

AN420 Application note

Expanding A/D resolution of the ST6 A/D converter

1 Introduction

Occasionally the analog signal provided by external sensors require an Analog to Digital conversion with a resolution of greater than 8 bits. In order to extract the full information for subsequent data processing within the microcontroller a higher resolution Analog to Digital is thus required.

The solution described in this note enables this higher resolution with the on-chip 8-bit A/D converter of the ST62, using only an additional Operational Amplifier (OpAmp) and a few resistors

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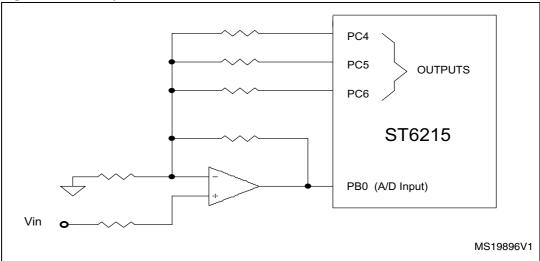
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2 Overview

The technique implemented is that of the Algebraic Adder, a full discussion of the principle of operation is included in this note.

A practical example of the external components used is shown in the following figure:

Figure 1. Example circuit



The resistances are selected by the ST62 I/O pins depending on the analog input voltage.

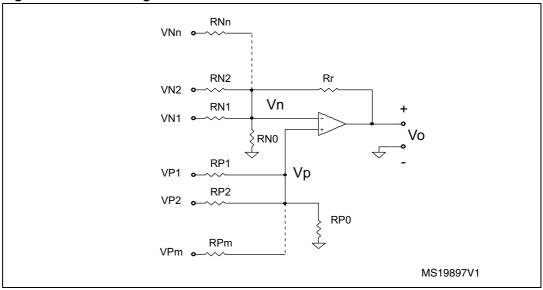
The selection programmed modifies the output voltage of the OpAmp in such a way that the following A/D conversion is always made with the maximum input range of the converter.

This selection is made by software, therefore the total conversion time is increased versus a normal 8-Bit conversion, however the precision is increased and the input voltage range can be enlarged.

3 Principle of operation of an algebraic adder

Figure 2 represents the generic algebraic adder.

Figure 2. Generic algebraic adder



The circuit generates an output voltage equal to: i

$$V_0 = \sum_{i=1}^{m} K_i \times V_{P_i} - \sum_{i=1}^{n} K_i \times V_{N_j}$$
(1)

To minimize the effects of the input polarizing currents, the total resistances seen from the two inputs of the OpAmp should be the same. Therefore:

$$\frac{1}{R_{r}} + \frac{1}{R_{N_{0}}} + \sum_{j=1}^{n} \frac{1}{R_{N_{j}}} = \frac{1}{R_{P_{0}}} + \sum_{i=1}^{m} \frac{1}{R_{P_{i}}} = \frac{1}{R_{T}}$$
(2)

The two resistances RP0 and RN0 are needed to satisfy the above relation. In general, only one of them will be needed.

To analyze the circuit, let us calculate the input voltages:

$$\begin{array}{c}
m \\
\sum\limits_{i=1}^{m}G_{P_{i}}\times V_{P_{i}} \\
V_{P} = \frac{i=1}{m} \\
G_{P_{0}} + \sum\limits_{i=1}^{m}G_{P_{i}}
\end{array}$$
where

$$V_{n} = \frac{V_{0} \times G_{R} + \sum_{j=1}^{n} G_{N_{j}}}{G_{N_{0}}}$$
(4)

Relation (2) becomes:

$$G_{N_0} + G_R + \sum_{j=1}^{n} G_{N_j} = G_{P_0} + \sum_{j=1}^{m} G_{P_j} = G_T$$
 (5)

From 3, 4 and 5 we get:

$$V_0 = -\sum_{i=1}^{n} V_{N_i} \times \frac{R_r}{R_{N_i}} + \sum_{i=1}^{m} V_{P_i} \times \frac{R_r}{R_{P_i}}$$
 (6)

Relation (6) is the relevant formula to be used. It also explains the name given to this circuit, since the output voltage is the 'algebraic sum' of the input voltages. To design the actual circuit, you chose one value of Rr (arbitrarily). The other resistances are then determined by the desired coefficients:

$$K_i = \frac{R_r}{R_{P_i}} \qquad K_j = \frac{R_r}{R_{N_i}}$$
 (7)

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Finally, the values for $\ensuremath{R_{\text{N0}}}$ and $\ensuremath{R_{\text{P0}}}$ are chosen, based on (2).

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4 Example

Let us assume we have a voltage swing of 10 volts (0 to 10) that we want to convert with a 10-bit resolution. And let us assume we have a set of voltage sources VNj that we can switch between 0 to 5 volts under software control, and each one independently from the other.

Let us also assume we can 'cut' the 10 volt swing in 4 'pieces' of 2.5 volts each, and that every 'piece' can be converted with 8-bit resolution. The overall resolution will therefore be:

$$2^8$$
 (ST6 A/D resolution) * 2^2 (# of 'pieces') = 2^{10}

Let us call V_{in} the actual value of the source to be converted. For instance, if V_{in} ϵ [10, 7,5] volts, we could supply the ST6 A/D with the voltage:

$$(V_{in}-7.5volt)x2 => \epsilon[0,5]volt$$

or, for (10,7.5) volts:

$$(V_{in}-1.5xV_{N1})x2 = 2xV_{in}-3xV_{N1}$$

where V_{N1} is one of the V_{Nj} sources, either 0 or 5 volts. In similar fashion, for the other intervals, we could obtain:

(7.5, 5) volts

$$(V_{in}-V_{N2})x2 = 2xV_{in}-2xV_{N2}$$

(5, 2.5) volts

$$(V_{in}-0.5xV_{N3})x2 = 2xV_{in}-V_{N3}$$

(2.5, 0) volts

$$(V_{in}-0xV_{N4})x2 = 2xV_{in}$$

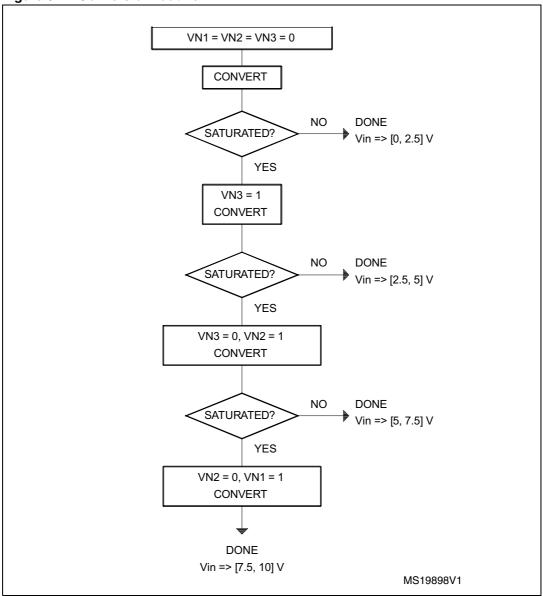
So, relation (6) becomes:

$$V_0 = 2xV_{in}-3xV_{N1}-2xV_{N2}-V_{N3}$$
 where $V_{in} = V_{P1}$

The software driving the conversion will therefore verify if, given a certain status of the V_{Nj} voltages, the conversion is far from being saturated. If so, another try will be performed with a different status of the V_{Ni} voltages. Figure 3 gives the flow chart of such software.

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Figure 3. Conversion routine



The actual circuit values are calculated as follows. With arbitrarily chosen Rr equal to 10 K Ω , the other resistor values are given by:

$$\frac{R_r}{R_{P1}} = 2 \Rightarrow R_{P1} = 5000\Omega$$

$$\frac{R_r}{R_{N1}} = 3 \Rightarrow R_{N1} = 3333\Omega$$

$$\frac{R_r}{R_{N2}} = 2 \Rightarrow R_{N2} = 5000\Omega$$

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$$\frac{R_r}{R_{N3}} = 1 \Rightarrow R_{N3} = 10\Omega$$

To satisfy relation (2), we obtain the following values, as indicated in Figure 4.

$$\frac{1}{R_r} + \frac{1}{R_{N0}} + \frac{1}{R_{N1}} + \frac{1}{R_{N2}} + \frac{1}{R_{N3}} + \frac{1}{R_{N0}} + 0.0007$$

$$\frac{1}{R_{P0}} + \frac{1}{R_{P1}} = \frac{1}{R_{P0}} + 0.0002$$

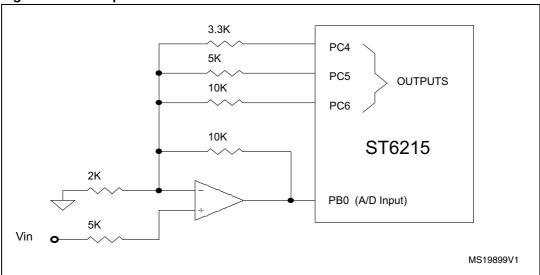
$$\frac{1}{R_{N0}} + 0.0007 = \frac{1}{R_{P0}} + 0.0002$$

Assuming
$$\frac{R}{P0} = \infty \Rightarrow R_{N0} = 2K\Omega$$

5 Application example

An example ST62 software program follows on the next pages. It executes the program flow of *Figure 3* in the application circuit of *Figure 4*.

Figure 4. Example circuit



The ST6215 pin allocation is arbitrary. The three outputs can drive other identical circuits, when more the one 10-bit A/D channel is needed. Also, a different number of 'pieces' can be used to achieve a different resolution.

```
;* File name: HIRES_AD.ASM
; * ALGEBRAIC ADDER AND ST6 A/D CONVERTERS - Application note software
;* This software is an example on how to increase the ST6 converter
; * resolution. Please refer to the application note for further
; * explanations.
; ^{\star} Allocation of pins: PC4, PC5 and PC6 are, respectively, voltage sources
;* VN1, VN2 and VN3. PB0 is an A/D input
.input "6215_reg.asm" ;ST6215 standard definitions file
                        ; PC4 bit select
VN1 .equ 4
                        ;PC5 bit select
VN2 .equ 5
VN3 .equ 6
                        ; PC6 bit select
drcs .def 0bfh,0ffh,0ffh
                        ;shadow register for Data Register C
```

```
Hres .def 0bdh,0ffh,0ffh
                        ;MS 2 bits of conversion result, and
                        ;conversion flag
conv_f .equ 7;the MSB of Hres is the high resolution
                        ; end of conversion flag
c1 .equ 6
                         ; conversion step flags
c2 .equ 5
c3 .equ 4
c4 .equ 3
                        ;using Hres
Lres .def Obeh,Offh,Offh ;LSB of conversion result
;register W is used to save the accumulator contents
; in standard interrupt routines
; one module only. Do not use this
        .org 880h
                        ;assembly directive if you organize
                        ;your software in linkable modules
init ldi drb,1
        ldi orb,1 ;PBO is analog input
        ldi ddrc,070h ;PC4..6 are open drain outputs
        ldi orc,070h ;PC4..6 are push-pull outputs now
        ldi drcs,0 ;assume PC7 is input with pull-up,
                        ;no interrupt
        ldi ior,10h ;enable interrupts
        ldi Hres, 0
        reti ;initialize interrupt machine
                         ; this is an endless loop converting
conv
                        ;PBO input with 10-bit resolution
                        ; the first time here after reset,
                        ; VN1=VN2=VN3=0
        set conv_f, Hres
        set c1, Hres
        set 5,adcr ;start high resolution conversion
        jrs conv_f,Hres,$
        nop ;here the high resolution result is
                        ;available in Hres-Lres
        jp conv
adcint
        ld w,a ; save accumulator
        ld a,adr ;in accumulator conversion result
        jrs c1, Hres, c1conv
```

```
jrs c2, Hres, c2conv
          jrs c3, Hres, c3conv
         ldi Hres,3
c4conv
         ld Lres,a
         ld a,drcs
          res VN1,a
          ld drcs,a
          ld drc,a
                           ; VN1=VN2=VN3=0
          jp convout
c1conv
         pi a,0ffh
                           jrnz c1c1
1r Hres
         ld Lres,a
convout
        d a,w
          reti
c1c1
         ld a,drcs
         set VN3,a
          ld drcs,a
          ld drc,a
                           ;VN1=VN2=0, VN3=1
          set 5,adcr
                            ;start conversion
          res c1, Hres
          set c2,Hres
          jp convout
                           ;exit interrupt
c2conv
         cpi a,0ffh
          jrnz c2c1
         ldi Hres,1
          ld Lres,a
          jp convout
c2c1
         ld a,drcs
         res VN3,a
          set VN2,a
          ld drcs,a
          ld drc,a
                            ; VN1=VN3=0, VN2=1
          set 5,adcr
                            ;start conversion
          res c2,Hres
          set c3, Hres
          jp convout
                           ;exit interrupt
         cpi a,0ffh
c3conv
          jrnz c3c1
```

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```
ldi Hres,2
         ld Lres,a
         jp convout
c3c1
         ld a,drcs
         res VN2,a
         set VN1,a
         ld drcs,a
         ld drc,a
                           ; VN2=VN3=0, VN1=1
         set 5,adcr
                           ;start conversion
         res c3,Hres
         set c4,Hres
         jp convout
                          ;exit interrupt
         .org 0ff0h
         jp adcint
                          ;A/D interrupt vector
         .org Offeh
         jp init ;reset vector
```

.end

AN420 Revision history

6 Revision history

Table 1. Document revision history

Date	Revision	Changes
21-Dec-1992	1	Initial release.
02-Nov-2011	2	Updated format and company logo.

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