TOSHIBA TA8081P

TENTATIVE

TOSHIBA BIPOLAR DIGITAL INTEGRATED CIRCUIT SILICON MONOLITHIC

TA8081P

0.7A MOTOR DRIVER WITH DIAGNOSIS

The TA8081P is a 0.7A motor driver which directly drivers a bidirectional DC motor. Inputs DI1 and DI2 are combined to select one of forward, reverse, stop, and brake modes. Since the inputs are TTL-compatible, this IC can be controlled directly from a CPU or other control system. The IC also has various protective, self-diagnostic, and standby functions.

FEATURES

Bidirectional DC motor driver.

Current capacity : 0.7A (Max.) Low standby current : $100\mu A$ (Max.)

Four operation modes: Forward, reverse, stop, and brake.

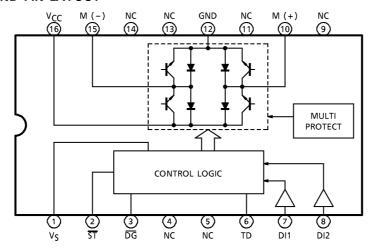
: Thermal shutdown, short-circuit protection, and over-voltage shutdown. Protective functions

Built-in counter electromotive force absorption diodes.

Self-diagnostic output: On short-circuit detection.

Plastic DIP-16pin.

BLOCK DIAGRAM AND PIN LAYOUT



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DIP16-P-300-2.54A

Weight: 1.0g (Typ.)

PIN DESCRIPTION

PIN No.	SYMBOL	DESCRIPTION				
1	Vs	Control power supply pin. This pin is completely isolated from V _{CC} .				
2	ST	When this pin is opened or grounded, the output turns off, thus reducing the current consumption to $100\mu A$ or less. If standby mode is not needed, the pin is connected to V _{CC} .				
3	DG	Self-diagnostic output pin. When the output current becomes 1.5A or more, this pin outputs a protection switching waveform similar to the waveform which would be supplied from M (+)/M (-) pin. If a capacitor is connected to the TD pin, the signal from this pin will become low after a specific delay. The output from the pin is an open-collector output. The delay time is calculated approximately by the following : $TD = 50 \times C_T \text{ (ms)}$ $C_T (\mu F) \cdots \text{The permissible range of } C_T \text{ is from } 0.01 \mu F \text{ to } 2 \mu F.$				
4	NC	Not connected.				
5	NC	Not connected.				
6	TD	Provides a delay for the \overline{DG} output. A capacitor is connected between this pin and GND. When the pin is opened, the \overline{DG} pin supplies a switching output.				
7	DI1	Output status control pin.				
8	DI2	Connects to a PNP-type voltage comparator.				
9	NC	Not connected.				
10	M (+)	Connects to the DC motor. Both the sink and the source have a current capacity of 0.7A. Diodes for absorbing counter electromotive force are contained on the V_{CC} and GND sides.				
11	NC	Not connected.				
12	GND	Grounded				
13	NC	Not connected.				
14	NC	Not connected.				
15	M (-)	Connects to the DC motor together with pin 10 and has the same function as pin 10. This pin is controlled by the inputs from pins 7 and 8.				
16	Vcc	Output section power supply pin. This pin has a function to turn off the output when the applied voltage exceeds 30.0V, thus protecting the IC and the load.				

TRUTH TABLE

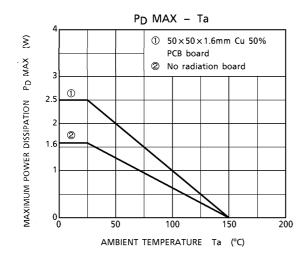
	INPUT		OUT	PUT	OUTPUT MODE	
DI1	DI2	ST	M (+)	M (-)	OUTPUT WIODE	
Н	Н	Н	L	L	Brake	
L	Н	Н	L	Н	Reverse (CCW)	
Н	L	Н	Н	L	Forward (CW)	
L	L	Н	OFF (high impedance)		Stop	
H/L	H/L	L	OFF (high	impedance)	Standby (stop)	

MAXIMUM RATINGS (Ta = 25° C)

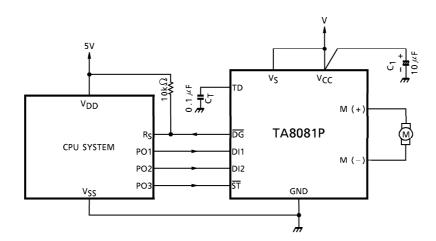
CHARACTERISTIC	SYMBOL	RATING	UNIT	
Power Supply Voltage	Vcc	33	V	
Fower supply voltage	Vcc	60 (1s)		
Input Voltage	V _{IN}	−0.3~V _{CC}	V	
Output Current	IO AVE	0.7	Α	
Power Dissipation	PD	1.6	W	
Operating Temperature	T _{opr}	-40~110	°C	
Storage Temperature	T _{stg}	- 55∼150	°C	
Lead Temperature-time	T _{sol}	260 (10s)	°C	

ELECTRICAL CHARACTERISTICS ($V_{CC} = 6 \sim 16V$, $Ta = -40 \sim 110^{\circ}C$)

CHARACTERISTIC	SYMBOL	PIN	TEST CIR- CUIT	TEST CONDITION	MIN.	TYP.	MAX.	UNIT	
	I _{S1}		—	Stop	_	5	10		
Current Consumption 1	I _{S2}	V _S	_	Forward / Reverse	_	10	20	mA	
	ls3		_	Brake	_	10	20		
	lCC1	Vcc	_	Stop	_	1.0	2.0	mA	
Current Consumption 2	l _{CC2}		_	Forward / Reverse	_	15	30		
	I _{CC3}		_	Brake	_	1.0	2.0		
	V _{IL}	DI4 / DI2	_	_	_	_	0.8		
Innut Valtage	VIH	DI1/DI2	_	_	2.0	_	_		
Input Voltage	V _{IL}	ST	_	_	_	_	0.5	V	
	V _{IH}	31	_	_	2.0	_	_		
	Ι _Ι L	DI1 / DI2	_	V _{IN} = 0.4V	- 10	_	10	μΑ	
Innut Current	lН		_	$V_{IN} = V_{CC}$	– 10	_	10		
Input Current	I _{IL}	- ST	_	V _{IN} = 0.4V	_	_	20		
	lН		_	V _{IN} = V _{CC}	_	_	2.0	mA	
Output Saturation	V _{sat}	M (+)/	_	$I_{O} = 0.5A$, $T_{C} = 25^{\circ}C$	_	1.7	2.4	V	
Voltage	(total)	M (-)	_	$I_{O} = 0.5A$, $T_{C} = 110^{\circ}C$	_	1.6	2.3	\ \ \	
Output Leakage Current	^I LEAK∙U	M (+)/	_	V _{OUT} = 0V		_	- 10		
Output Leakage Current	^I LEAK∙L	M (-)	_	V _{OUT} = V _{CC}		_	10	μ A	
Output Voltage	V _{OL}	- DG	_	$I_{OL} = 3mA$	_	_	0.5	<	
Output Leakage Current	ILEAK		_	V _{OUT} = V _{CC}		_	10	μ A	
Diode Forward Voltage	V _F .U	M (+)/	_	I _F = 0.5A	_	1.5	_	V	
Didde Forward Voltage	V _F .L	M (-)			_	1.5	_		
Over-current Detection	ISD	_	_	_	1.0	1.5	2.0	Α	
Shutdown Temperature	T_{SD}	_	_	_		150	_	°C	
Over-voltage Detection	V_{SD}	_	_	_	27	30	33	V	
Standby Current	Is	V _{CC} + V _S		<u>ST</u> = 0V			100	μΑ	
Transfer Delay Time	t _{pLH}	_	_	_	_	1	10	,,,	
Transier Delay Tillie	t _{pHL}	_	_	_	_	1	10	μ s	



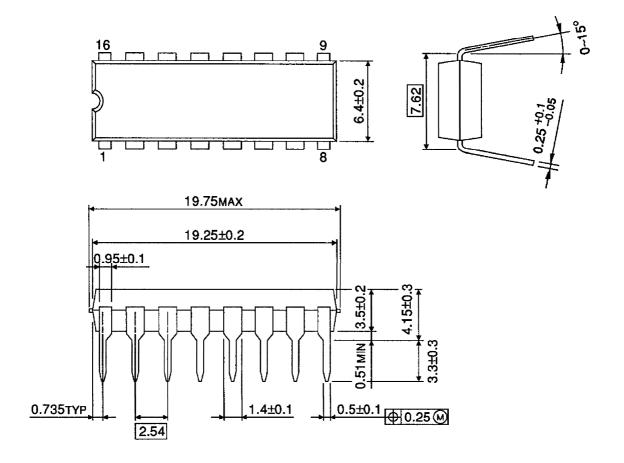
EXAMPLE OF APPLICATION CIRCUIT



Cautions for Wiring: C₁ is for absorbing disturbance, noise, etc. Connect is as close to the IC as possible.

OUTLINE DRAWING DIP16-P-300-2.54A

Unit: mm



Weight: 1.0g (Typ.)