EAV/SAV synchro- nization. EIA-770.2 output levels.
0x31	0x01	Pixel data valid.

Table 101. 10-Bit 525p YCrCb In (EAV/SAV), RGB Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (8×).
0x01	0x20	ED-DDR input mode. Luma data clocked on falling edge of CLKIN.
0x02	0x10	RGB output enabled. RGB output sync enabled.
0x30	0x04	525p @ 59.94 Hz. EAV/SAV synchro- nization. EIA-770.2 output levels.
0x31	0x01	Pixel data valid.
0x33	0x6C	10-bit input enabled.

Table 102. 8-Bit 625p YCrCb In (EAV/SAV), YPrPb Out

1 "		
Setting	Description	
0x02	Software reset.	
0x1C	All DACs enabled. PLL enabled (8×).	
0x20	ED-DDR input mode. Luma data clocked on falling edge of CLKIN.	
0x1C	625p @ 50 Hz. EAV/SAV synchronization. EIA-770.2 output levels.	
0x01	Pixel data valid.	
	0x02 0x1C 0x20 0x1C	

Table 103. 10-Bit 625p YCrCb In (EAV/SAV), YPrPb Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (8×).
0x01	0x20	ED-DDR input mode. Luma data clocked on falling edge of CLKIN.
0x30	0x1C	625p @ 50 Hz. EAV/SAV synchronization. EIA-770.2 output levels.
0x31	0x01	Pixel data valid.
0x33	0x6C	10-bit input enabled.

Table 104. 8-Bit 625p YCrCb In (EAV/SAV), RGB Out

Tuble 101. 0 Dit 023p Teleb III (Eliviolity); Red Out		
Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (8×).
0x01	0x20	ED-DDR input mode. Luma data clocked on falling edge of CLKIN.
0x02	0x10	RGB output enabled. RGB output sync enabled.
0x30	0x1C	625p @ 50 Hz. EAV/SAV synchroni- zation. EIA-770.2 output levels.
0x31	0x01	Pixel data valid.

Table 105. 10-Bit 625p YCrCb In (EAV/SAV), RGB Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled $(8\times)$.
0x01	0x20	ED-DDR input mode. Luma data clocked on falling edge of CLKIN.
0x02	0x10	RGB output enabled. RGB output sync enabled.
0x30	0x1C	625p @ 50 Hz. EAV/SAV synchroni- zation. EIA-770.2 output levels.
0x31	0x01	Pixel data valid.
0x33	0x6C	10-bit input enabled.

HIGH DEFINITION

Table 106. HD Configuration Scripts

Input Format	Input Data Width	Synchronization Format	Input Color Space	Output Color Space	Table Number
720p	8-Bit DDR	EAV/SAV	YCrCb	YPrPb	Table 115
720p	8-Bit DDR	EAV/SAV	YCrCb	RGB	Table 117
720p	10-Bit DDR	EAV/SAV	YCrCb	YPrPb	Table 116
720p	10-Bit DDR	EAV/SAV	YCrCb	RGB	Table 118
720p	16-Bit SDR	EAV/SAV	YCrCb	YPrPb	Table 107
720p	16-Bit SDR	HSYNC/VSYNC	YCrCb	YPrPb	Table 108
720p	16-Bit SDR	EAV/SAV	YCrCb	RGB	Table 109
720p	16-Bit SDR	HSYNC/VSYNC	YCrCb	RGB	Table 110
1080i	8-Bit DDR	EAV/SAV	YCrCb	YPrPb	Table 119
1080i	8-Bit DDR	EAV/SAV	YCrCb	RGB	Table 121
1080i	10-Bit DDR	EAV/SAV	YCrCb	YPrPb	Table 120
1080i	10-Bit DDR	EAV/SAV	YCrCb	RGB	Table 122
1080i	16-Bit SDR	EAV/SAV	YCrCb	YPrPb	Table 111
1080i	16-Bit SDR	HSYNC/VSYNC	YCrCb	YPrPb	Table 112
1080i	16-Bit SDR	EAV/SAV	YCrCb	RGB	Table 113
1080i	16-Bit SDR	HSYNC/VSYNC	YCrCb	RGB	Table 114

Table 107. 16-Bit 720p YCrCb In (EAV/SAV), YPrPb Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (4×).
0x01	0x10	HD-SDR input mode.
0x30	0x2C	720p @ 60 Hz/59.94 Hz. EAV/SAV syn- chronization. EIA-770.3 output levels.
0x31	0x01	Pixel data valid. 4× oversampling.

Table 108. 16-Bit 720p YCrCb In, YPrPb Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (4×).
0x01	0x10	HD-SDR input mode.
0x30	0x28	720p @ 60 Hz/59.94 Hz. HSYNC/VSYNC synchronization. EIA-770.3 output levels.
0x31	0x01	Pixel data valid. 4× oversampling.

Table 109. 16-Bit 720p YCrCb In (EAV/SAV), RGB Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (4×).
0x01	0x10	HD-SDR input mode.
0x02	0x10	RGB output enabled. RGB output sync enabled.
0x30	0x2C	720p @ 60 Hz/59.94 Hz. EAV/SAV syn- chronization. EIA-770.3 output levels.
0x31	0x01	Pixel data valid. 4× oversampling.

Table 110. 16-Bit 720p YCrCb In, RGB Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled ($4\times$).
0x01	0x10	HD-SDR input mode.
0x02	0x10	RGB output enabled. RGB output sync enabled.
0x30	0x28	720p @ 60 Hz/59.94 Hz. HSYNC/VSYNC synchronization. EIA-770.3 output levels.
0x31	0x01	Pixel data valid. 4× oversampling.

Table 111. 16-Bit 1080i YCrCb In (EAV/SAV), YPrPb Out

14010 1111 10 210 10001 1 01 00 111 (2111 / 0111 /), 1111 0 0 40			
Subaddress	Setting	Description	
0x17	0x02	Software reset.	
0x00	0x1C	All DACs enabled. PLL enabled (4×).	
0x01	0x10	HD-SDR input mode.	
0x30	0x6C	1080i @ 30 Hz/29.97 Hz. EAV/SAV synchronization. EIA-770.3 output levels.	
0x31	0x01	Pixel data valid. 4× oversampling.	

Table 112. 16-Bit 1080i YCrCb In, YPrPb Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (4×).
0x01	0x10	HD-SDR input mode.
0x30	0x18	1080i @ 30 Hz/29.97 Hz. HSYNC/VSYNC synchronization. EIA-770.3 output levels.
0x31	0x01	Pixel data valid. 4× oversampling.

Table 113. 16-Bit 1080i YCrCb In (EAV/SAV), RGB Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (4×).
0x01	0x10	HD-SDR input mode.
0x02	0x10	RGB output enabled. RGB output sync enabled.
0x30	0x6C	1080i @ 30 Hz/29.97 Hz. EAV/SAV syn- chronization. EIA-770.3 output levels.
0x31	0x01	Pixel data valid. 4× oversampling.

Table 114. 16-Bit 1080i YCrCb In, RGB Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (4×).
0x01	0x10	HD-SDR input mode.
0x02	0x10	RGB output enabled. RGB output sync enabled.
0x30	0x18	1080i @ 30 Hz/29.97 Hz. HSYNC/VSYNC synchronization. EIA-770.3 output levels.
0x31	0x01	Pixel data valid. 4× oversampling.

Table 115. 8-Bit 720p YCrCb In (EAV/SAV), YPrPb Out

Subaddress	Setting	Description	
0x17	0x02	Software reset.	
0x00	0x1C	All DACs enabled. PLL enabled ($4\times$).	
0x01	0x20	HD-DDR input mode. Luma data clocked on falling edge of CLKIN.	
0x30	0x2C	720p @ 60 Hz/59.94 Hz. EAV/SAV synchronization. EIA-770.3 output levels.	
0x31	0x01	Pixel data valid. 4× oversampling.	

Table 116. 10-Bit 720p YCrCb In (EAV/SAV), YPrPb Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled $(4\times)$.
0x01	0x20	HD-DDR input mode. Luma data clocked on falling edge of CLKIN.
0x30	0x2C	720p @ 60 Hz/59.94 Hz. EAV/SAV synchronization. EIA-770.3 output levels.
0x31	0x01	Pixel data valid. 4× oversampling.
0x33	0x6C	10-bit input enabled.

Table 117. 8-Bit 720p YCrCb In (EAV/SAV), RGB Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled $(4\times)$.
0x01	0x20	HD-DDR input mode. Luma data clocked on falling edge of CLKIN.
0x02	0x10	RGB output enabled. RGB output sync enabled.
0x30	0x2C	720p @ 60 Hz/59.94 Hz. EAV/SAV synchronization. EIA-770.3 output levels.
0x31	0x01	Pixel data valid. 4× oversampling.

Table 118. 10-Bit 720p YCrCb In (EAV/SAV), RGB Out

1 word 110/10 210/20p 1 01 00 11 (211//011/), 1/02 0 w				
Subaddress	Setting	Description		
0x17	0x02	Software reset.		
0x00	0x1C	All DACs enabled. PLL enabled (4×).		
0x01	0x20	HD-DDR input mode. Luma data clocked on falling edge of CLKIN.		
0x02	0x10	RGB output enabled. RGB output sync enabled.		
0x30	0x2C	720p @ 60 Hz/59.94 Hz. EAV/SAV synchronization. EIA-770.3 output levels.		
0x31	0x01	Pixel data valid. 4× oversampling.		
0x33	0x6C	10-bit input enabled.		

Table 119. 8-Bit 1080i YCrCb In (EAV/SAV), YPrPb Out

	, , , , , , , , , , , , , , , , , , , ,			
Setting	Description			
0x02	Software reset.			
0x1C	All DACs enabled. PLL enabled (4×).			
0x20	HD-DDR input mode. Luma data clocked on falling edge of CLKIN.			
0x6C	1080i @ 30 Hz/29.97 Hz. EAV/SAV syn- chronization. EIA-770.3 output levels.			
0x01	Pixel data valid. 4× oversampling.			
	0x02 0x1C 0x20 0x6C			

Table 120. 10-Bit 1080i YCrCb In (EAV/SAV), YPrPb Out

Subaddress	Setting	Description	
0x17	0x02	Software reset.	
0x00	0x1C	All DACs enabled. PLL enabled (4×).	
0x01	0x20	HD-DDR input mode. Luma data clocked on falling edge of CLKIN.	
0x30	0x6C	1080i @ 30 Hz/29.97 Hz. EAV/SAV syn- chronization. EIA-770.3 output levels.	
0x31	0x01	Pixel data valid. 4× oversampling.	
0x33	0x6C	10-bit input enabled.	

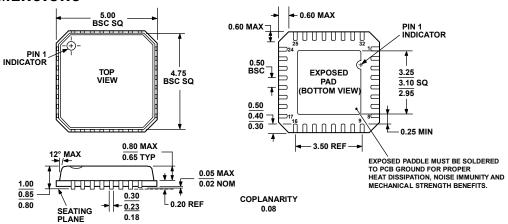
Table 121. 8-Bit 1080i YCrCb In (EAV/SAV), RGB Out

Subaddress	Setting	Description
0x17	0x02	Software reset.
0x00	0x1C	All DACs enabled. PLL enabled (4×).
0x01	0x20	HD-DDR input mode. Luma data clocked on falling edge of CLKIN.
0x02	0x10	RGB output enabled. RGB output sync enabled.
0x30	0x6C	1080i @ 30 Hz/29.97 Hz. EAV/SAV syn- chronization. EIA-770.3 output levels.
0x31	0x01	Pixel data valid. 4× oversampling.

Table 122. 10-Bit 1080i YCrCb In (EAV/SAV), RGB Out

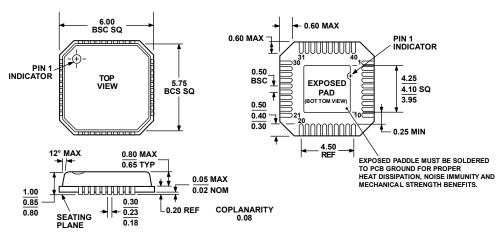
Subaddress	Setting	Description	
0x17	0x02	Software reset.	
0x00	0x1C	All DACs enabled. PLL enabled (4×).	
0x01	0x20	HD-DDR input mode. Luma data clocked on falling edge of CLKIN.	
0x02	0x10	RGB output enabled. RGB output sync enabled.	
0x30	0x6C	1080i @ 30 Hz/29.97 Hz. EAV/SAV synchronization. EIA-770.3 output levels.	
0x31	0x01	Pixel data valid. 4× oversampling.	
0x33	0x6C	10-bit input enabled.	

OUTLINE DIMENSIONS



COMPLIANT TO JEDEC STANDARDS MO-220-VHHD-2

Figure 142. 32-Lead Lead Frame Chip Scale Package [LFCSP_VQ] 5 mm × 5 mm Body, Very Thin Quad (CP-32-2) Dimensions shown in millimeters



COMPLIANT TO JEDEC STANDARDS MO-220-VJJD-2

Figure 143. 40-Lead Frame Chip Scale Package [LFCSP] (CP-40) Dimensions shown in millimeters

ORDERING GUIDE

		Macrovision ¹		
Model	Temperature Range	Anti-Taping	Package Description	Package Option
ADV7390BCPZ ²	-40°C to +85°C	Yes	32-Lead Lead Frame Chip Scale Package [LFCSP_VQ]	CP-32-2
ADV7390BCPZ-REEL ²	-40°C to +85°C	Yes	32-Lead Lead Frame Chip Scale Package [LFCSP_VQ]	CP-32-2
ADV7391BCPZ ²	-40°C to +85°C	No	32-Lead Lead Frame Chip Scale Package [LFCSP_VQ]	CP-32-2
ADV7391BCPZ-REEL ²	-40°C to +85°C	No	32-Lead Lead Frame Chip Scale Package [LFCSP_VQ]	CP-32-2
ADV7392BCPZ ²	-40°C to +85°C	Yes	40-Lead Lead Frame Chip Scale Package [LFCSP_VQ]	CP-40
ADV7392BCPZ-REEL ²	-40°C to +85°C	Yes	40-Lead Lead Frame Chip Scale Package [LFCSP_VQ]	CP-40
ADV7393BCPZ ²	-40°C to +85°C	No	40-Lead Lead Frame Chip Scale Package [LFCSP_VQ]	CP-40
ADV7393BCPZ-REEL ²	-40°C to +85°C	No	40-Lead Lead Frame Chip Scale Package [LFCSP_VQ]	CP-40
EVAL-ADV739xFEZ ^{2, 3}		N/A	ADV739x Evaluation Platform Front-End Board.	
EVAL-ADV7390EBZ ²		Yes	ADV7390 Evaluation Board	
EVAL-ADV7391EBZ ²		No	ADV7391 Evaluation Board	
EVAL-ADV7392EBZ ²		Yes	ADV7392 Evaluation Board	
EVAL-ADV7393EBZ ²		No	ADV7393 Evaluation Board	

¹ Macrovision-enabled ICs require the buyer to be an approved licensee (authorized buyer) of ICs that are able to output Macrovision Rev 7.1.L1-compliant video.

Purchase of licensed I^2C components of Analog Devices or one of its sublicensed Associated Companies conveys a license for the purchaser under the Philips I^2C Patent Rights to use these components in an I^2C system, provided that the system conforms to the I^2C Standard Specification as defined by Philips.



 $^{^{2}}$ Z = Pb-free

³ To be used in conjunction with any one of the ADV793x evaluation boards; this front-end board contains an Analog Devices decoder and Xilinx Spartan-3 FPGA.